

ESM-7750 72 x 72 DIN SIZE Universal Input PID Process Controller with Smart I/O Module System

- 4 digits process (PV) and 4 digits process set (SV) display
- Universal process input (TC, RTD, mV____, V____, mA____)
- Optional secondary sensor input
- Dual or multi point calibration for ____Voltage / Current input
- Configurable ON/OFF, P, PI, PD and PID control forms
- Adaptation of PID coefficients to the system with Auto-tune and Self-tune
- Manual/Automatic mode selection for control outputs
- Bumpless transfer
- Smart I/O module system
- Programmable heating, cooling and alarm functions for control outputs
- Motorized valve control function
- 8 steps profile control (Ramp & Soak) function and start-holdstop by using logic input module
- Remote set point function by using analogue input modules
- Retransmission of process value or process control by using 0/4...20 mA=== Current Output Module
- Detection of heater failure by using 0...5 A ← CT input module
- Hardware configuration by using input/output modules
- RS-232 (standard) or RS-485 (optional) serial communication with Modbus RTU protocol



ABOUT INSTRUCTION MANUAL

Instruction manual of ESM-7750 Process Controller consists of two main sections. Explanation of these sections are below. Also, there are other sections which include order information and technical specifications of the device. All titles and page numbers in instruction manual are in "**CONTENTS**" section. User can reach to any title with section number.

Installation:

In this section, physical dimensions of the device, panel mounting, electrical wiring, module mounting to the device, physical and electrical installation of the device to the system are explained.

Operation and Parameters:

In this section, user interface of the device, how to access to the parameters, description of the parameters are explained.

Also in these sections, there are warnings to prevent serious injury while doing the physical and electrical mounting or using the device.

Explanation of the symbols which are used in these sections are given below.



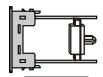
This symbol is used for safety warnings. User must pay attention to these warnings.



This symbol is used to determine the dangerous situations as a result of an electric shock. User must pay attention to these warnings definitely.



This symbol is used to determine the important notes about functions and usage of the device.



In parameters section, for making relevant parameters to be active, determined module must be installed to Module-1 or Module-2 socket.

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EU DECLARATION OF CONFORMITY

Manufacturer Company Name: Emko Elektronik A.S.

Manufacturer Company Address: DOSAB, Karanfil Sokak, No:6, 16369 Bursa, Turkiye

The manufacturer hereby declares that the product conforms to the following standards and conditions.

Product Name : Process Controller

Model Number : ESM-7750

Type Number : ESM-7750

Product Category

laboratory use

: Electrical equipment for measurement, control and

Conforms to the following directives:

2006 / 95 / EC The Low Voltage Directive

2004 / 108 / EC The Electromagnetic Compatibility Directive

has been designed and manufactured to the following specifications:

EN 61000-6-4:2007 EMC Generic Emission Standard for the Industrial Environments

EN 61000-6-2:2005 EMC Generic Immunity Standard for the Industrial Environments

EN 61010-1:2001 Safety Requirements for electrical equipment for measurement, control

And laboratory use

When and Where Issued Authorized Signature

16th October 2009 Name : Serpil YAKIN

Bursa-TURKEY Position : Quality Manager

1.Preface

ESM series process controllers are designed for measuring and controlling temperature and any process value. They can be used in many applications with their universal process input, multifunction control outputs, selectable alarm functions, serial communication unit and input/output modules.

Some application fields and applications which they are used are below:

<u>Application Fields</u> <u>Applications</u>

Glass Motorized valve control

Plastic Profile Control

Petro-Chemistry PID Process Control Textile Heater Failure detection

Automative

Machine production industries

1.1 General Specifications **Standard** ESM-7750 **Universal Supply Input** 100-240 V∼, 50/60Hz **Power Supply** Low Voltage (optional) Input Supply Input 24V~50/60Hz ,24V=== Universal Process Input Start and Stop function for **Process Input** RAMP/SOAK TC,RTD,___Voltage/Current Selection of Manual / **Logic Input Module** Automatic operation for process control output Analogue Input Modules - 2nd Sensor Input TC, PT-100, ____Voltage/ - Remote Set Input Current - Multi point calibration for ---Voltage/Current input **~CT Input Module** - Detection of heater failure Relay, SSR Driver. Digital (Transistor). Current Output Module **Optional** Input/Output Module-1 **Control Output Heating-Cooling Function Alarm Output** ON/OFF, PID Operation **Optional Re-Transmission Output** Auto-Tune, Self-Tune Input/Output Module-2 **Automatic/Manual Operation Standard Control Output** Output-3(Relay Output) **Alarm Output Standard RS-232** Serial Communication Baud Rate from 1200 to 19200 **Optional Modbus RTU Protocol** RS-485

1.2 Ordering Information

ESM-7750(72x72 DIN SIZE) A BC D E / FG HI / U V W Z									
Α	A Supply Voltage								
1	1 100-240V∼ (-15%;+10%) 50/60Hz								
2 24 V~ (-15%;+10%) 50/60Hz 24V== (-15%;+10%)									
9 Customer (Maximum 240V~ (-15%;+10%))50/60Hz									
BC Input Type Scale									

20	Configurable (Table-1)	Table-1	
D	Serial Communication		Product Code
0	None		-
1	RS-232	•	EMC-700
2	RS-485		EMC-710
F	Output-1		

	Output-1
1	Relay Output (5A@ 250V~ at resistive load)

FG	Module-1	Product Code
00	None	-
01	Relay Output Module	EMO-700
02	SSR Driver Output Module	EMO-710
03	Digital (Transistor) Output Module	EMO-720
04	Current Output Module (0/420 mA===)	EMO-730
07	Digital Input Module	EMI-700
08	0/420 mA===Current Input Module	EMI-710
09	05A ∼CT Input Module	EMI-720
10	TC or 050mV=== Input Module	EMI-730
11	PT-100 Input Module	EMI-740
12	010 V=== Input Module	EMI-750

Н	Module-2	Product Code
00	None	-
01	Relay Output Module	EMO-700
02	SSR Driver Output Module	EMO-710
03	Digital (Transistor) Output Module	EMO-720
04	Current Output Module (0/420 mA===)	EMO-730
07	Digital Input Module	EMI-700
08	0/420 mA=== Current Input Module	EMI-710
09	05A ∼CT Input Module	EMI-720
10	TC or 050mV=== Input Module	EMI-730
11	PT-100 Input Module	EMI-740
12	010 V== Input Module	EMI-750

Table-1

BC	Input Type(TC)	Scale(°C)	Scale(°F)
21	L ,Fe Const DIN43710	-100°C,850°C	-148°F ,1562°F
22	L ,Fe Const DIN43710	-100.0°C,850.0°C	-148.0°F,999.9°F
23	J ,Fe CuNi IEC584.1(ITS90)	-200°C,900°C	-328°F,1652°F
24	J ,Fe CuNi IEC584.1(ITS90)	-199.9°C,900.0°C	-199.9°F,999.9°F
25	K ,NiCr Ni IEC584.1(ITS90)	-200°C,1300°C	-328°F,2372°F
26	K ,NiCr Ni IEC584.1(ITS90)	-199.9°C,999.9°C	-199.9°F,999.9°F
27	R ,Pt13%Rh Pt IEC584.1(ITS90)	0°C,1700°C	32°F,3092°F
28	R ,Pt13%Rh Pt IEC584.1(ITS90)	0.0°C,999.9°C	32.0°F,999.9°F
27	S ,Pt10%Rh Pt IEC584.1(ITS90)	0°C,1700°C	32°F,3092°F
28	S ,Pt10%Rh Pt IEC584.1(ITS90)	0.0°C,999.9°C	32.0°F,999.9°F
29	T ,Cu CuNi IEC584.1(ITS90)	-200°C,400°C	-328°F,752°F
30	T ,Cu CuNi IEC584.1(ITS90)	-199.9°C,400.0°C	-199.9°F,752.0°F
31	B ,Pt30%Rh Pt6%Rh IEC584.1(ITS90)	44°C,1800°C	111°F,3272°F
32	B ,Pt30%Rh Pt6%Rh IEC584.1(ITS90)	44.0°C,999.9°C	111.0°F,999.9°F
33	E ,NiCr CuNi IEC584.1(ITS90)	-150°C,700°C	-238°F,1292°F
34	E ,NiCr CuNi IEC584.1(ITS90)	-150.0°C,700.0°C	-199.9°F,999.9°F
35	N ,Nicrosil Nisil IEC584.1(ITS90)	-200°C,1300°C	-328°F,2372°F
36	N ,Nicrosil Nisil IEC584.1(ITS90)	-199.9°C,999.9°C	-199.9°F,999.9°F
37	C, (ITS90)	0°C,2300°C	32°F,3261°F
38	C, (ITS90)	0.0°C,999.9°C	32.0°F,999.9°F

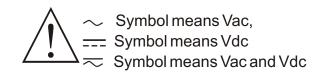
BC	Input Type(RTD)	Scale(*C)	Scale('F)
39	PT 100 , IEC751(ITS90)	-200°C,650°C	-328°F,1202°F
40	PT 100 , IEC751(ITS90)	-199.9°C,650.0°C	-199.9°F,999.9°F
ВС	Input Type (=== Voltage and C	Current) So	cale

BC	Input Type (Voltage and Current)	Scale	
41	050 mV 	-1999	9999
42	05 V 	-1999	9999
43	010 V 	-1999	9999
44	020 mA 	-1999	9999
45	420 mA 	-1999	9999

All order information of ESM-7750 are given on the table at left. User may form appropriate device configuration from information and codes that at the table and convert it to the ordering codes.

Firstly, supply voltage then input/output modules and other specifications must be determined. Please fill the order code blanks according to your needs.

Please contact us, if your needs are out of the standards.



1.3 Warranty

EMKO Elektronik warrants that the equipment delivered is free from defects in material and workmanship. This warranty is provided for a period of two years. The warranty period starts from the delivery date. This warranty is in force if duty and responsibilities which are determined in warranty document and instruction manual performs by the customer completely.

1.4 Maintenance

Repairs should only be performed by trained and specialized personnel. Cut power to the device before accessing internal parts.

Do not clean the case with hydrocarbon-based solvents (Petrol, Trichlorethylene etc.). Use of these solvents can reduce the mechanical reliability of the device. Use a cloth dampened in ethyl alcohol or water to clean the external plastic case.

2.Installation



Before beginning installation of this product, please read the instruction manual and warnings below carefully.

In package,

- One piece unit
- Two pieces mounting clamps
- One piece instruction manual

A visual inspection of this product for possible damage occured during shipment is recommended before installation. It is your responsibility to ensure that qualified mechanical and electrical technicians install this product.

If there is danger of serious accident resulting from a failure or defect in this unit, power off the system and separate the electrical connection of the device from the system.

The unit is normally supplied without a power switch or a fuse. Use power switch and fuse as required.

Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.

Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

Never attempt to disassemble, modify or repair this unit. Tampering with the unit may results in malfunction, electric shock or fire.

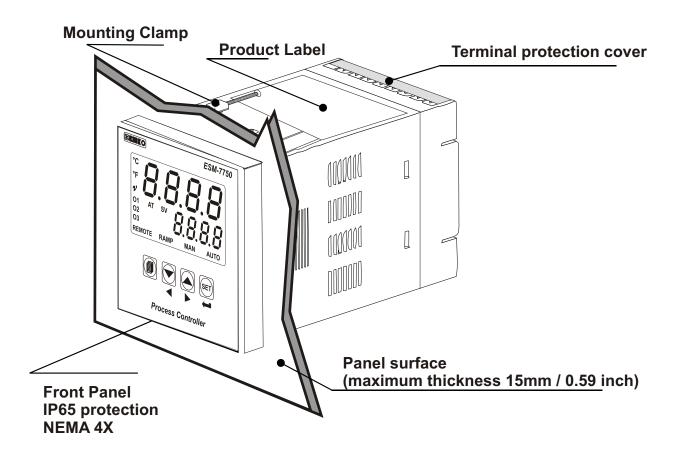
Do not use the unit in combustible or explosive gaseous atmospheres.

During the equipment is putted in hole on the metal panel while mechanical installation some metal burrs can cause injury on hands, you must be careful.

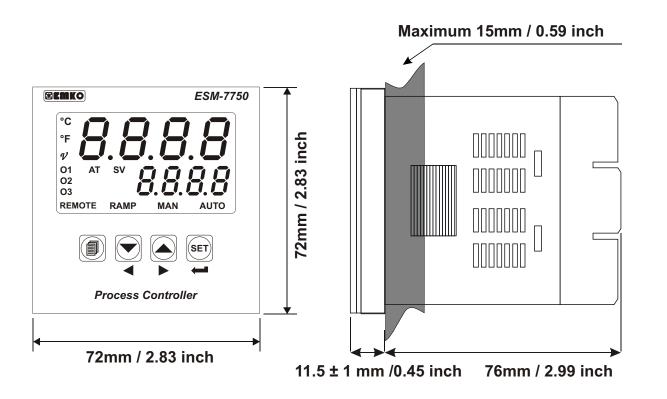
Montage of the product on a system must be done with it's fixing clamps. Do not do the montage of the device with inappropriate fixing clamp. Be sure that device will not fall while doing the montage.

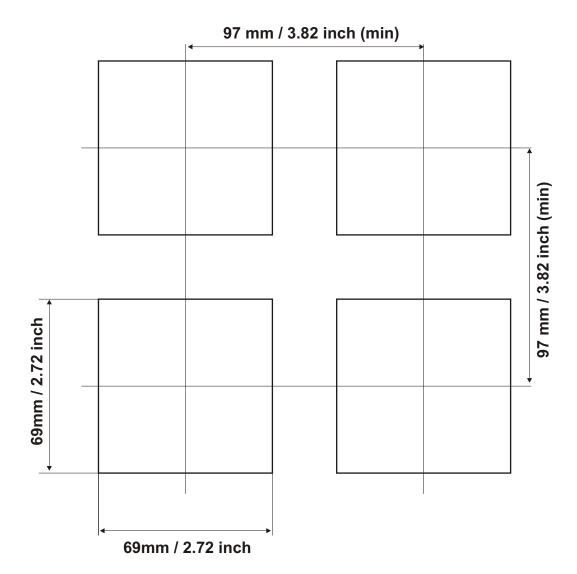
It is your responsibility if this equipment is used in a manner not specified in this instruction manual.

2.1 General Description



2.2 Dimensions





2.4 Environmental Ratings

Operating Conditions



Operating Temperature : 0 to 50 °C



Max. Operating Humidity: 90% Rh (non-condensing)

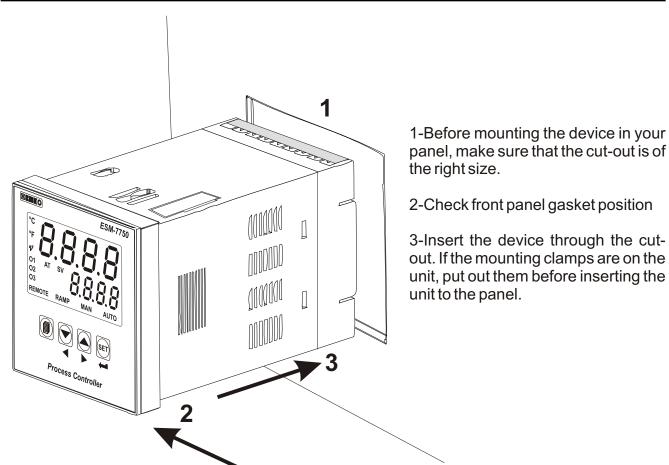


Altitude : Up to 2000m.



Forbidden Conditions:
Corrosive atmosphere
Explosive atmosphere
Home applications (The unit is only for industrial applications)

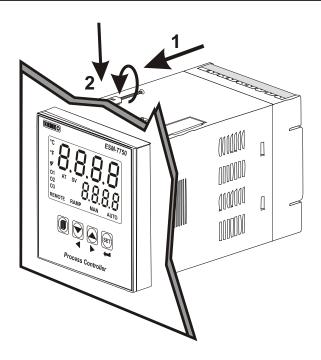
2.5 Panel Mounting





During installation into a metal panel, care should be taken to avoid injury from metal burrs which might be present. The equipment can loosen from vibration and become dislodged if installation parts are not properly tightened. These precautions for the safety of the person who does the panel mounting.

2.6 Installation Fixing Clamp



The unit is designed for panel mounting.

- 1-Insert the unit in the panel cut-out from the front side.
- 2- Insert the mounting clamps to the holes that located top and bottom sides of device and screw up the fixing screws until the unit completely immobile within the panel

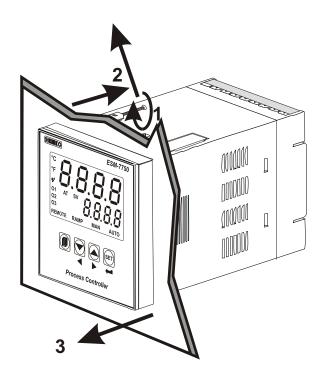


Montage of the unit to a system must be done with it's own fixing clamps. Do not do the montage of the device with inappropriate fixing clamps. Be sure that device will not fall while doing the montage.

2.7 Removing from the Panel



Before starting to remove the unit from panel, power off the unit and the related system.



- 1-Loosen the screws.
- 2-Pull mounting clamps from top and bottom fixing sockets.
- 3-Pull the unit through the front side of the panel

3. Electrical Wirings



You must ensure that the device is correctly configured for your application. Incorrect configuration could result in damage to the process being controlled, and/or personal injury. It is your responsibility, as the installer, to ensure that the configuration is correct.

Device parameters has factory default values. These parameters must be set according to the system's needs.



Only qualified personnel and technicians should work on this equipment. This equipment contains internal circuits with voltage dangerous to human life. There is severe danger for human life in the case of unauthorized intervention.

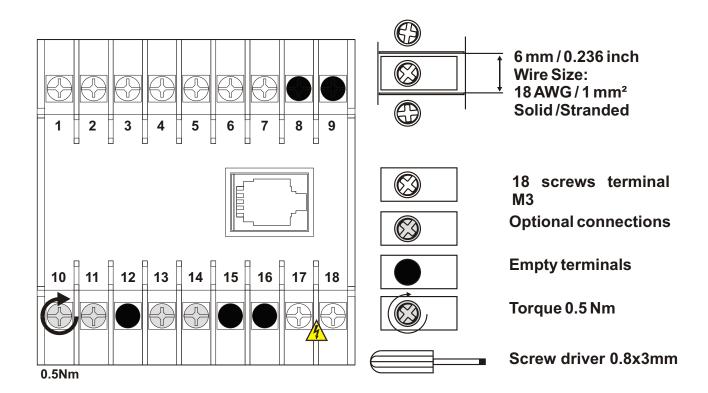


Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.



Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

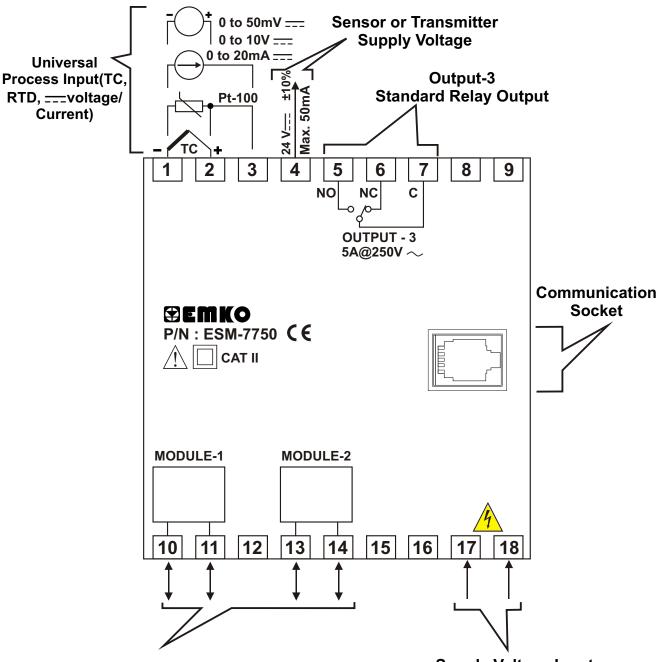
3.1 Terminal Layout and Connection Instructions



3.2 Electrical Wiring Diagram



Electrical wiring of the device must be the same as 'Electrical Wiring Diagram' below to prevent damage to the process being controlled and personnel injury.



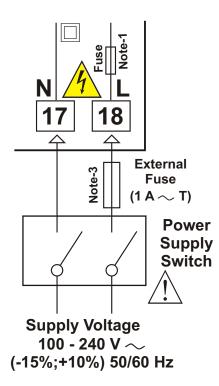
Optional Input/Output Module Terminals Relay, SSR Driver, Digital or Current Output Module Digital, Analogue and CT Input Modules Supply Voltage Input 100-240V~(-15%;+10%) 50/60Hz - 6VA 24 V~(-15%;+10%) 50/60Hz - 6VA 24V==-(-15%;+10%) - 6W (It must be determined in order)



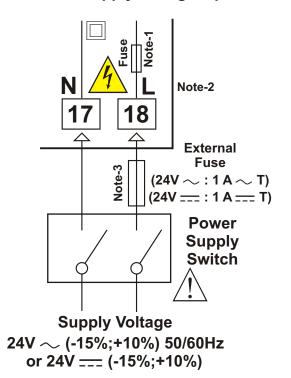
Process input, Analogue Module Inputs (EMI-710, EMI-730, EMI-740, EMI-750) and CT Module Input (EMI-720) are in CAT II class.

3.3 Supply Voltage Input Connection of the Devices

Connection of Universal Supply Voltage Input



Connection of Low Voltage 24 V Supply Voltage Input



Note-1: There is an internal 33R fusible flameproof resistor in 100-240 V \sim 50/60Hz There is an internal 4R7 fusible flameproof resistor in 24V \sim 50/60Hz, 24V=

Note-2: "L" is (+), "N" is (-) for 24V ___ Supply Voltage

Note-3: External Fuse is recommended.



Make sure that the power supply voltage is the same indicated on the instrument.

Switch on the power supply only after that all the electrical connections have been completed.

Supply voltage range must be determined in order. While installing the unit, supply voltage range must be controlled and appropriate supply voltage must be applied to the unit. Controlling prevents damages in unit and system and possible accidents as a result of incorrect supply voltage.



There is no power supply switch on the device. So a power supply switch must be added to the supply voltage input. In accordance with the safety regulations, the power supply switch shall bring the identification of the relevant instrument. Power supply switch shall be easily accessible by the user.

Power switch must be two poled for seperating phase and neutral. On/Off condition of power switch is very important in electrical connection. On/Off condition of power switch must be signed for preventing the wrong connection.

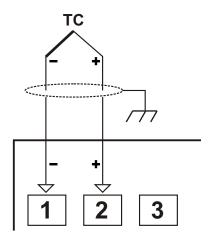
If an external fuse is used, it must be on phase connection in ∼supply input.

If an external fuse is used, it must be on (+) line connection in = supply input.



The instrument is protected with an internal fuse (Please refer to Note1 for information). In case of failure it is suggested to return the instrument to the manufacturer for repair.

3.4.1 TC (Thermocouple) Connection



Connect the wires with the polarity as shown in the figure left.

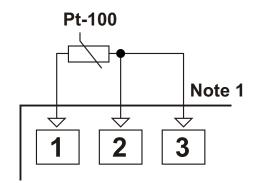
(i)

Always use compensation wire corresponding to the thermocouple used. If present, the shield must be connected to a proper ground.

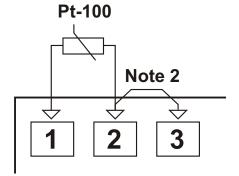
(i)

Input resistance is greater than 10M

3.4.2 RTD Connection



3-wire Pt-100 connection (with line compensation) (Max. Line impedance is 10)



2-wire Pt-100 connection (without line compensation)

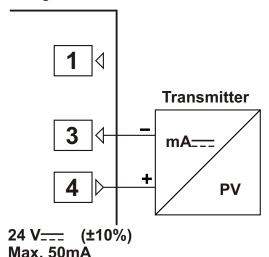
- **Note 1:** In 3-wire system, use always cables of the same diameter (min 1mm²) Always use wires of the same gauge and type whether a 2-wire or 3-wire system.
- Note 2: Install a jumper between terminals 2 and 3 when using a 2-wire RTD.
- **Note 3 :** If the distance is longer than 10 meters, use 3-wire system

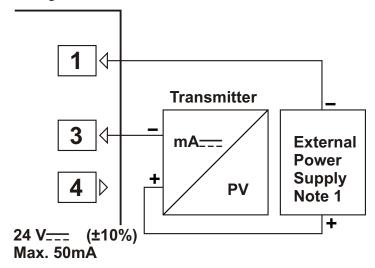
Input resistance is greater than 10M

3.4.3 Process Input Connection of Serial Transmitters with Current Output (Loop Powered)

Transmitter connection by using supply voltage on the device

Transmitter connection by using external supply voltage source.





Note 1: External power supply must be selected according to supply voltage range and required current for transmitter.

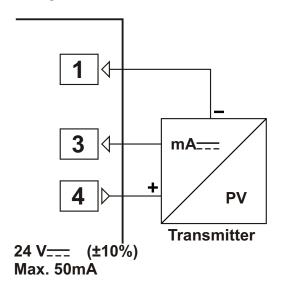


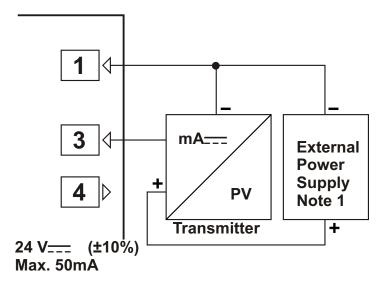
Input Resistance is 2R7

3.4.4 Process Input Connection of 3-Wire Transmitters with Current Output

Transmitter connection by using supply voltage on the device

Transmitter connection by using external supply voltage source.





Note 1: External power supply must be selected according to supply voltage range and required current for transmitter.

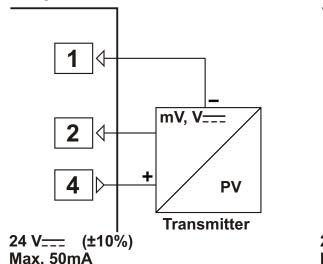


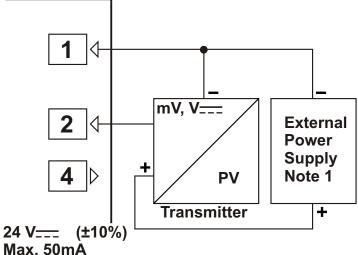
Input Resistance is 2R7 .

3.4.5 Connection of Transmitters with Voltage Output to Process Input

Transmitter connection by using supply voltage on the device

Transmitter connection by using external supply voltage source.



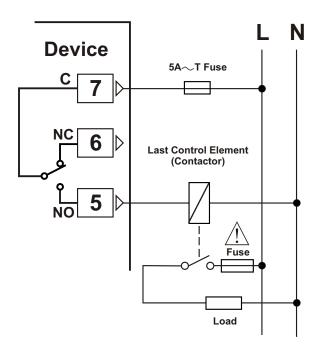


Note 1: External power supply must be selected according to supply voltage range and required current for transmitter.



Input resistance is greater than 10M for 0...50mV === Input resistance is 43K for 0...10V ===

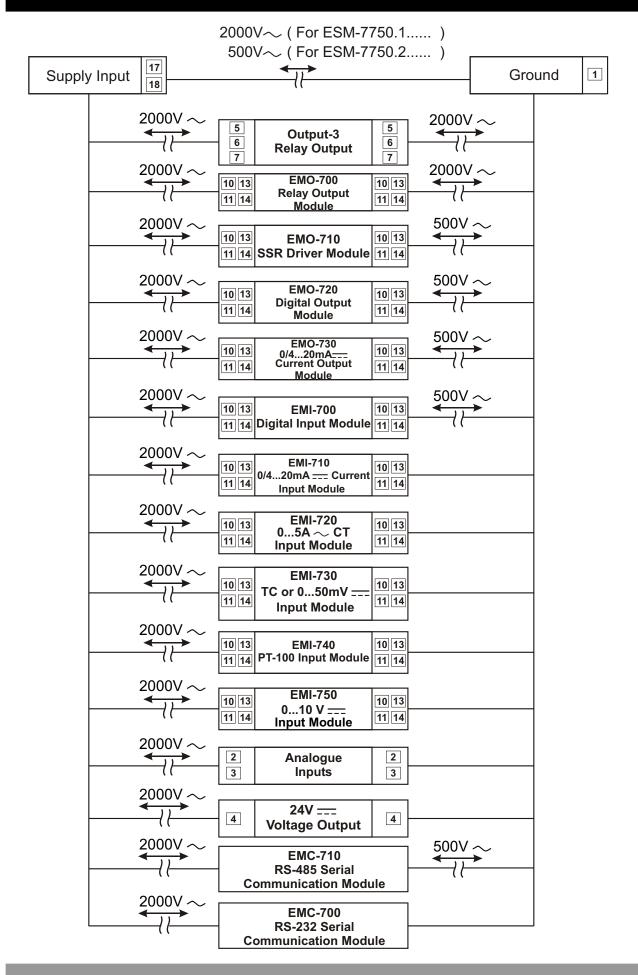
3.5 Relay Output Connection





Fuses must be selected according to the application.

3.6 Galvanic Isolation Test Values of ESM-7750 Process Controller and Input/Output Modules

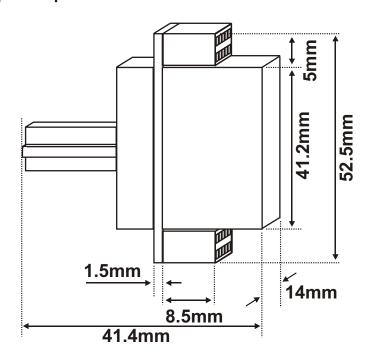


4. Definitions and Specifications of Modules

ESM-7750 process controller is a modular product which is designed to operate with additional analogue and digital input/output units which user may need.

Two input/output modules can be plugged in the device by the user. User may configure the product for different applications according to the system requirements with the input/output modules which are described in this section.

Dimensions of Input/Output Modules



4.1 Input Modules

4.1.1 EMI-700 Digital Input Module

EMI-700 Digital input module can be installed to Module-1 or Module-2 socket for using the digital input functions.

Specifications of EMI-700 Digital Input Module

Input Type :Normally Open Contact, NPN, PNP, Voltage Input (2 Volt and below 2 Volt

is Logic "0", 4 Volt and above 4 Volt is Logic "1". Maximum 30V can be applied)

Dimensions :14x52.5x41.4mm

Input Resistance: 2K2.

Applications of EMI-700 Digital Input Module

It is used to run, stop and pause ramp-soak functions in RAMP/SOAK applications. It can be used to operate the process control output as AUTOMATIC/MANUAL, start the PID tune operation and latch canceling.



Detailed information about functions of Digital Input Module functions are given in parameters section. For using these functions EMI-700 Digital Input Module must be installed to Module-1 or Module-2 socket.

4.1.2 EMI-710 0/4...20mA Current Input Module

EMI-710 0/4...20mA___ current input module can be plugged in Module-1 or Module-2 socket to use as 2nd sensor input, for measuring process value or for using alarm functions which are related to measured value.



EMI-710, EMI-730, EMI-740 or EMI-750 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

Specifications of EMI-710 0/4...20mA___ Current Input Module

Input Type : 0/4...20 mA=== Current Input

Accuracy : 0.3%

Dimensions : 14x52.5x41.4mm

Input Resistance : 2R7 .

Applications of EMI-710 0/4...20mA—— Current Input Module

It can be used to measure any process value and use it with an alarm function in applications that 2nd sensor input is necessary.

The current value (0/4...20mA===) on the module input can be used as process set value when "remote set" function is activated and system can be controlled with analogue signal (0/4...20 mA====) which is applied from remote point.



Detailed information about functions of EMI-710 0/4...20mA—Current Input Module functions are given in parameters section. For using these functions EMI-710 0/4...20mA—Current Input Module must be installed to Module-1 or Module-2 socket.



For using EMI-710 0/4...20mA—— current input module as 0...20mA——, uffs I Or uffs I must be 0000

4.1.3 EMI-720 0...5A ∼ CT Input Module

EMI-720 $0...5A \sim$ CT Input Module can be plugged in Module-1 or Module-2 socket for detecting heater failures in any applications.



Only one EMI-720 \sim CT input module can be plugged in Module-1 or Module-2 socket.

Specifications of EMI-720 0...5A CT Input Module

Input Type : 0...5A Accuracy : 2% FS

Dimensions :14x52.5x41.4mm

Input Resistance :23m .

Applications of EMI-720 0...5A ∼CT Input Module

It can be used for observing heater current with current transformer and detecting heating failure.



Detailed information about functions of EMI-720 0...5A CT Input Module functions are given in parameters section. For using these functions EMI-720 EMI-720 0...5A CT Input Module must be installed to Module-1 or Module-2 socket.

4.1.4 EMI-730 TC (Thermocouple) or 0...50mV=== Input Module

EMI-730 TC or 0...50mV=== input module can be plugged in Module-1 or Module-2 socket to use as 2nd sensor input, for measuring process value or for using alarm functions which are related to measured value.

Also "remote set" function can be used by plugging this module. Please refer to Section 8.2.3 or 8.2.4 for detailed information.(\(\bar{\cappa} \) \(\bar{\cappa} \) \(\bar{\cappa} \) parameters)



EMI-710, EMI-730, EMI-740 or EMI-750 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

Specifications of EMI-730 TC or 0...50mV=== Input Module

Please refer to Section 8.2.3 or 8.2.4 for selection of input type and scale of TC input

type (L, J, K, R, S, T, B, E, N,C) Accuracy : 0.3%

Dimensions :14x52.5x41.4mm **Input Resistance** :Greater than 10M

Applications of EMI-730 0...50mV Input Module

It can be used to measure any process value and use it with an alarm function in applications that 2nd sensor input is necessary.

The voltage value (0...50mV===)on the module input can be used as process set value when "remote set" function is activated and system can be controlled with analogue signal(0..50mV===) which is applied from remote point.



Detailed information about functions of EMI-730 TC or 0...50mV ... Input Module are given in parameters section. For using these functions EMI-730 TC or 0...50mV ... Input Module must be installed to Module-1 or Module-2 socket.



For using EMI-730 TC or 0...50mV=== input module as 0...50mV===, URS | or URS | Must be 0000

4.1.5 EMI-740 Pt-100 Input Module

EMI-740 Pt-100 input module can be plugged in Module-1 or Module-2 socket to use as 2nd sensor input, for measuring process value or for using alarm functions which are related to measured value.

Also "remote set" function can be used by plugging this module. Please refer to Section 8.2.3 or 8.2.4 for detailed information.(F 5 1 , F 5 2 parameters)



EMI-710, EMI-730, EMI-740 or EMI-750 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

Specifications of EMI-740 Pt-100 Input Module

Please refer to Section 8.2.3 or 8.2.4 for selection of input type and scale

Accuracy : 0.5%

Dimensions : 14x52.5x41.4mm **Input Resistance** : Greater than 10M

Applications of EMI-740 Pt-100 Input Module

It can be used to measure any process value and use it with an alarm function in applications that 2nd sensor input is necessary.

The Pt-100 value on the module input can be used as process set value when "remote set" function is activated and system can be controlled with analogue signal which is applied from remote point.



Detailed information about functions of EMI-740 Pt-100 input module are given in PARAMETERS section. For using these functions EMI-740 Pt-100 input module must be installed to Module-1 or Module-2 socket.

4.1.6 EMI-750 0...10V=== Input Module

EMI-750 0...10V=== input module can be plugged in Module-1 or Module-2 socket to use as 2nd sensor input, for measuring process value or for using alarm functions which are related to measured value.(In some sections it is defined as analogue input module)



EMI-710, EMI-730, EMI-740 or EMI-750 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

Specifications of EMI-750 0...10V Input Module

Accuracy : 0.3%

Dimensions : 14x52.5x41.4mm

Input Resistance :43K .

Applications of EMI-750 0...10V____ Input Module

It can be used to measure any process value and use it with an alarm function in applications that 2nd sensor input is necessary.

 $(0...10V_{---})$ value on module input can be used as process set value when "remote set" function is activated and system can be controlled with analogue signal $(0...10V_{---})$ which is applied from remote point.



Detailed information about functions of EMI-750 0...10mV—— Input Module are given in parameters section. For using these functions EMI-750 0...10mV—— Input Module must be installed to Module-1 or Module-2 socket.



For using EMI-750 0...10V $\underline{\hspace{0.3cm}}$ input module as 0...10V $\underline{\hspace{0.3cm}}$, $\ \square \hspace{0.3cm}$ 95 $\ \square \hspace{0.3cm}$ or $\ \square \hspace{0.3cm}$ 95 $\ \square \hspace{0.3cm}$ must be $\ \square \hspace{0.3cm}$ $\ \square \hspace{0.3cm}$

4.2 Output Modules

4.2.1 EMO-700 Relay Output Module

EMO-700 Relay output module can be plugged in Module-1 or Module-2 socket to use functions which are defined for relay output.

Specifications of EMO-700 Relay Output Module

Output : 5A @ 250V~, Single Open or Close Contact

Dimensions : 14x52.5x41.4mm

Electrical Life : 100.000 Operation (Full Load)

Applications of EMO-700 Relay Output Module

It can be used with heating or cooling functions as process control output, as alarm output by programmable different alarm functions, as logic output to transfer some datas on the device to the system. These alternatives are explained in parameters section as logic output function.



Detailed information about functions of EMO-700 Relay Output Module are given in parameters section. For using these functions EMO-700 Relay Output Module must be installed to Module-1 or Module-2 socket.

4.2.2 EMO-710 SSR Driver Output Module

EMO-710 SSR Driver Output Module can be plugged in Module-1 or Module-2 socket to use functions which are defined for SSR driver output.

Specifications of EMO-710 SSR Driver Module

Output: Maximum 26 mA, 22V=== ±10%, isolated

Dimensions: 14x52.5x41.4mm

Applications of EMO-710 SSR Driver Output Module

It can be used with heating or cooling functions as process control output, as alarm output by programmable different alarm functions, as logic output to transfer some datas on the device to the system.

Note 1: If short output period is needed in a system, using SSR Driver output module is recommended. (Relay must not be used for short output periods because of limited life of their relay contact (open/close events))



Detailed information about functions of EMO-710 SSR Driver Output Module are given in parameters section. For using these functions EMO-710 SSR Driver Output Module must be installed to Module-1 or Module-2 socket.

4.2.3 EMO-720 Digital (Transistor) Output Module

EMO-720 Digital (Transistor) Output Module can be plugged in Module-1 or Module-2 socket to use functions which are defined for digital output.

Specifications of EMO-720 Digital (Transistor) Output Module

Output : Maximum 40 mA, 15-18V=== ±10%, isolated

Dimensions: 14x52.5x41.4mm

Applications of EMO-720 Digital (Transistor) Output Module

It can be used with heating or cooling functions as process control output, as alarm output by programmable different alarm functions, as logic output to transfer some datas on the device to the system. These alternatives are explained in parameters section as logic output function.



Detailed information about functions of EMO-720 Digital (Transistor) Output Module are given in parameters section. For using these functions EMO-720 Digital (Transistor) Output Module must be installed to Module-1 or Module-2 socket.

4.2.4 EMO-730 0 / 4 ...20mA ___ Current Output Module

EMO-730 0/4...20mA --- Current Output Module can be plugged in Module-1 or Module-2 socket to use functions which are defined for current output.

Specifications of EMO-730 0/4...20mA—— Current Output Module

Output : 0/4...20mA=== current output

Accuracy : 1%

Note: To get 0...10V₋₋₋, 500 resistor with 0.05% tolerance must be connected in parallel as a shunt resistor to module output (Please refer to Section 5.2.5 for detailed information)

Maximum load impedance : 600

Dimensions : 14x52.5x41.4mm

Applications of EMO-730 0/4...20mA == Current Output Module

It can be used in heating or cooling functions as process control output.

Process value, error between process and set value or set value can be retransmitted to the system as 0...20mA—— or 4...20mA—— output. Retransmission is explained in parameters section.

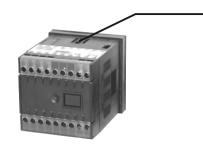


Detailed information about functions of EMO-730 Current Output Module are given in parameters section. For using these functions EMO-730 0/4...20mA——current Output Module must be installed to Module-1 or Module-2 socket.

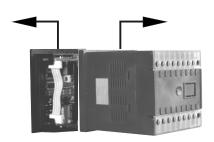
4.3 Installing and Pulling Out Input/Output Modules



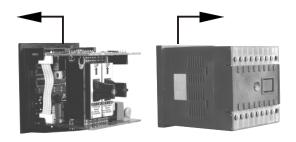
First, detach all cable connections from the device and uninstall it from the panel.



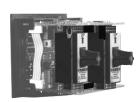
Suppress to the lock pins where top and bottom of the device



Pull the cover case with your other hand from front panel to rear side.



Pull out the cover case from the device



Slide input/output modules into socket.

Pull out the module from it's socket, instead of this module install the new one or other module user wants to use.



Replace the cover case by taking care of the terminal numbers should be at right position.

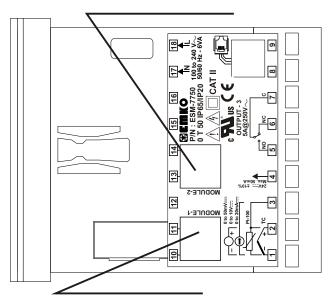


After adding or changing modules to the unit, these changes must be taken into consideration while mounting of the unit to the system. If mounting is incorrect, it can cause accidents to harm system, operator or person who does the mounting. Responsibility of these kind of harmful events belongs to the user.

4.4 To Stick Input/Output Modules' Labels to the Device

Every module which is plugged in Module-1 or Module-2 socket has labels' for showing the relation between connection terminal and the device. These labels are attached to empty boxes which are separated for Module-1 and Module-2 on the device. Labels for all modules and attachment places are shown below.

Label which is plugged in Module-2 socket, describes module termination connection is attached to this area.



Label which is plugged in Module-1 socket, describes module termination connection is attached to this area.

LABELS FOR INPUT MODULES



Label for EMI-700 Digital Input Module



Label for EMI-710 0/4...20mA
—— Current Input Module



Label for EMI-720 0...5A \sim CT Input Module



Label for EMI-730 TC or 0...50mV ===input Module



Label for EMI-740 Pt-100 Input Module



Label for EMI-750 0...10V === Input Module

LABELS FOR OUTPUT MODULES



Label for EMO-700 Relay Output Module



Label for EMO-710 SSR Driver Module

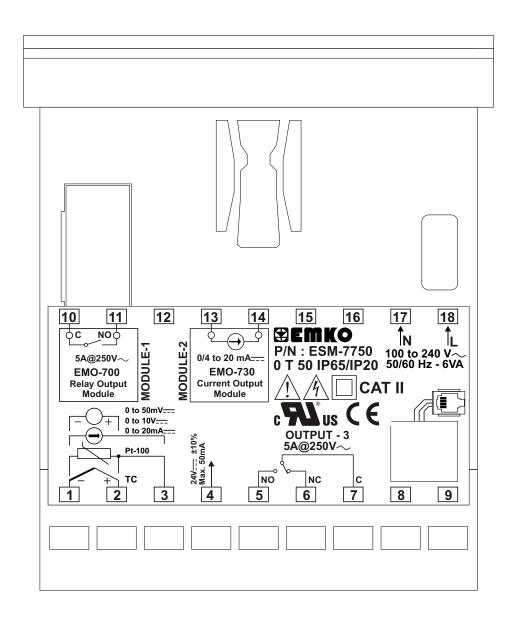


Label for EMO-720 Digital Output Module



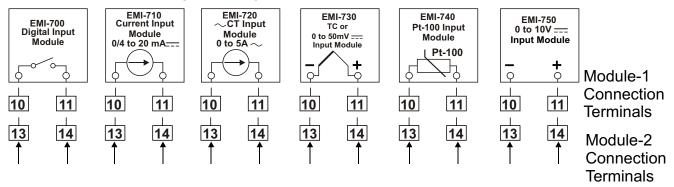
Label for EMO-730 0 / 4 ...20mA ___ Current Output Module

Example: If user installs EMO-700 Relay Output Module to Module-1 socket, EMO-730 0/4...20mA—— Current Output Module to Module-2 socket and attach the appropriate labels on the device view will be like below:

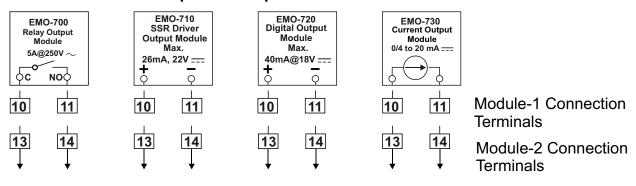


5. Connection Terminals of Input/Output Modules and Connection Wirings

Module-1 / Module-2 Optional Input Modules

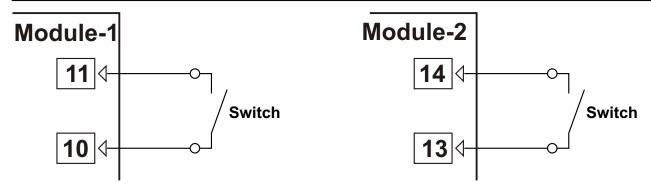


Module-1 / Module-2 Optional Output Modules



5.1 Connection Wirings for Input Modules

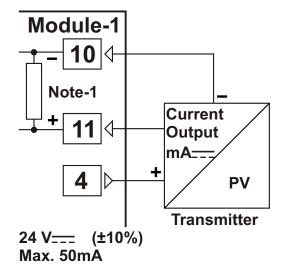
5.1.1 Connection of EMI-700 Digital Input Module

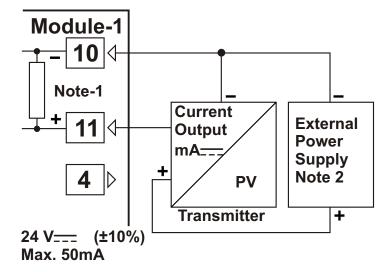


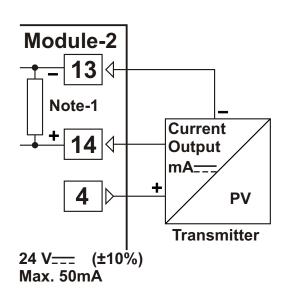
5.1.2 Connection of 3-Wire Transmitter to EMI-710 0/4...20 mA___ Current Input Module

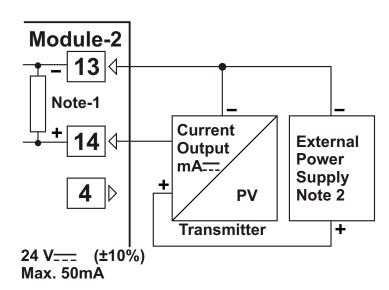
Transmitter connection by using supply voltage on the device

Transmitter connection by using external supply voltage source.









Note-1: There is internal 2R7 shunt

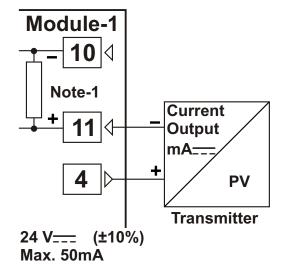
Note 2: External power supply must be selected according to power supply voltage range and required current for transmitter.

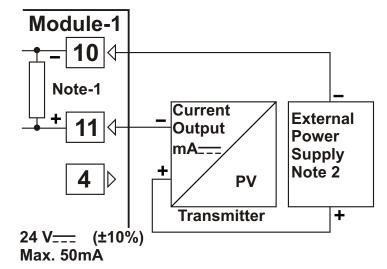
(i)

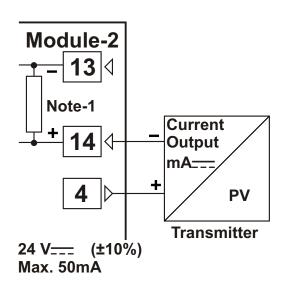
5.1.3 Connection of Serial Transmitter(Loop Powered) to EMI-710 0/4...20 mA——Current Input Module

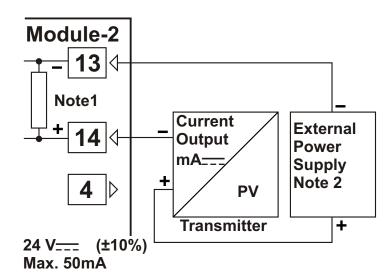
Transmitter connection by using supply voltage on the device

Transmitter connection by using external supply voltage source.





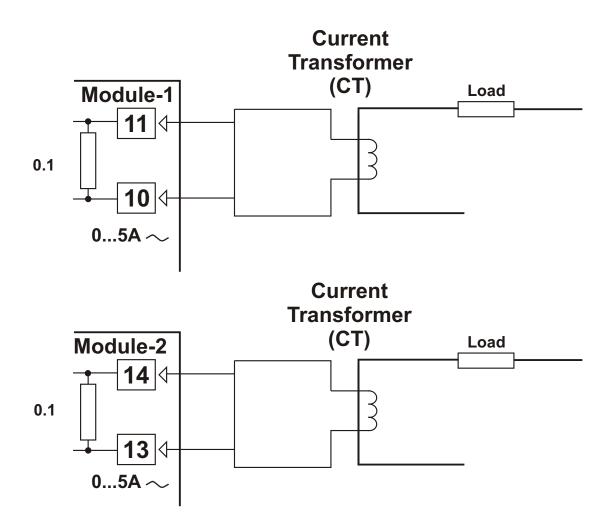




Note-1: There is internal 2R7 shunt

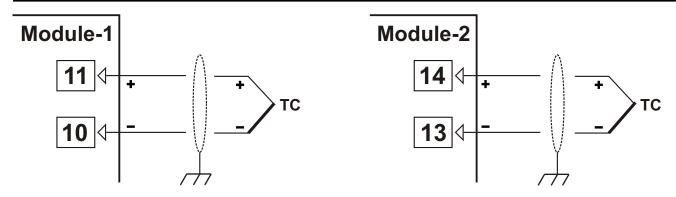
Note 2: External power supply must be selected according to power supply voltage range and required current for transmitter.





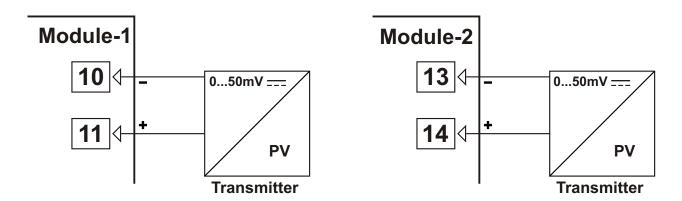
Two EMI-720 ~ CT input modules can not be plugged in Module-1 and Module-2 socket at the same time.

5.1.5 Connection of EMI-730 TC (Thermocouple) or 0...50mV___ Input Module



Connect the wires with the polarity as shown above. Always use compensation wire corresponding to the thermocouple used. If present, the shield must be connected to a proper ground.

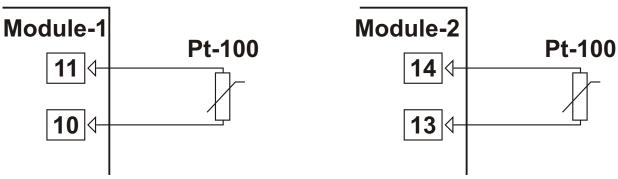
5.1.6 Using EMI-730 TC or 0...50mV Input Module as 0...50mV Input



By selecting Module-1 or Module-2 analogue input configuration parameter 51 or 512 and defining calibration points with dual point calibration property, EMI-730 TC or 0...50mV== module can be used as 0...50mV== input.

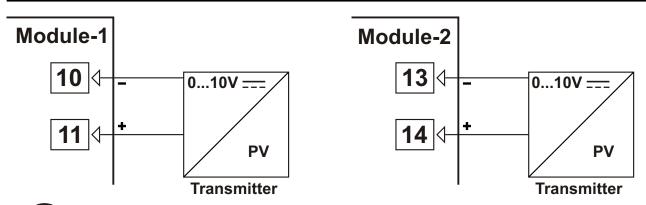
EMI-710, EMI-730, EMI-740 or EMI-750 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

5.1.7 Connection of EMI-740 PT-100 Input Module



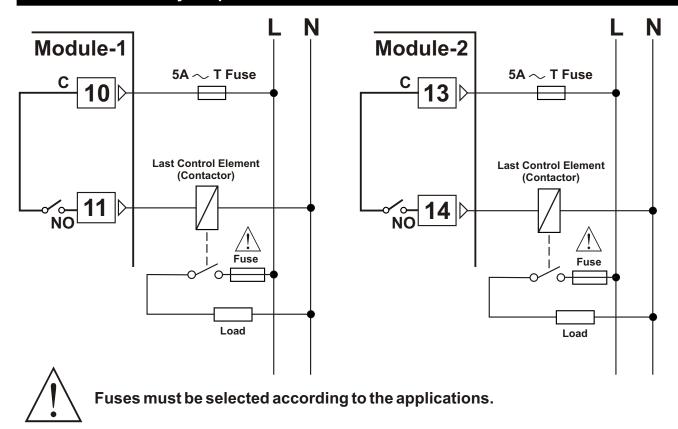
There is no line compensation in PT-100 Input Module EMI-710, EMI-730, EMI-740 or EMI-750 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

5.1.8 Connection of EMI-750 0...10V== Input Module

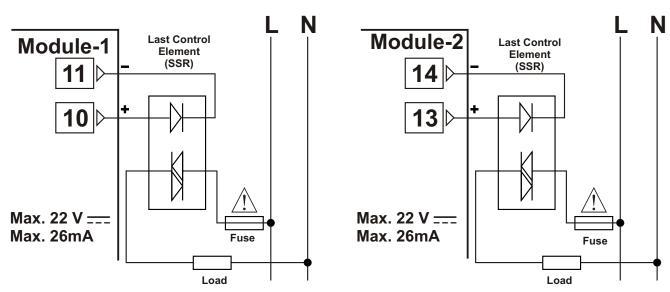


5.2 Connection Wirings for Output Modules

5.2.1 EMO-700 Relay Output Module Connection



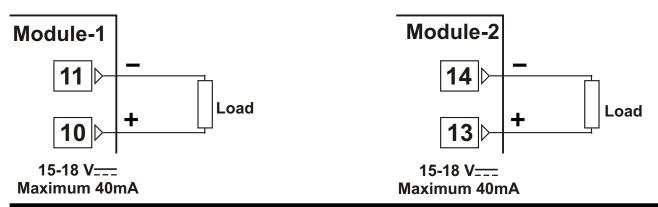
5.2.2 EMO-710 SSR Driver Module Connection



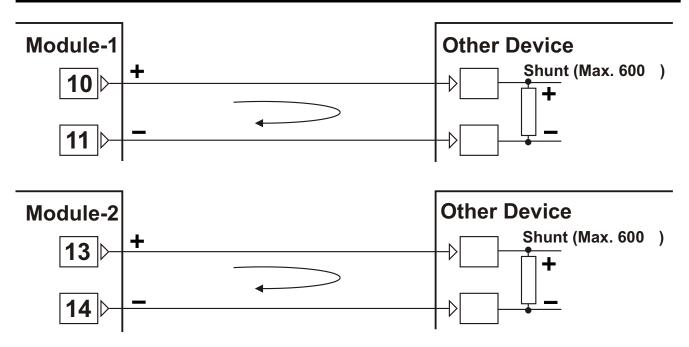
 \triangle

Fuses must be selected according to the applications.

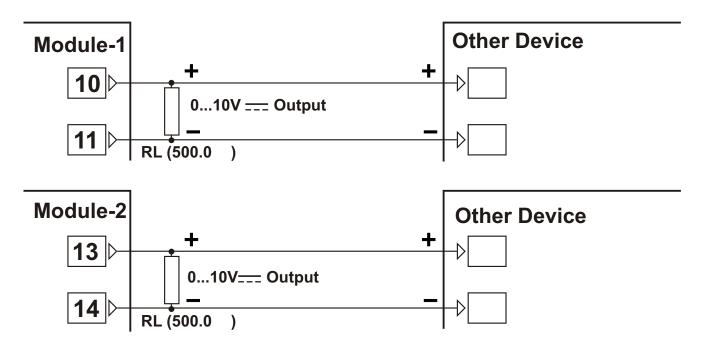
5.2.3 EMO-720 Digital (Transistor) Output Module Connection



5.2.4 EMO-730 0/4... 20 mA___ Current Output Module Connection

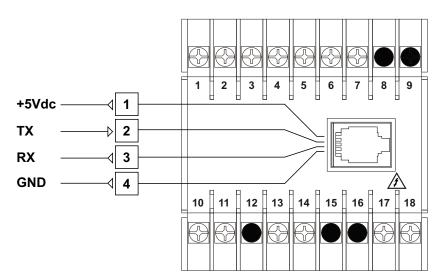


5.2.5 To Get 0...10V with EMO-730 0/4...20 mA Current Output Module

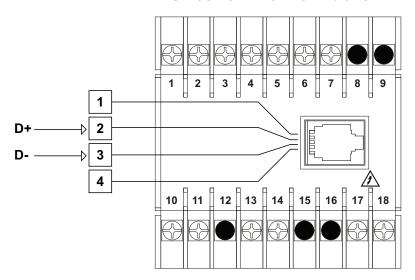


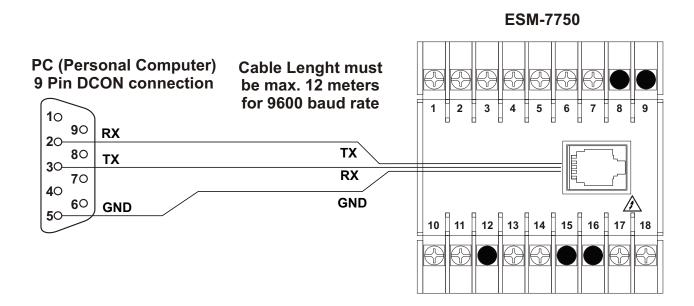
6.Connections for RS-232 / RS-485 Serial Communication

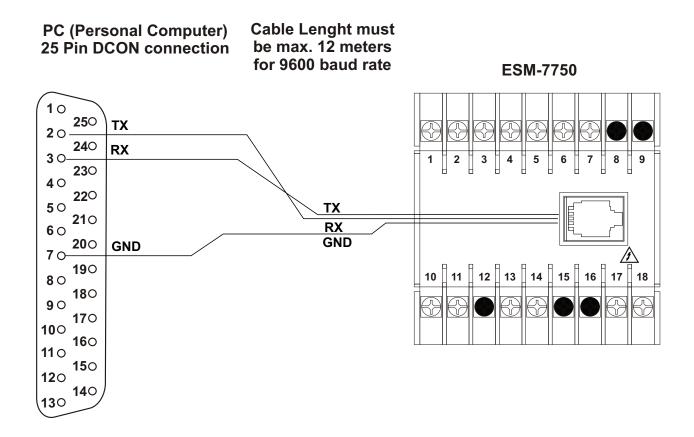
RS-232 Terminal Definitions



RS-485 Terminal Definitions

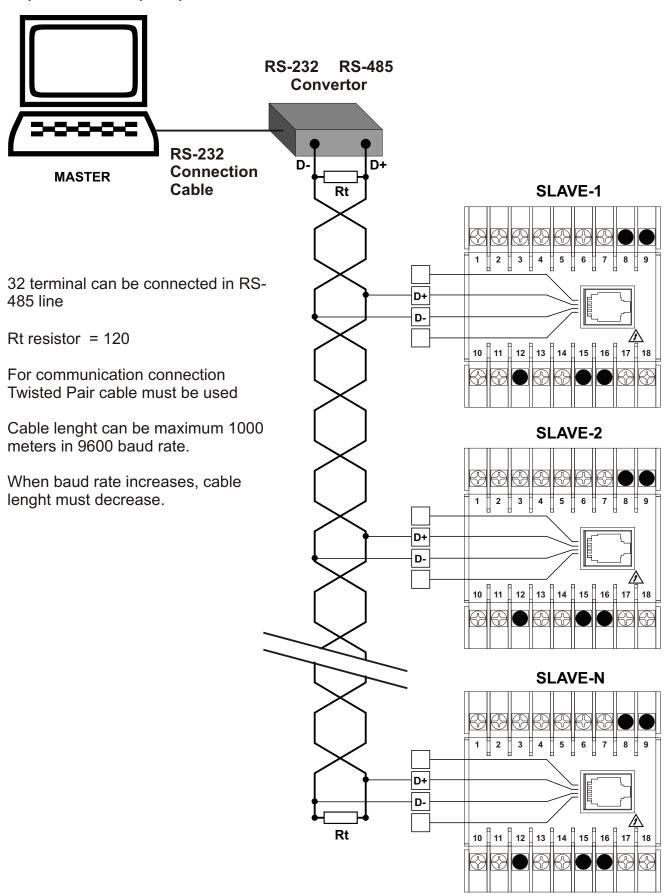






6.2 Connection for RS-485 Serial Communication

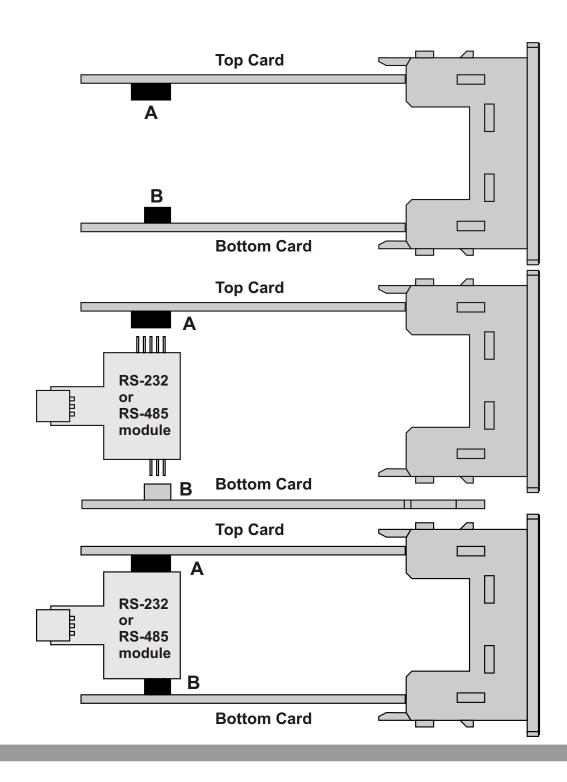
PC(Personal Computer)



6.3 Installing RS-232 / RS-485 Serial Communication Modules to the Device

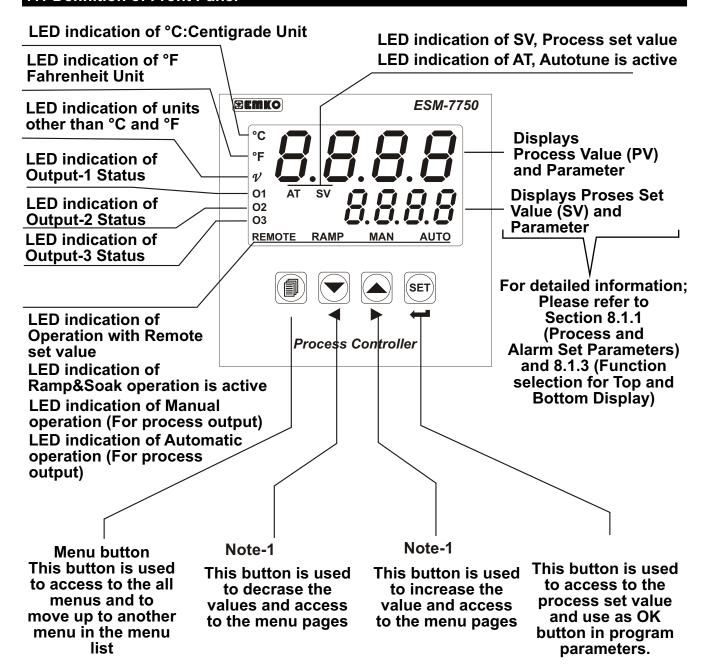
Pull the cover case with your hand through rear side as explained in "Installing and Pulling Out Input/Output Modules" section. Pull the modules in Module-1 and Module-2 socket through rear side. Separate supply card which is at the bottom of the equipment by lifting the locking tabs located on front panel. Pay attention to cable connection between top and bottom cards. Damages in this cable makes the equipment not to work.

RS-232 or RS-485 module is plugged into socket signed as A and B. Hold the equipment to be it's front panel is on your right, communication socket is on your left and module connection socket with 5 terminals on above. Plug in module connection socket with 5 terminals to the socket on Top Card. Do the same things for terminal socket in bottom card and connection socket with 3 terminals. Plug in bottom card to the place in front panel. Install the modules which are pulled out to Module-1 and Module-2 socket. Replace the cover case by taking care of the terminal numbers should be at right position.



7. Definition of Front Panel and Accessing to the Parameters

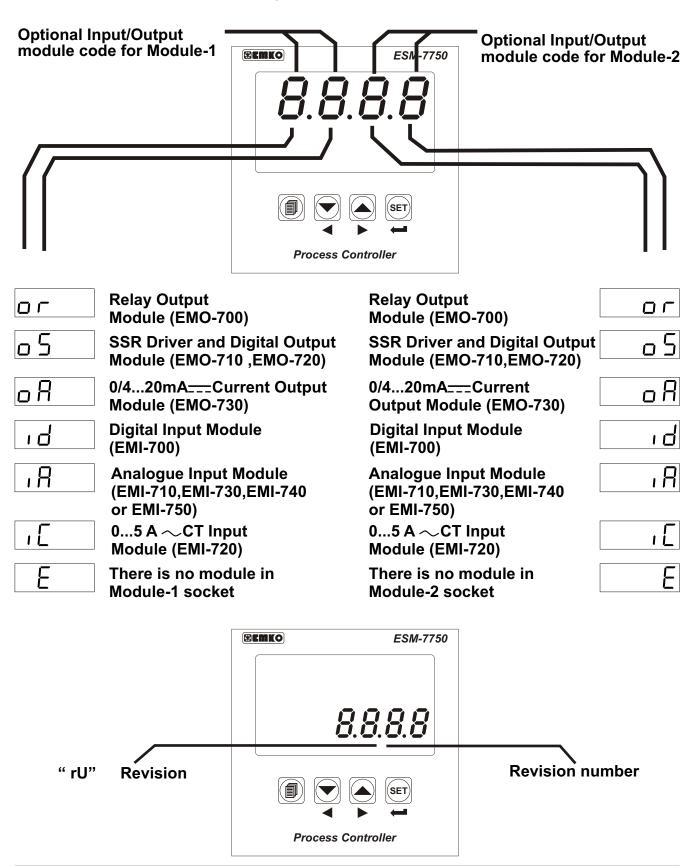
7.1 Definition of Front Panel



Note-1: If increment or decrement button is pressed for 5 seconds continuously, increment and decrement number become 10, if increment or decrement button is pressed for 10 seconds continuously, increment and decrement number become 100.

7.2 Observation of Optional Modules and Software Revision on the Displays

There are two sockets for plugging optional modules to the device. These modules are recognized by the device automatically. When the power is applied to the device all led indicators and display segments are momentarily illuminated for testing. Software revision number of the controller on the bottom display and module definition codes on the top display are momentarily illuminated. Module definition codes and how to observe these codes of optional modules in Module-1 and Module-2 socket are explained below:



When power on, display of the device is like below:



First segments of top and bottom displays are tested



Second segments of top and bottom displays are tested.



Third segments of top and bottom displays are tested.



Fourth segments of top and bottom displays are tested.



On top display which modules are plugged in Module-1 and Module-2 socket and on bottom display revision number are shown. All leds are energised. Above, there is EMO-710 SSR Driver Output module in Module-1 socket and EMO-700 Relay Output Module in Module-2 socket. Revision number is "13".

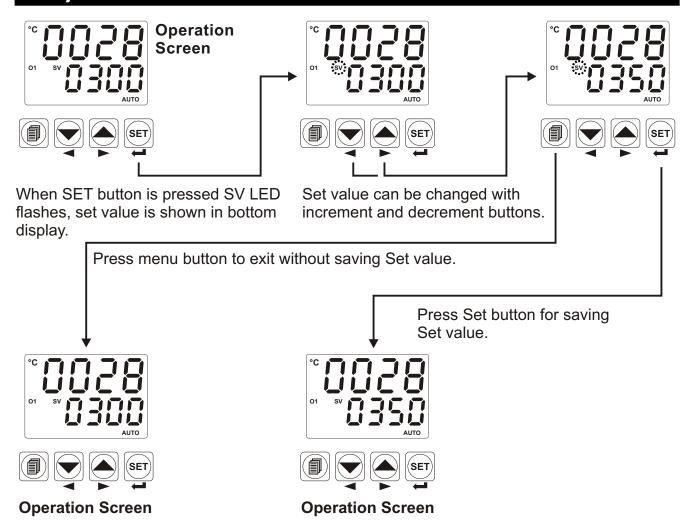


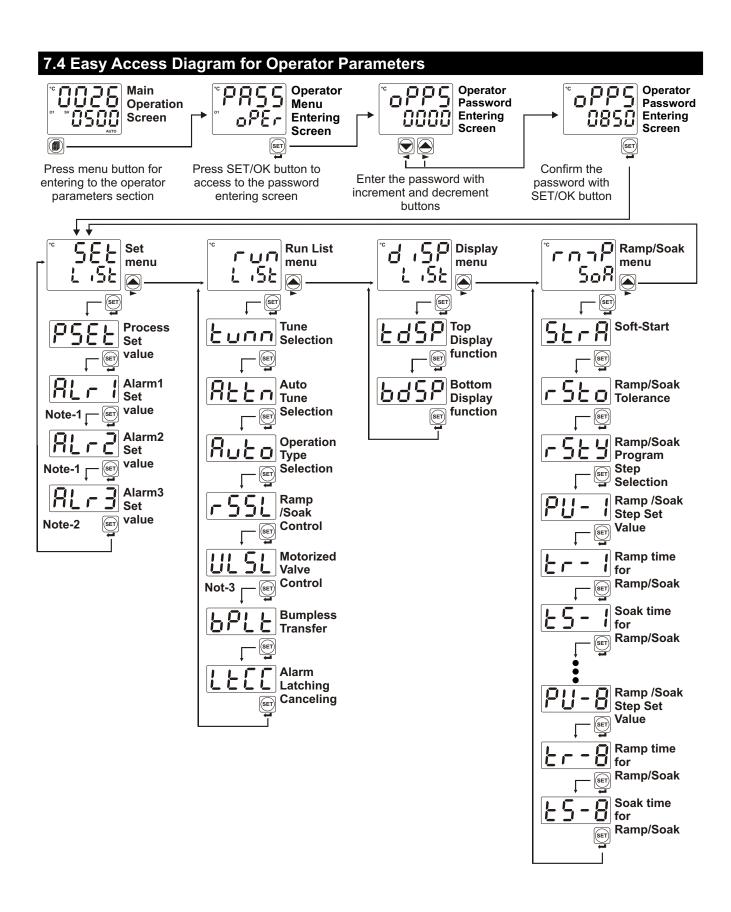
Main operation screen is shown



If there is an unexpected situation while opening the device, power off the device and inform a qualified personnel.

7.3 Adjustment of Process Set Value

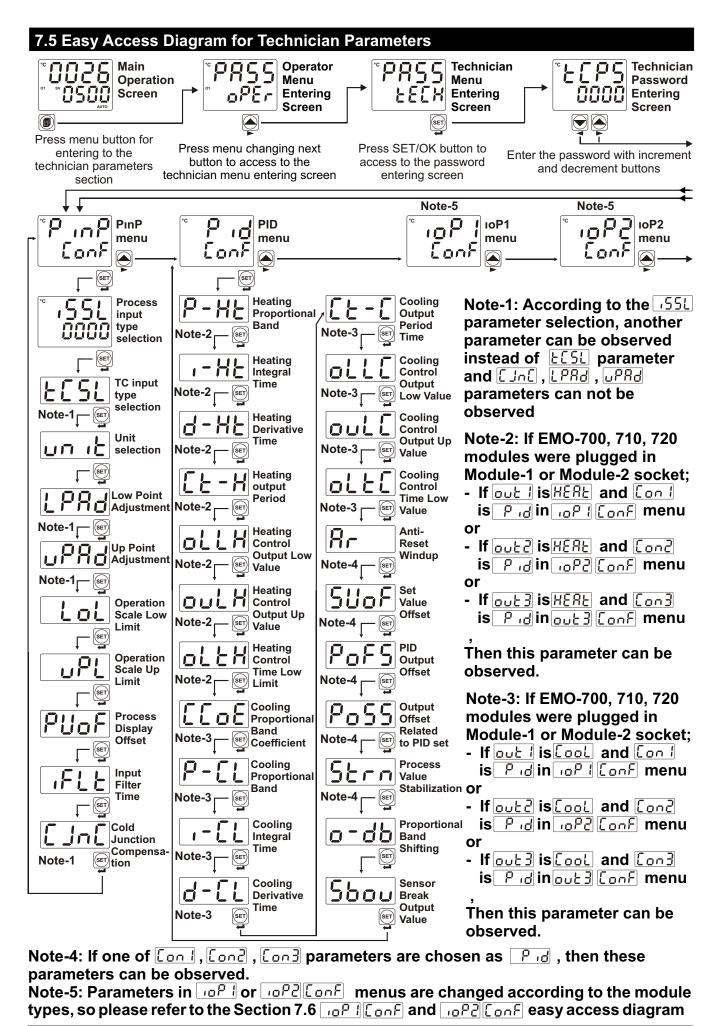




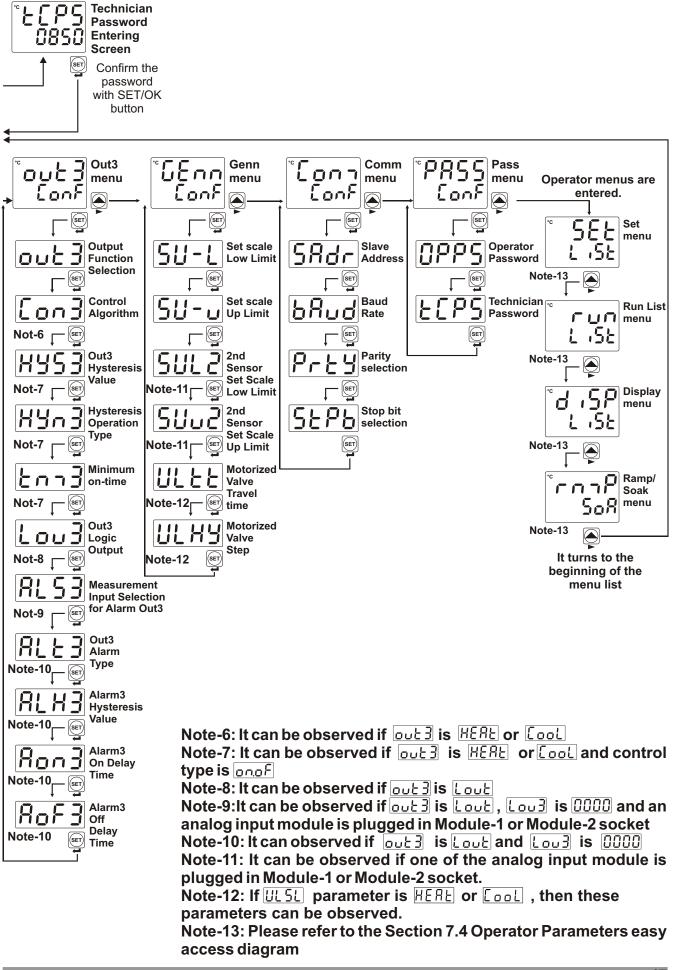
Note-1: It is observed when EMO-700, EMO-710 or EMO-720 module is plugged in Module-1 or Module-2 socket if <code>out</code> parameter is <code>lout</code> in <code>op</code> <code>loof</code> menu and <code>louf</code> parameter is <code>lout</code> in <code>op</code> menu and <code>louf</code> parameter is <code>lout</code> in <code>op</code> menu and <code>louf</code> parameter is <code>lout</code>.

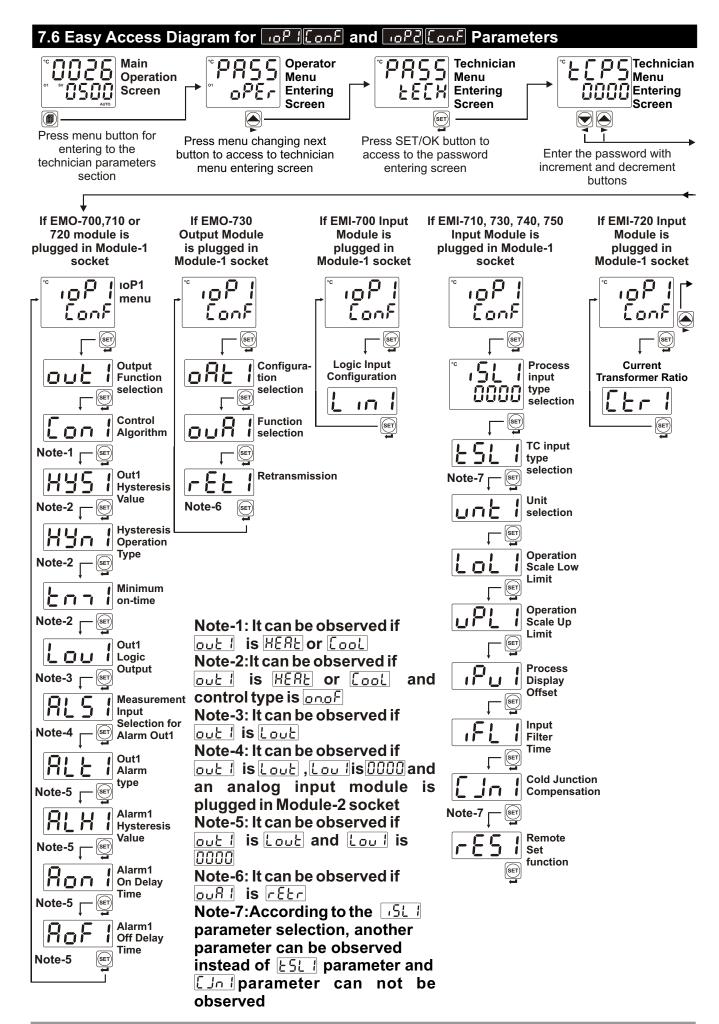
Note-2: It is observed if ਾਰਤੇ parameter is ਿਹਾਏ in ਾਰਤੇ ਰਿਹਾ menu and ਿਹਾਤੇ parameter is ਹਿਰਦੇ in ਾਰਤੇ ਰਿਹਾ ਸਿੰਘ ਸ਼ਿਲ੍ਹੇ ਸ਼ਿ

Note-3: It is observed if EMO-700 Relay Module is plugged in Module-1 socket.



7.5 Easy Access Diagram for Technician Parameters



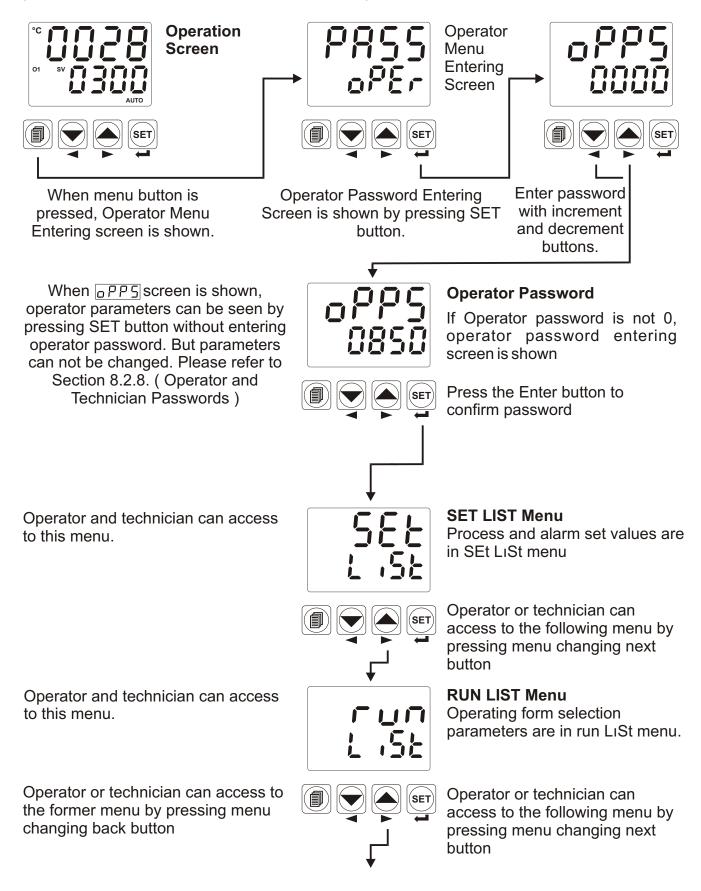


7.6 Easy Access Diagram for op tone and opposer Parameters PinP **Technician Password** menu menu Conf Conf Entering Screen SET Confirm the password with SET/OK button If EMI-710,730,740, 750 If EMO-700,710 or If EMO-730 If EMI-700 Input If EMI-720 Input 720 module is **Output Module** Module is Input Module is Module is plugged in Module-2 is plugged in plugged in plugged in Module-2 plugged in socket Module-2 socket Module-2 socket socket Module-2 socket 10 P2 menu Lonf Loni Process Input type selection Configura-Output **Logic Input** Current Function Configuration Transformer Ratio selection selection Function Selection Control Algorithm TC input Note-8 Out3 menu type selection օրե3| Out2 Retransmission Note-14 Hysteresis Conf Value Unit Note-9 Note-13 selection Genn menu Hysteresis Operation GEnn Operation [onf Scale Low Limit SET Minimum Comm menu Operation Lonn Scale Up Note-8: It can be observed if Lonf Limit out2 is HEAt or [oot Out2 Logic Note-9:It can be observed if Pass menu Process Output out2 is HEAt or Coot and PRSS Display offset Conf Measurement control type is onoF Input Note-10: It can be observed if Selection for Input Filter Alarm Out2 lout2 is Lout Set menu S8Ł Note-11: It can be observed if **Out2 Alarm** Ĺ įSE ♠ out2 is Lout, Lou2 is 0000 and Cold Junction an analog input module is Note-12 Run List menu plugged in Module-1 socket Compensa-(SET) tion Alarm2 run Note-12: It can be observed if **Hysteresis** L ist Rem Set Value out? is Lout and Lou? is Remote 0000 function Display menu Alarm2 Note-13: It can be observed if On Delay ou82 **is** rEtr Time Note-14: According to the 562 parameter selection, another Off Delay Ramp/Soak menu parameter can be observed Time ودما Note-12 instead of <code>ESL2</code> parameter and 508 []n] parameter can not be observed It turns to the beginning

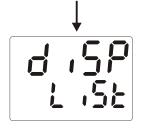
of the menu list

7.7 Accessing to the Operator Menu

The parameters have been divided into groups according to their functions. Every group has a title and firstly user must determine the title (menu) for accessing to the parameters. Refer to the parameters section for detailed information about parameters.



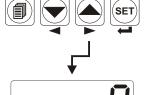
Operator and technician can access to this menu



DİSPLAY LIST Menu

This menu determines which parameter is shown in top and bottom display.

Operator or technician can access to the former menu by pressing menu changing back button



Operator or technician can access to the following menu by pressing menu changing next button.

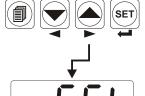
Operator and technician can access to this menu



RAMP&SOAK Menu

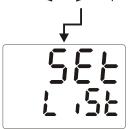
Configuration of Ramp/Soak function and step set value parameters are in this menu.

Operator or technician can access to the former menu by pressing menu changing back button



Operator or technician can access to the following menu by pressing menu changing next button.

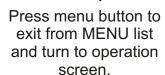
Operator and technician can access to this menu



SET LIST Menu

SET LIST menu exists after RAMP/SOAK menu.

Operator or technician can access to the former menu by pressing menu changing back button

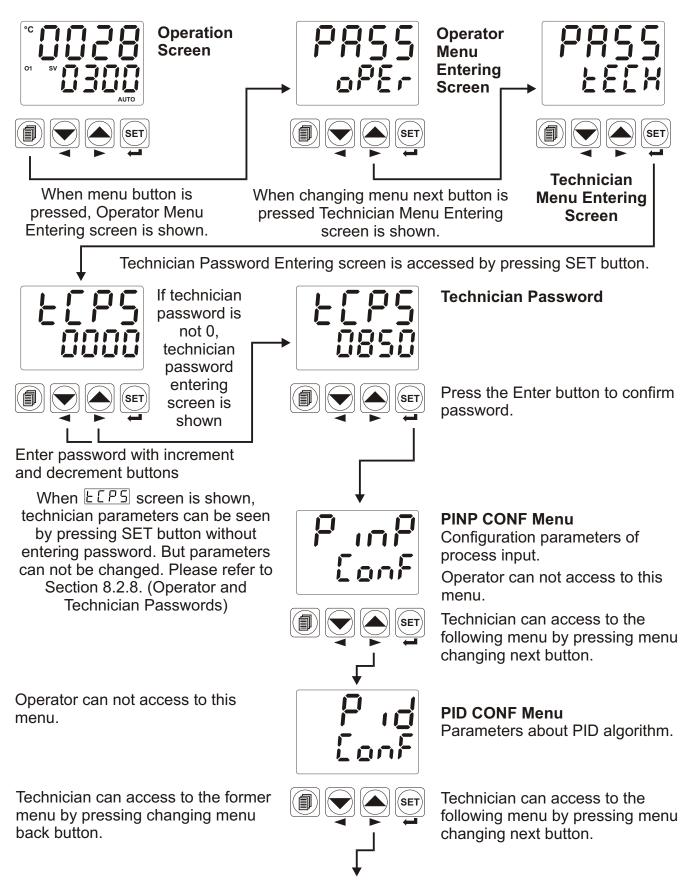


Continue to press menu changing next and back buttons to change the menu page

By pressing ENTER button, user can access to the menu page and to all parameters in this menu page.

7.8 Accessing to the Technician Menu

The parameters have been divided into groups according to their functions. Every group has a title and firstly user must determine the title (menu) for accessing to the parameters. Refer to the parameters section for detailed information about parameters.



Operator can not access to this menu.

This menu is not visible if there is no module in Module-1 socket.

Technician can access to the former menu by pressing changing menu back button.

Operator can not access to this menu.

This menu is not visible if there is no module in Module-2 socket.

Technician can access to the former menu by pressing changing menu back button.

Operator can not access to this menu.

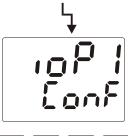
Technician can access to the former menu by pressing changing menu back button.

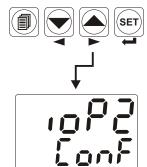
Operator can not access to this menu.

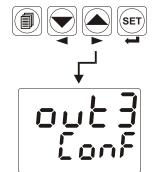
Technician can access to the former menu by pressing changing menu back button.

Operator can not access to this menu.

Technician can access to the former menu by pressing changing menu back button.







IOP1 CONF Menu

This menu defines configuration parameters of input/output modules in Module-1 socket.

Technician can access to the following menu by pressing menu changing next button.

IOP2 CONF Menu

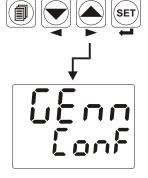
This menu defines configuration parameters of input/output modules in Module-2 socket.

Technician can access to the following menu by pressing menu changing next button.

OUT3 CONF Menu

This menu defines configuration parameters of output-3.

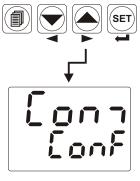
Technician can access to the following menu by pressing menu changing next button.



GENN CONF Menu

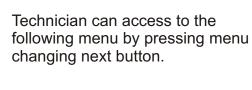
This menu defines general parameters

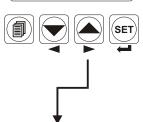
Technician can access to the following menu by pressing menu changing next button.



COM CONF Menu

This menu defines configuration parameters for serial communication





Operator can not access to this menu.

This menu is not visible if
Technician Parameters
Section is entered by pressing
SET button without entering
Technician Password.

Operator and technician can access to the former menu by pressing menu changing back button.

Operator and technician can access to this menu.

Operator and technician can access to the former menu by pressing menu changing back button.

Operator and technician can access to this menu.

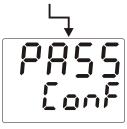
Operator and technician can access to the former menu by pressing menu changing back button.

Operator and technician can access to this menu.

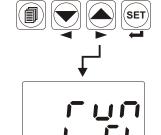
Operator and technician can access to the former menu by pressing menu changing back button.

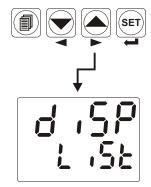
Operator and technician can access to this menu.

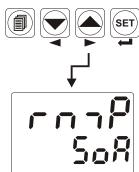
Operator and technician can access to the former menu by pressing menu changing back button.

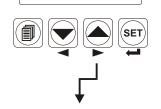


SET SET SET









PASS CONF Menu

Operator and technician passwords are in this menu.

Operator and technician can access to the following menu by pressing menu changing next button

SET LIST Menu

Process and alarm set values are in SET LIST menu.

Operator and technician can access to the following menu by pressing menu changing next button

RUN LIST Menu

Operating form selection parameters are in RUN LIST menu.

Operator and technician can access to the following menu by pressing menu changing next button

DISP LIST Menu

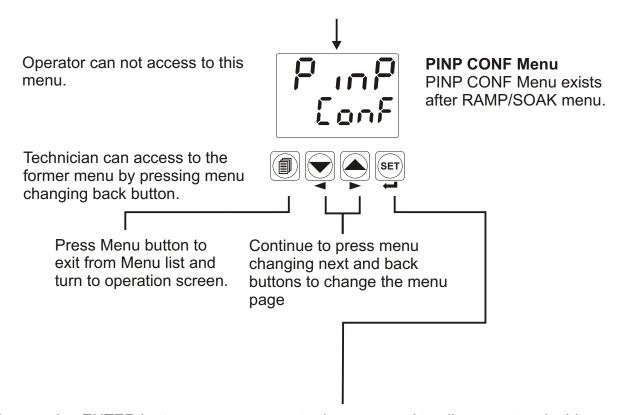
It defines which parameter will be shown on top and bottom displays.

Operator and technician can access to the following menu by pressing menu changing next button

Ramp&Soak Menu

Configuration of Ramp/Soak functions and step set value parameters are in this menu.

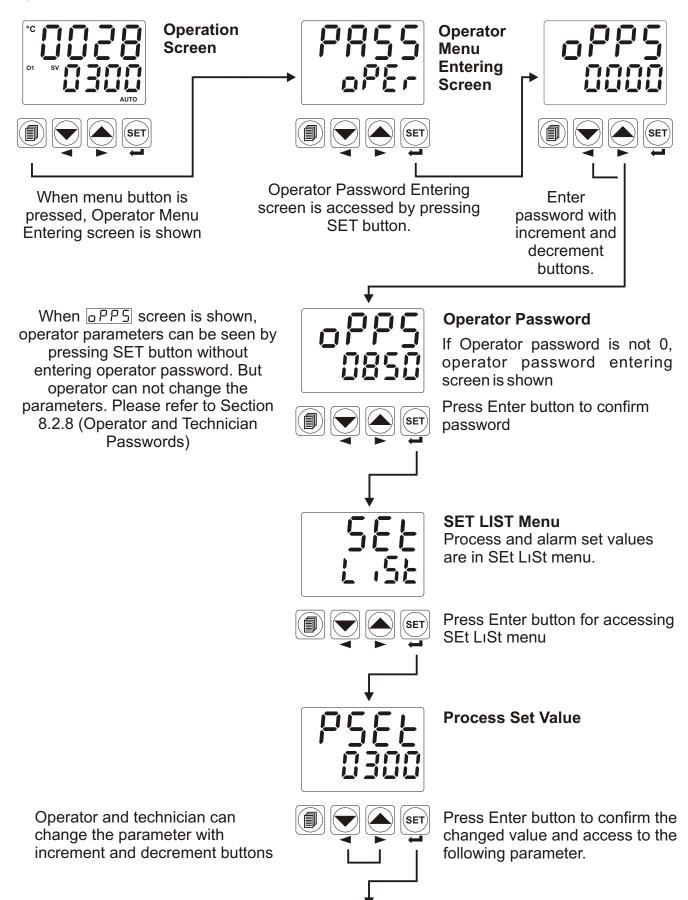
Operator and technician can access to the following menu by pressing menu changing next button



By pressing ENTER button, user accesses to the menu and to all parameters in this menu.

7.9 Adjustment of Alarm Set Values

If standard output (Output-3), Module-1 or Module-2 is configured as an alarm output, alarm set values of these outputs are in "SEt LiSt" menu. User can access to "SEt LiSt" menu both from operator and technician menus.



This parameter is not visible if there is no output module in Module-1 socket or output module is not configured as an alarm output.

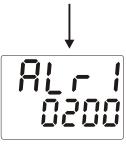
Operator and technician can change the parameter with increment and decrement buttons.

This parameter is not visible if there is no output module in Module-2 socket or output module is not configured as an alarm output.

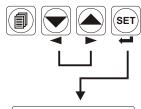
Operator and technician can change the parameter with increment and decrement buttons.

This parameter is not visible if Output-3 is not configured as an alarm output

Press menu button to turn to operation screen



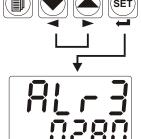
Alarm-1 Set Value



Press Enter button to confirm the changed value and access to the following parameter.



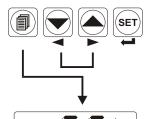
Alarm-2 Set Value



Press Enter button to confirm the changed value and access to the following parameter.



Alarm-3 Set Value



Operator and technician can change the parameter with increment and decrement buttons.



SET LIST Menu



Press menu button to turn to operation screen

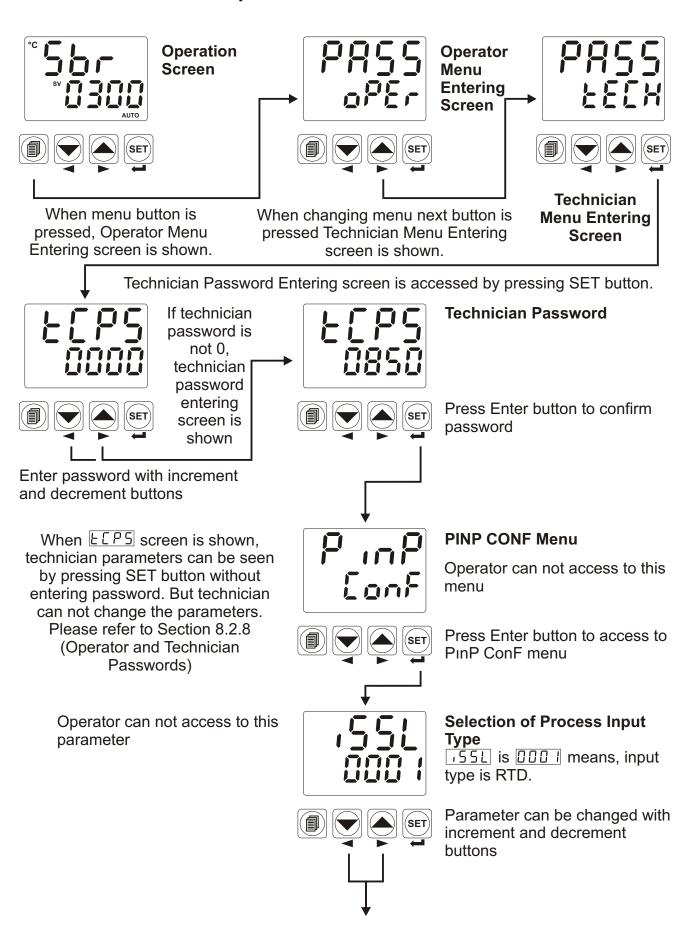


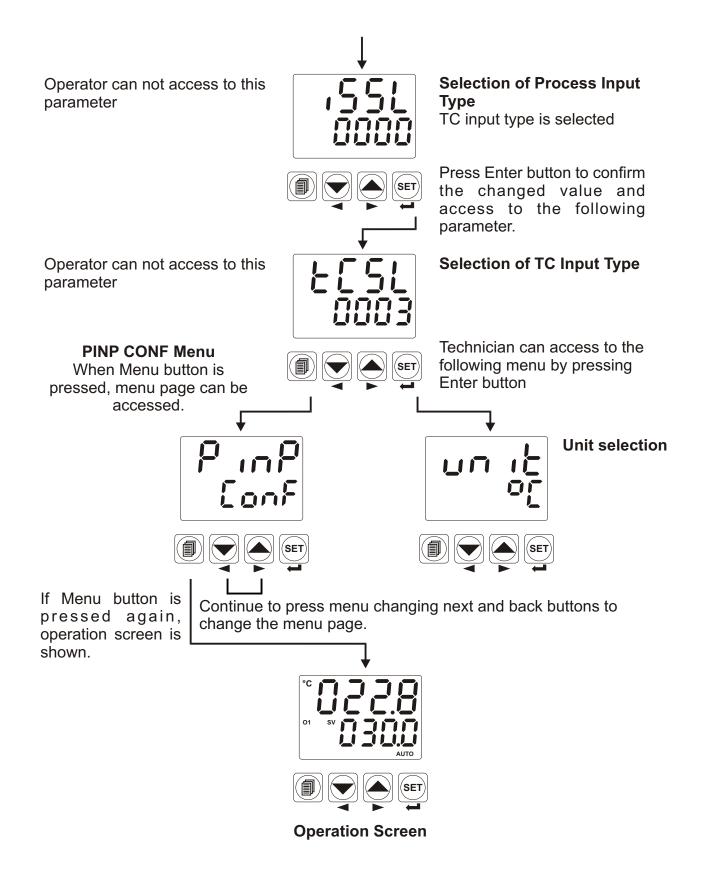
Operation Menu



7.10 Changing and Saving Parameter Values

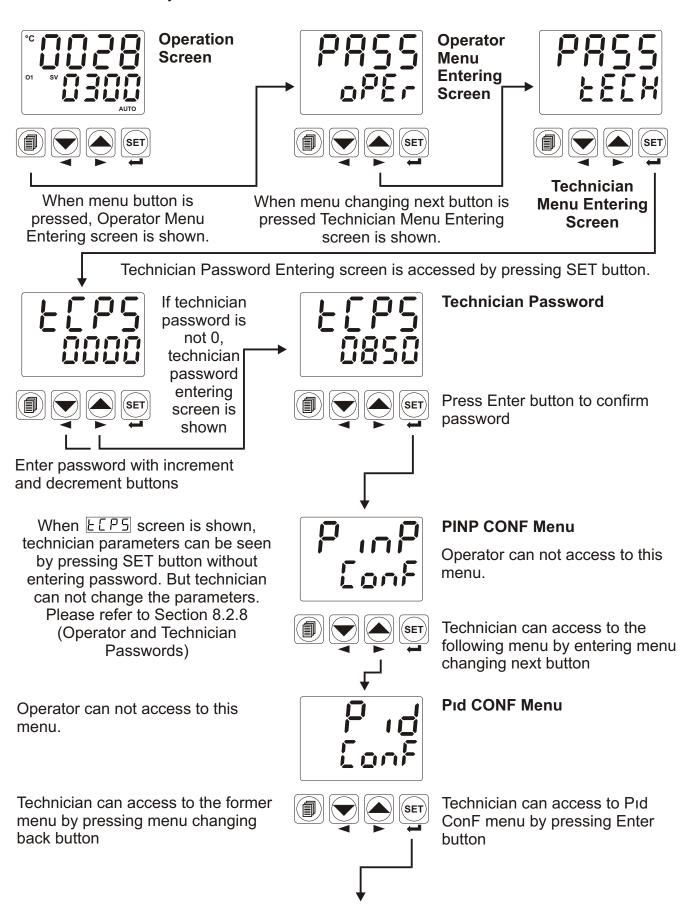
Example-1: To change Process Input Type parameter 551 in "PinP Conf" menu, user must access to PinP ConF menu firstly.

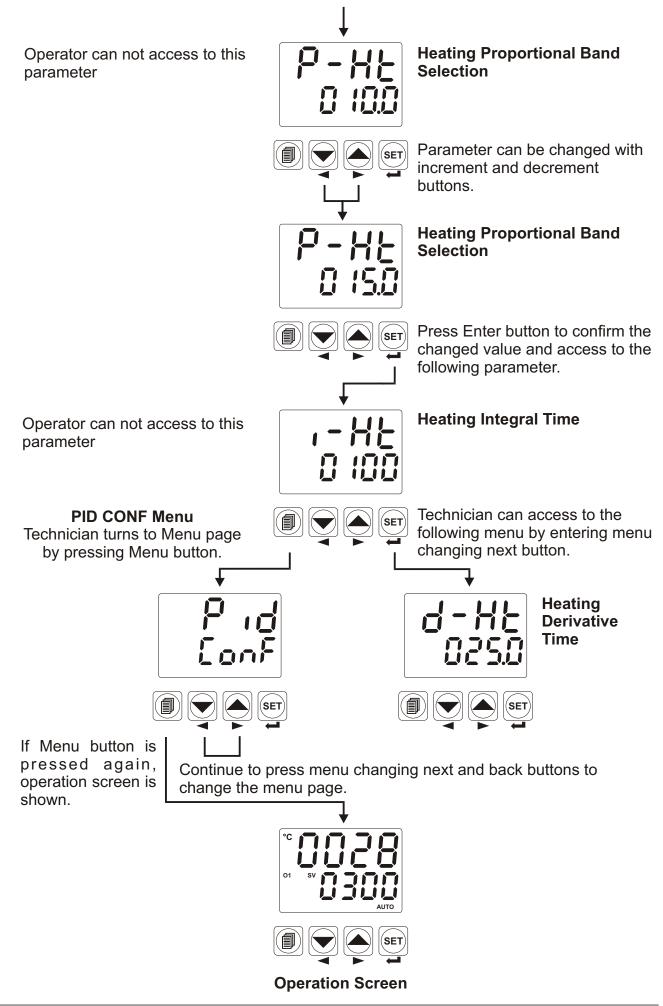




Example-2: To change heating proportional band parameter P-HE in "Pid Conf" menu.

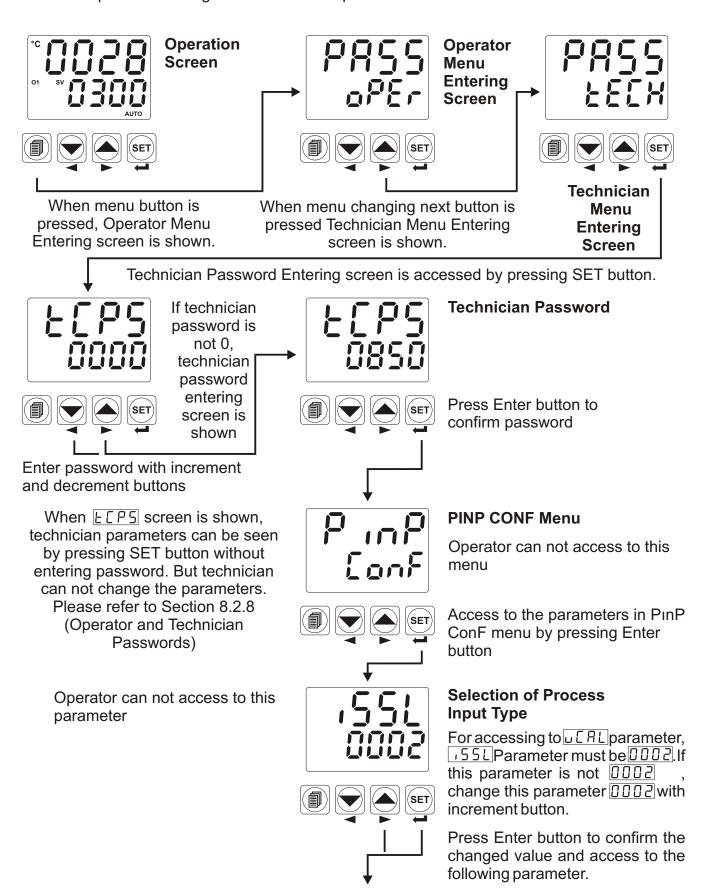
P-HE Parameter is on Pid ConF menu. For accessing to this parameter, user must access to "Pid ConF" menu firstly.





Example-3: To change — Voltage / Current Input Calibration Type Selection parameter $\square \subseteq \mathcal{PL}$ in "PInP Conf" menu

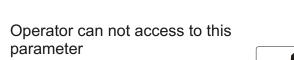
Parameter is on "PINP ConF" menu. For accessing to this parameter, technician must access to "PINP ConF" menu firstly. In this example, changing input type of a device from thermocouple to ____Voltage/Current and dual point calibration selection is shown.

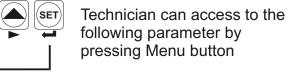


Operator can not access to this parameter

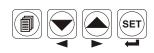


___ Voltage / Current Input Type selection



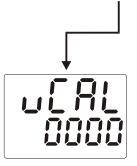


Decimal Point Position Selection



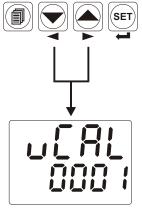
Technician can access to the following menu by pressing Enter button

Operator can not access to this parameter



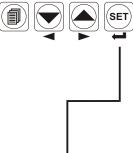
Voltage / Current Input Calibration Type Selection

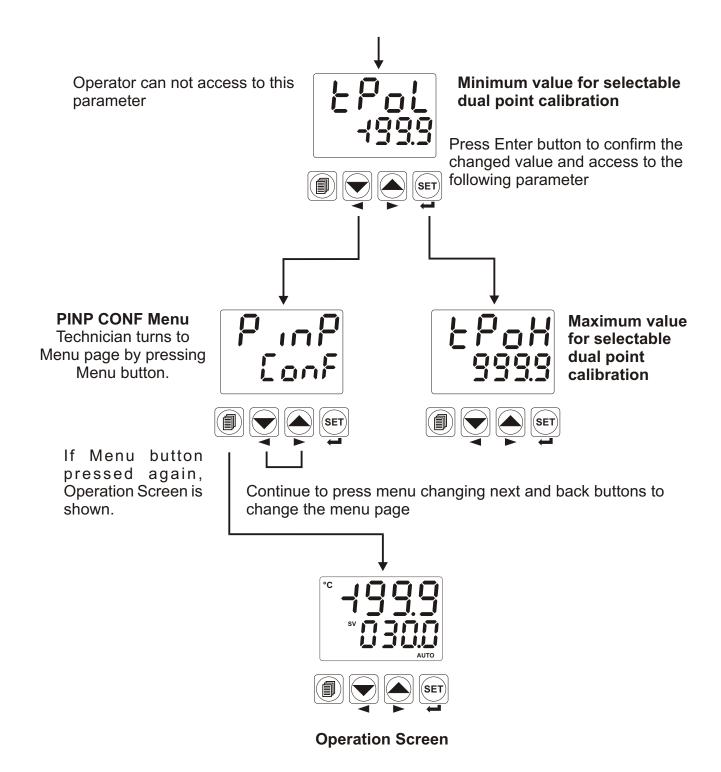
Technician can change the parameter with increment and decrement buttons



Voltage / Current Input Calibration Type Selection

Press Enter button to confirm the changed value and access to the following parameter.





8. Parameters

Parameters are divided into two groups. These can be accessed by operator and technician. Also, they are grouped into subgroups according to their functions. The subgroups are named as menu pages.

8.1 Operator Parameters



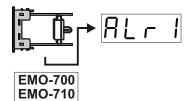
EMO-720

8.1.1 Process and Alarm SET Parameters

PSEL

This is the device's process set value. Controlling is done according to this value by process control outputs.

Process set value can be adjusted from minimum value of set scale 5 U - L To maximum value of set scale 5 U - u



If EMO-700 Relay, EMO-710 SSR Driver or EMO-720 Digital (Transistor) output module is plugged in Module-1 socket and output is configured as an alarm output, this parameter defines the set value of the alarm output.

 FL r I
 Set value can be adjusted from minimum value of set scale

 5 U - L
 To maximum value of set scale



EMI-730 EMI-740

EMI-750

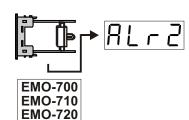
If one of the analogue input modules is plugged in Module-2 socket and measurement input selection parameter [8.5.] which is explained in Section 8.2.3 for Module-1 alarm output is [9.0.], [8.6.] can be defined alarm set value for analogue input module in Module-2.

Parameter can be adjusted from minimum set value of 2nd sensor input $\boxed{5UL2}$ to maximum set value of 2nd sensor input $\boxed{5UL2}$. Also point position of $\boxed{9Lr1}$ parameter and measured value from analogue input module (2nd sensor input) is the same.

In this conditions, alarm output operates according to 2nd sensor input value and $\boxed{\text{FL} \, \text{Γ}}$ parameter.



Set value of Heating Failure Alarm



If EMO-700 Relay, EMO-710 SSR Driver or EMO-720 Digital (Transistor) output module is plugged in Module-2 socket and output is configured as an alarm output, this parameter defines the set value of the alarm output.

ALr2Set value can be adjusted from minimum value of set scale5U-LTo maximum value of set scale

MODULE-1

EMI-710 EMI-730 EMI-740 EMI-750

Parameter can be adjusted from minimum set value of 2nd sensor input 500 and maximum set value of 2nd sensor input 500 and maximum set value of 2nd sensor input 500 and sensor i

In this conditions, alarm output operates according to 2nd sensor input value and $\boxed{RL \ r \ 2}$ parameter.

MODULE-1

Set value of Heating Failure Alarm



If \sim CT input module (EMI-720) is plugged in Module-1 socket and Module-1 alarm type parameter $\boxed{\text{RLE}}$ which is explained in Section 8.2.3 is $\boxed{\text{DDD}}$, $\boxed{\text{RLrE}}$ parameter can be adjusted from 0.0 to $100.0A\sim$



If OUT-3 relay output module is configured as alarm output, this parameter defines the set value of the alarm output.

 FLr3
 Set value can be adjusted from minimum value of set scale

 to maximum value of set scale

MODULE-1 or MODULE-2

If one of the analogue input modules is plugged in Module-1 or Module-2 socket and measurement input selection parameter $\boxed{\text{FL53}}$ which is explained in Section8.2.5 for Module-1 alarm output is $\boxed{\text{DD1}}$, $\boxed{\text{FLr3}}$ can be defined alarm set value for analogue input module in Module-1 or Module-2 socket.



EMI-710

EMI-730

EMI-740 EMI-750 Parameter can be adjusted from minimum set value of 2nd sensor input 500 and maximum set value of 2nd sensor input 500 and maximum set value of 2nd sensor input 500 and parameter and measured value from analogue input module (2nd sensor input) is the same.

In this conditions, alarm output operates according to 2nd sensor input value and \Box parameter.

MODULE-1

or MODULE-2

Set value of Heating Failure Alarm



If CT input module (EMI-720) is plugged in Module-1 or Module-2 socket and Module-1 alarm type parameter ☐ Which is explained in Section 8.2.5 is ☐ ☐ ☐ ☐ , ☐ ☐ ☐ parameter can be adjusted from 0.0 to 100.0A ...

8.1.2 Selection of PID Tune and Operation Form

եսոո

TUNE SELECTION

By selecting one of the methods below, device can determine the PID parameters.

00

Device operates according to the defined PID parameters

Rtun

Auto tune (Limit Cycle Tuning) operation

Stun

Self tune (Step Response Tuning) operation

AL.SE

Auto-Self Tune

Self Tune operation is performed, if the conditions are realized when power on firstly. In normal operation, it controls the tune conditions in **Auto Tune** selection which explained below. If any of the conditions is realized, it performs the **Auto Tune** operation.

Attn

AUTOMATIC TUNE SELECTION



Device does not do Rtun (Limit Cycle Tuning) operation or while Rtun operation runs, this selection is adjusted and **Auto Tune** operation is canceled.



If <u>Funn</u> parameter is <u>REun</u> or <u>RESE</u>, when the conditions for Auto Tune parameter that are explained in Tune Methods section are realized, it starts to perform Auto Tune (Limit Cycle Tuning) operation.

TUNE METHODS:

There are 2 different methods for determining PID parameters by the device. These are **Auto tune** (Limit Cycle Tuning) and **Self Tune** (Step Response Tuning) methods.

Determining of PID parameters with **Auto Tune** is started in these conditions:

- **1-** By the user in any time,
- 2- By the device when system gets unstable and starts oscillation

If process value is out of **Set ± Process value stabilisation** 5trn value (Please refer to Section 8.2.2) and starts to oscillate, then device changes the Parameter to 45 and Auto Tune operation is started.

3- After changing set value, if difference between newly defined set value and former set value is greater than proportional band, device will start it.

If set value is changed to a value that is greater than;

±[Scale * (Heating or Cooling Proportional Band)]/1000 value,

Parameter is adjusted <u>YES</u> by the device and **Auto Tune** operation is started.



For Auto Tune (Limit Cycle Tuning) operation:

- 1- Tune selection parameter եսոր in "run List" menu must be selected Զեսո Autotune or Զե.Տե Auto-Self tune .
- **2 -** For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.
- **3 -** If process set value is changed while Tune operation is being performed, Tune operation is canceled

Example -1: Starting Auto Tune operation by the user;

- Enter operator or technician menu.
- Adjust tune selection parameter <u>Lunn</u> in "run List" menu, **Auto Tune** <u>R Lun</u> Or **Auto-Self Tune** <u>R L 5 L</u>
- Adjust automatic tune selection parameter RELD in "run List" menu YES And return to main operation screen.
- Observe that "AT" led is active.

If **Auto Tune** operation finishes without any problem, device saves the PID coefficients to memory and continue to run. Recommendate PID parameter is adjusted automatically.

Canceling Auto Tune operation:

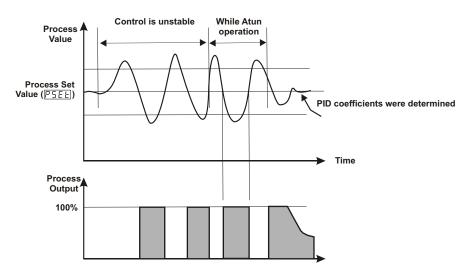
- 1- If sensor breaks:
- 2- If Auto Tune operation can not be completed in 8 hours
- 3-If user adjusts Eunn parameter no or 5Eun
- 4- If user adjusts R L L n parameter no
- 5- If process set value is changed while Tune operation is being performed
- **6-** While Tune operation is being performed, if operation type selection is changed as "Manual" when it is "Automatic" (If operation type selection is changed as "Automatic" when it is "Manual", then Tune operation is started again)
- **7-** If output function is changed while Tune operation is being performed (Heat Cool, Cool Heat)
- **8-** While Tune operation is being performed, if control form is changed as "ON/OFF" when it is "PID" (If control form is changed as "PID" when it is "ON/OFF", the Tune operation is started again)

Auto Tune is canceled. Then, without doing any changes in PID parameters and $\boxed{R + L - 1}$ Parameter, device continues to run with former PID parameters.

Auto Tune (Limit Cycle Tuning) operation;

Process control output runs according to heating if heating or heating-cooling function and PID control form is selected,

Process control output runs according to cooling if cooling function and PID control form is selected.



For Auto Tune (Limit Cycle Tuning) operation:

- 1- Tune selection parameter **Lunn** in "run List" menu must be selected **BLun Auto tune** or **BL5E Auto-Self tune**.
- **2 -** For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD, PID.
- **3** -If process set value is changed while Tune operation is being performed, Tune operation is canceled

Self Tune (Step Response Tuning):

When power is on, while process value starts to change for being equal to process set value, PID parameters are determined by the device with **Self Tune** method. For starting **Self Tune** (**Step Response Tuning**) operation firstly power the device

For starting **Self Tune (Step Response Tuning)** operation firstly power the device off and then on. Also difference between process value and set value must be too much.

Example 2: Determination of PID parameters with Self Tune method

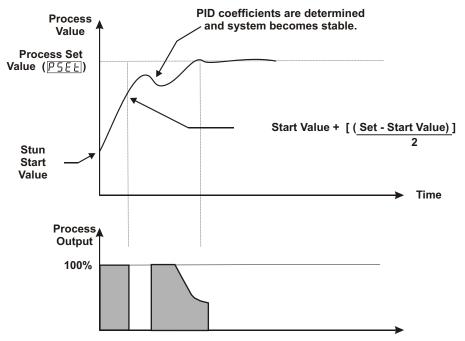
- Enter operator or technician menu
- Select tune selection parameter <u>Lunn</u> in "run List" menu <u>Stun</u> or <u>Rt. St</u> and turn to operation screen.
- Power off the device.
- Wait system to be in first conditions.

(For example : Decreasing of the temperature to ambient temperature while controlling the temperature)

- Apply power to the device
- See that "AT" led is active

If heating or heating-cooling function and PID control form is selected for the system;

If set value is greater than process value, process output becomes active till to the **Temperature+[(Set - Temperature) / 2]** value. When process value reaches to this value, process output reduces to 0% and it calculates the PID coefficients.



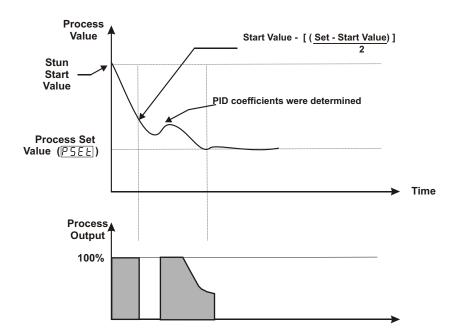
If cooling function and PID control form is selected for the system;

If set value is less than process value, process output becomes active till to the **Temperature - [(Set - Temperature) / 2]** value. When process value reaches to this value, process output is reduced to 0% and it calculates PID coefficients.



For Self Tune (Step Response Tuning) operation:

- 1 Tune selection parameter <u>Lunn</u> in "run List" menu must be selected **Self tune** [5 Lunn] Or **Auto-Self Tune** [7 L.5 L]
- 2 For **Self Tune** (Step Response Tuning) operation, firstly power off and then apply power to the device.
- 3 For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.
- 4- If process set value is changed while Tune operation is being performed, Tune



If **Self Tune** operation is interrupted at half, PID parameters and <u>Lunn</u> parameter are not changed, device continues to run with former PID parameters. When power is off and then on, device starts to complete the **Self Tune** operation.

Canceling **Self Tune** operation:

- 1- If sensor breaks;
- 2- If **Self Tune** operation can not be completed in 8 hours;
- **3-** While heating **Self Tune** operation is running, if process value becomes greater than Set value;
- **4-** While cooling **Self Tune** operation is running, if process value becomes less than Set value;
- 5- If user selects Funn parameter no or Atun
- 6- If process set value is changed while Tune operation is being performed
- **7-** While Tune operation is being performed, if operation type selection is changed as "Manual" when it is "Automatic"
- **8-** If output function is changed while Tune operation is being performed (Heat Cool, Cool Heat)
- **9-** While Tune operation is being performed, if control form is changed as "ON/OFF" when it is "PID" (If control form is changed as "PID" when it is "ON/OFF", the Tune operation is started again)

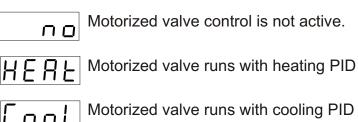
Self Tune operation is canceled. Then device continues to run with former PID parameters without changing PID parameters.



For Self Tune (Step Response Tuning) operation:

- 1 Tune selection parameter <u>Lunn</u> in "run List" menu must be selected **Self tune** [Stun] Or **Auto-Self Tune** [Rt. St]
- 2 For **Self Tune (Step Response Tuning)** operation, firstly power off and then apply power to the device.
- **3 -** For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.
- **4 -** If process set value is changed while Tune operation is being performed, Tune operation is canceled

OPERATION FORM SELECTION Device controls the process outputs by calculating the **Automatic Operation (Close-Loop Control)** %output value automatically. (If there is a PID or ON/OFF output) n - 8 n **Manual Operation (Open-Loop Control)** In PID control formed systems, user can adjust %output value with increment and decrement buttons. In ON/OFF control formed systems, user can adjust %output value "OFF", "HEAT" or "COOL" with decrement and with increment buttons. If manual operation form is selected, %output value is shown on bottom display whatever **bd5P** parameter is selected. RAMP / SOAK CONTROL Ramp / Soak function is not active. Ramp / Soak function is active HoLd Ramp / Soak function is paused. Process set value becomes constant at last value and ramp or soak time does not take into consideration. As explained in Section 8.1.4, when Soft-Start parameteri 5 E r R is active, Ramp/Soak control parameter -55L has no effect. **MOTORIZED VALVE CONTROL** It defines motorized valve control form. Module-1 output operates for opening the valve, Output-3 operates for closing the valve. If Module-1 is relay output, motorized valve control parameter [1], 5] is shown even motorized valve control is not used. If motorized valve control is used, Module-2 output can not be used as PID.



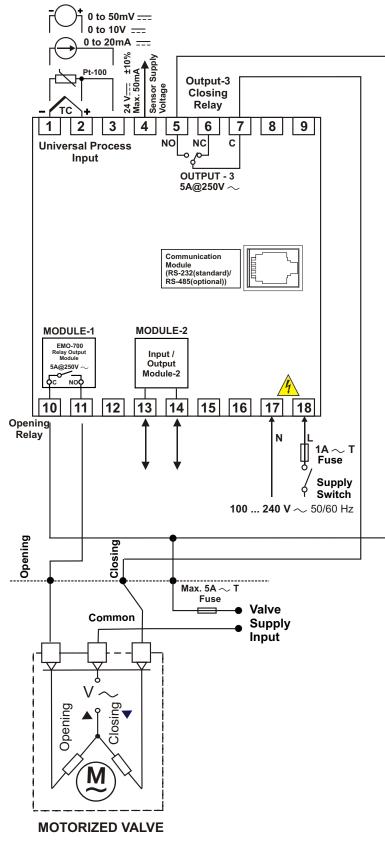


MODULE-1

EMO-700

Motorized valve control parameter must not be changed, if there is an electrical wiring.

Motorized valve control can be performed with <u>UL 51</u> parameter. For doing this operation, EMO-700 Relay output module must be plugged in Module-1 socket. Module-1 and output-3 controls the position of the valve with motorized valve control.



RELEVANT PARAMETERS:

In PASS OPEr or PASS tECH (run LiSt) menu page;

Parameter: It defines how to perform the motorized valve control with the device.

If motorized valve control is activated by selecting the ULSL parameter
HERL Or [0 0 L]

In PASS tECH GEnn COnF menu page <u>ULEE</u> and <u>ULHY</u> parameters are shown.

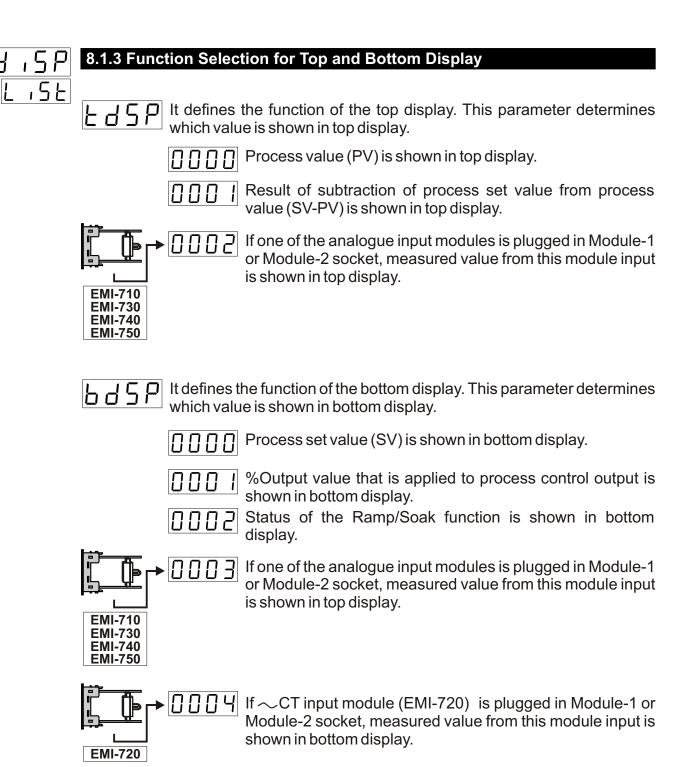
ULLE parameter: It can be adjusted from 5 to 600. The unit is "second".

It defines after how many seconds valve is completely opened. For determining the parameter correctly, close the valve manually. Be sure that valve is closed completely, then open it manually without stopping and measure that how many seconds have passed for opening it completely. Parameter must be entered measured value+5% of measured value and as second.

parameter: It can be adjusted from 0,1 to 5,0. Unit is %. It is % of Ultt parameter. Minimum movement steps of valve while opening or closing are determined as % ratio. If valve oscillates while controlling, INCREASE the parameter value!

Motorized Valve Control Electrical Wiring Diagram for ESM-7750.1.20.1.1/01.00

6915 BUMPLES	SS TRANSFER
ه ۵	Process output value in manual control is not taken into consideration while passing from manual control to automatic control. New control output that is measured in automatic control is applied to process output. Last %output value is taken output value of manual control and manual control continues while passing from automatic control to manual control.
¥E5	While passing from manual control to automatic control, last process output value in manual control is accepted as first process output value in automatic control and automatic control continues to run. Last % process output value in automatic control is accepted as process output value of manual control and manual control continues to run.
L L [] ALARM LA	ATCH CANCELING
no	Alarm latch canceling is not performed.
YE5	If there is an alarm output with latching and there is no alarm status, latching operation will be finished by the device. When it is finished, this parameter becomes no Automatically.





In 'Run List' menu Section 8.1.2, if operation form is $\mathbb{A}_{\underline{u} \, \underline{t} \, \underline{o}}$, then $\mathbb{A}_{\underline{d} \, \underline{b} \, \underline{d}}$ parameter is considered. If operation form is $\mathbb{A}_{\underline{u} \, \underline{b} \, \underline{o}}$, "output value is shown in bottom display whatever $\mathbb{A}_{\underline{d} \, \underline{b} \, \underline{d}}$ parameter is.

P 5-8	8.1.4 Conf	iguration of RAMP/SOAK Function and Step SET Values
ם כו	5L-A	Soft-Start parameter. When the power is applied to the device, process value reaches to the set value at the end of this time. It can be adjusted from 0 to 99 hours 59 minutes.
		When the power is applied to the device, if this parameter is 0, $5 + 7$ Ramp function is not active.
	rSto	Ramp / Soak Tolerance parameter. It can be adjusted from 0% to 50% of scale. In Ramp/Soak operation, if process value is out of the tolerance that is defined with this parameter, then time is stopped. To continue to count the Ramp/Soak time, process value must be between tolerances which are determined with this parameter. If parameter is 0, this function is not active.
	r 5 Ł Y	Ramp/Soak program step selection parameter. One program with 8 steps or two different programs with 4 steps can be defined.
		1.program 1-4 steps
		2.program 5-8 steps
		Steps between 1-8 is used as one program.
	PU-1	Ramp/Soak step set value. For ramp operation; process value reaches to step set values that are defined with these parameters at the end of the time that are defined in ramp time parameters. For soak operation; process value is constant in step set value that are defined in these parameters for time that are defined in soak time parameters. Ramp/Soak step set values can be adjusted from minimum value of set
	PU-8	scale 511 - L to maximum value of set scale 511 - u
	<u> </u>	Ramp time for Ramp/Soak Process value reaches to step set values at the end of the time that are defined in these parameters. It can be adjusted 0 to 99 hours 59 minutes
	F8	

Soak time for Ramp/Soak
Process value is constant in step set value for time that are defined in

these parameters.

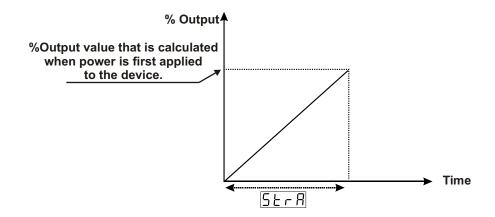
٤5-8

It can be adjusted 0 to 99 hours 59 minutes.

RAMPACTION DURING POWER ON (SOFT-START)

If $5 \not\vdash \neg R$ parameter is different from $\boxed{0.000}$ and selection of operation form parameter is $\boxed{R} \cup E \cup R$, Then Soft-Start starts to run. Ramp led blinks. By increasing the process output for $\boxed{5} \not\vdash \neg R$. Parameter , process output reaches to the %output value that is measured when power first applied to the device at the end of the $\boxed{5} \not\vdash \neg R$ time. When Soft-Start operation finishes, if operation form of the device is $\boxed{R} \cup E \cup R$, device continues to run from $\boxed{R} \cap E \cap R$ value.

Then Soft-Start operation is canceled.



RAMP/SOAK IN NORMAL OPERATION:

Whatever operation form parameter is; Normal Ramp/Soak operation is started by selecting $\[\] \]$ parameter $\[\] \[\] \]$. Ramp led becomes active. Ramp/Soak operation can be paused by selecting $\[\] \]$ Parameter $\[\] \[\] \]$. Ramp/Soak operation can be canceled by selecting $\[\] \]$ Parameter $\[\] \[\] \]$

While Ramp / Soak operation continues, if [-5 \(\frac{1}{2} \)] parameter is [1000] 1-4 numbered, if it is [1000] 5-8 numbered, if it is [1000], 1-8 numbered steps run.

If selection of operation form parameter before starting to Ramp/Soak operation is Puto then device continues to run from P5EE set value.

If any Ramp time or Soak time is $\square \square \square \square$, then relevant ramp or soak step is skipped.

Ramp/Soak operation is canceled

if there is a sensor break failure, while Ramp/Soak operation is running or if power off while Ramp/Soak operation is running.

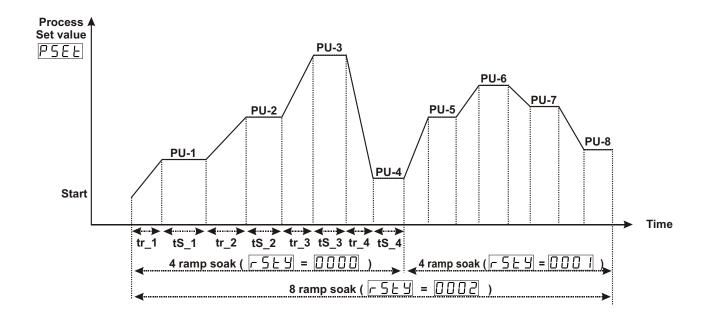


While any Ramp/Soak function is running, changing relevant time set value can cause unexpected effects in set value and process output.



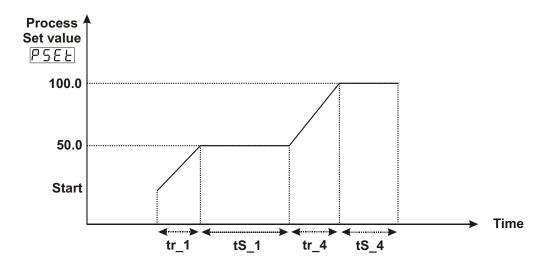
If Ramp / Soak tolerance parameter 5 to is [] [] [] , then it has no function. When it is different from 0 (While Ramp/Soak is running);

If (Calculated SET - <u>F5Ea</u>) < Process Value < (Calculated SET + <u>F5Ea</u>) condition is not true (process value is out of the tolerance), time counting is stopped till the condition is true.



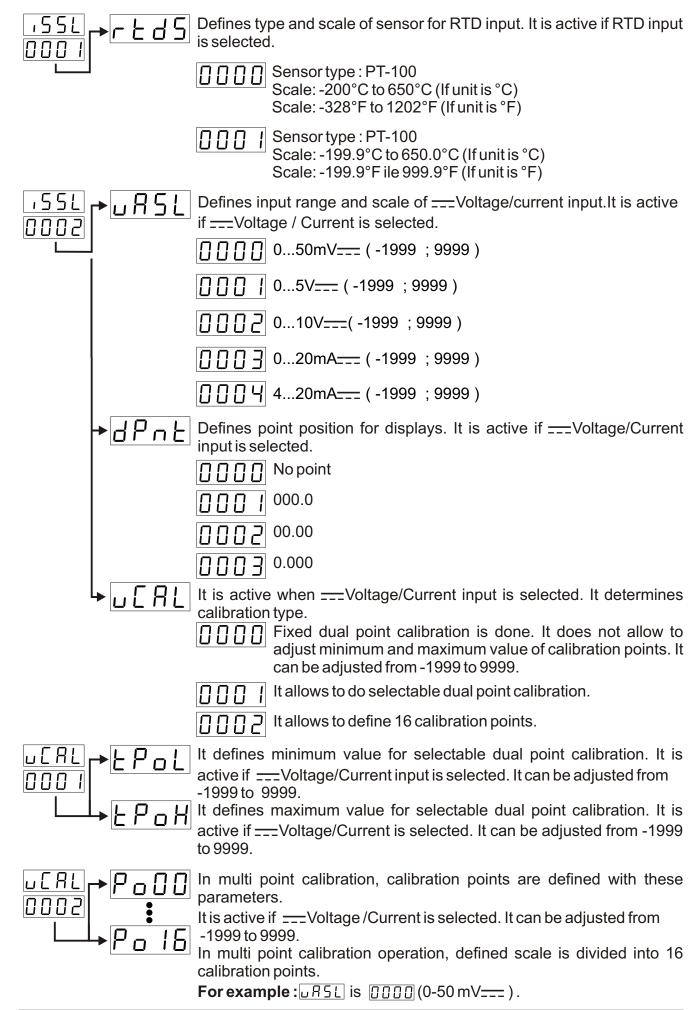
Example: If Ramp / Soak step set, ramp time and soak time parameters

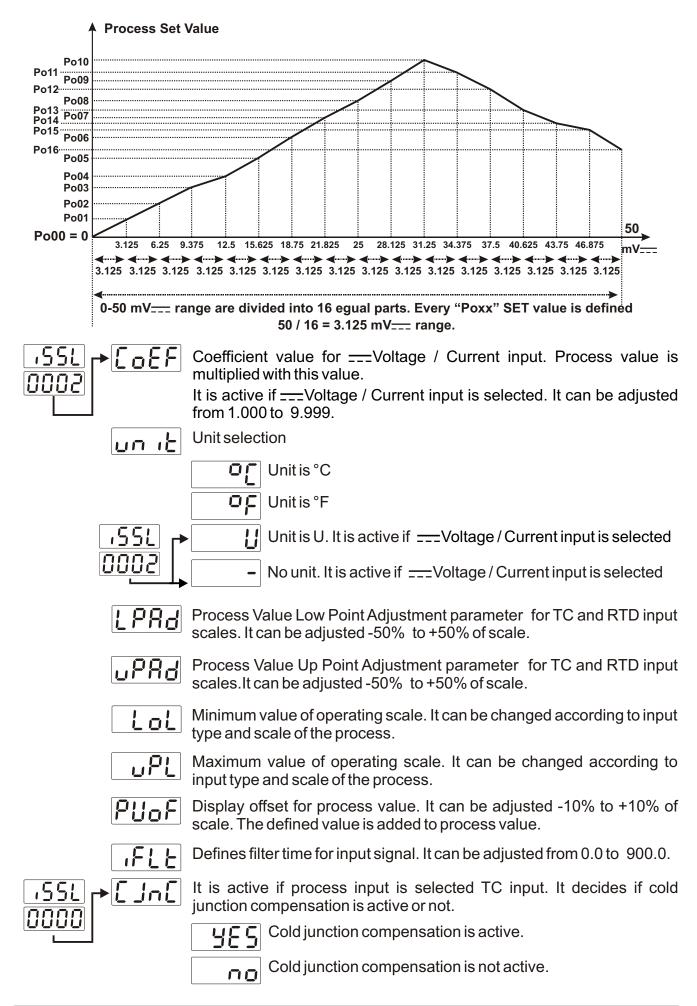
Device operates as shown below:



8.2 Technician Parameters

<u> </u>	8.2.1 Proc	ess Input Type and Relevant Parameters with Process Input
[onF		Defines the process input type
	1777	Defines the process input type.
		TC input type selection
		RTD input type selection
		☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐
.55L 0000	<u> </u>	Defines type and scale of the thermocouple for TC input. It is active if TC input type is selected.
		L (-100°C;850°C) or (-148°F;1562°F)
		[
		☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐
		☐ ☐ ☐ ☐ ☐ ☐ J (-199.9°C;900.0°C) or (-199.9°F;999.9°F)
		☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐
		[] [] [] [] K (-199.9°C;999.9°C) or (-199.9°F;999.9°F)
		R (0°C;1700°C) or (32°F;3092°F)
		R (0.0°C;999.9°C) or (32.0°F;999.9°F)
		S (0°C;1700°C) or (32°F;3092°F)
		S (0.0°C;999.9°C) or (32.0°F;999.9°F)
		T (-200°C;400°C) or (-328°F;752°F)
		T (-199.9°C;400.0°C) or (-199.9°F;752.0°F)
		☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐
		B (44.0°C;999.9°C) or (111.0°F; 999.9°F)
		[] [] Y E (-150°C;700°C) or (-238°F;1292°F)
		[] [] [] E (-150.0°C;700.0°C) or (-199.9°F;999.9°F)
		☐ ☐ ☐ N (-200°C;1300°C) or (-328°F;2372°F)
		[] [] 7 N (-199.9°C;999.9°C) or (-199.9°F;999.9°F)
		C (0°C;2300°C) or (32°F;3261°F)
		C (0.0°C;999.9°C) or (32.0°F;999.9°F)





P 18

8.2.2 PID Configuration Parameters

If any output is configured as heating PID;

P-HE, I-HE, I-HE, IE-H, IE-HE,
If any output is configured as cooling PID;

If no output is configured as PID;

Only o-db, 5500 parameters are visible in PID CONF menu.



OR

out3

Conf

OR

out2

OR Out3

HEAL

OR 1092 | 1-45

HEATING PROPORTIONAL BAND (000.0%, 999.9%)

Full Scale ($\Box PL$ - LoL) %. If $\Box PL$ = 1000 °C, LoL = 0 °C and P-HE = 50.0 then Proportional Band = ($\Box PL$ - LoL) * P-HE / 100.0

Proportional Band = (1000-0)*50.0/100.0 = 500 °C

HEATING INTEGRAL TIME (0000 sec, 3600 secs)

It can be changed by the user. When Tune operation stops, it can be changed by the device. If it is 0, integral control part does not run. When tune operation stops if this parameter is 0, this parameter can not be changed because of integral control part does not run.



HEATING DERIVATIVE TIME (000.0 sec, 999.9 secs)

It can be changed by the user. When Tune operation stops, it can be changed by the device. If it is 0, derivative control part does not run. When tune operation stops if this parameter is 0, this parameter can not be changed because of derivative control part does not run.



CONTROL PERIOD FOR HEATING OUTPUT (1 sec, 150 secs)

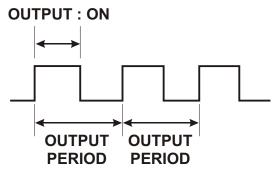
It is control period for heating. While motorized valve control runs, if ULSL is heat or cool, this parameter is not visible.





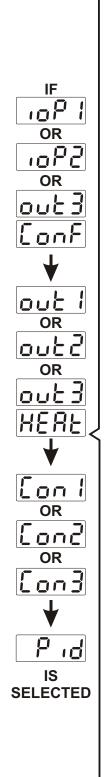


IS SELECTED



Relay Output: Output period must be short for stable process control. Relay must not be used in short output periods because of limited life of their relay contact (number of open/close events). Relay output must be used as control output in values near to 30 seconds or greater than this value.

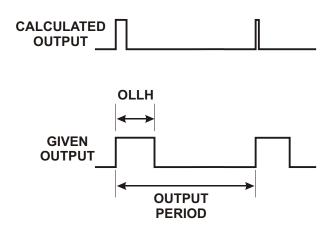
SSR Output : If short output period is needed in a system (approximately 1-2 seconds) SSR driver output module as last control element is recommended.



THEATING MINIMUM CONTROL OUTPUT (0.0%, out H)

It is % of heating minimum output. If heating and cooling PID control functions operate together, this parameter is not considered.

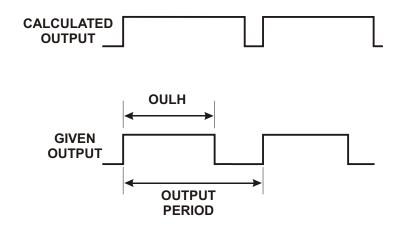
Even as a result of the heating PID calculation device calculates the % output value less than this parameter, heating output is active minimum for OLLH parameter.



HEATING MAXIMUM CONTROL OUTPUT (ロビビ州 , 100.0%)

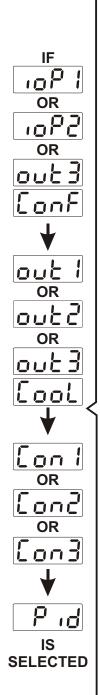
It is % of heating maximum output.

Even as a result of the heating PID calculation device calculates the % output value greater than this parameter, heating output is active maximum for OULH parameter.



日本 HEATING MINIMUM CONTROL OUTPUT TIME (0.0 sec , [と-H])

Heating output can not be active less than this parameter. Even if this parameter is 0, this parameter is accepted 50 msecs for security. While motorized valve control is running if UL5L parameter is selected heating or cooling, this parameter is not accessible.



COOLING PROPORTIONAL BAND COEFFICIENT (0.0, 100.0)

If heating and cooling PID is used in a system, tune operation is performed by heating output. Cooling proportional parameter P-LE is calculated with heating proportional band value P-HE and coefficient F-HE

P-[] = P-HE * [[oE] / 100.0

Example: If heating and cooling PID is used in a system at the end of the tune operation,

If P-HE = 10.0% and CCoE = 50.0 then

P-[] = P-H; * [[o] /100.0 = 10.0 * 50.0 / 100.0 = 5.0%

Note: It is recommended that cooling proportional band coefficient if cooling is done with air 100.0, with oil 80.0, with water 40.0 is accepted.

COOLING PROPORTIONAL BAND (000.0%, 999.9%)

Full Scale ($\Box PL$ - LoL) % If $\Box PL$ = 1000 °C, LoL = 0 °C and P-LE = 50.0 then Proportional Band = ($\Box PL$ - LoL) * P-LE / 100.0

Proportional Band = (1000-0)*50.0/100.0 = 500 °C

COOLING INTEGRAL TIME (0000 sec, 3600 secs)

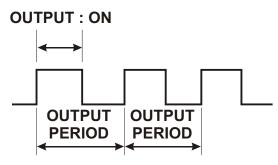
It can be changed by the user. When tune operation finishes, it can be changed by the device. If it is 0, integral control part does not perform. When tune operation finishes if this parameter is 0, it can not be changed because integral control part does not perform.

COOLING DERIVATIVE TIME (000.0 sec, 999.9 secs)

It can be changed by the user. When tune operation finishes, it can be changed by the device. If it is 0, derivative control part does not perform. When tune operation finishes if this parameter is 0, it can not be changed because derivative control part does not perform.

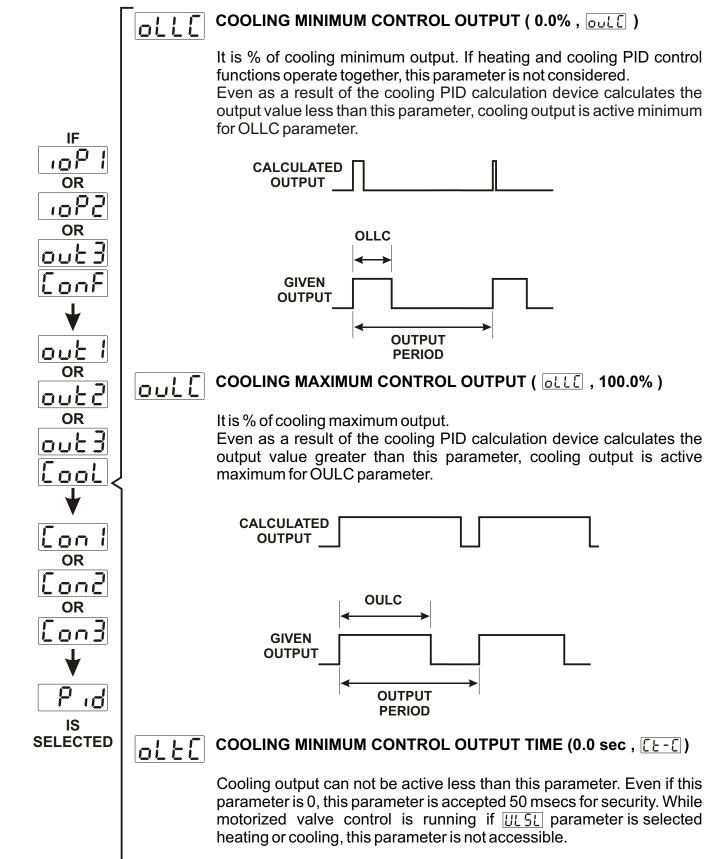
COOLING OUTPUT PERIOD TIME (1 sec, 150 secs)

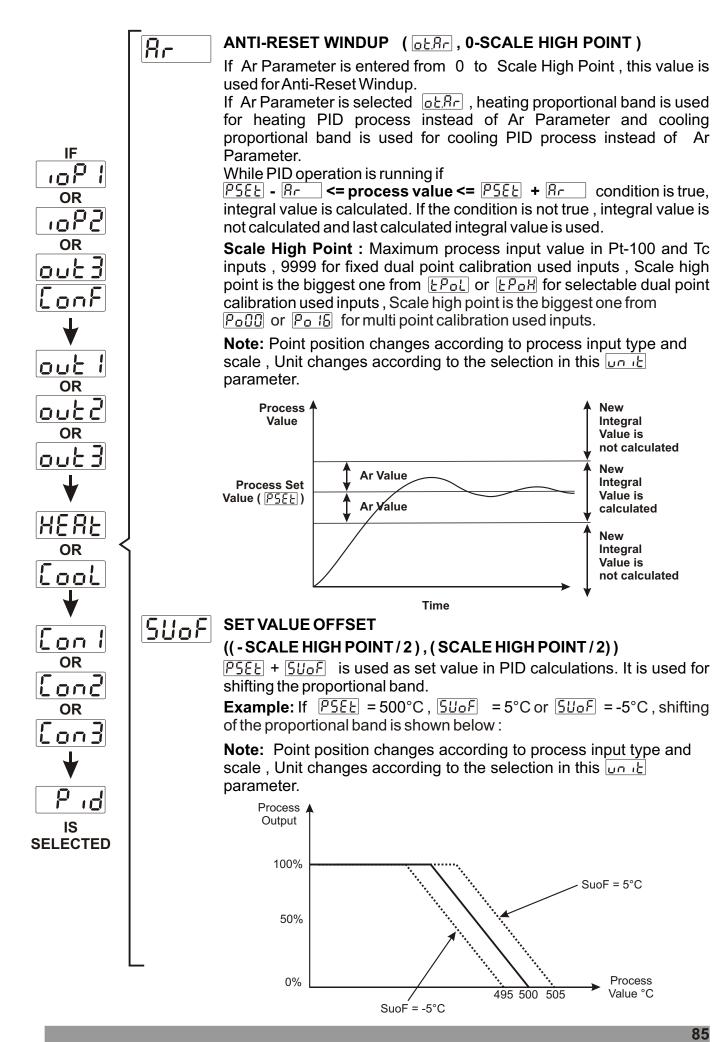
It is control period of cooling output. While motorized valve control is running, if <u>ULSL</u> is selected heating or cooling, this parameter is not visible.



Relay Output: Output period must be short for stable process control. Relay must not be used in short output periods because of limited life of their relay contact (number of open/close events). Relay output must be used as control output in values near to 30 seconds or greater than this value.

SSR Output: If short output period is needed in a system (approximately 1-2 seconds) SSR driver output module as last control element is recommended.



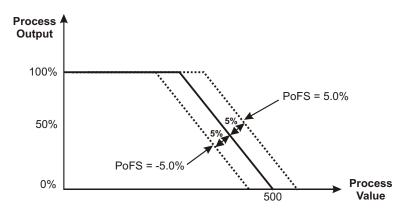




Pof5 PIDOUTPUTOFFSET

(FOR HEATING PID 0.0%, 100.0%) (FOR COOLING PID -100.0%, 0.0%) (FOR HEATING-COOLING PID -100.0%, 100.0%)

This parameter is added to "Output %" which is calculated at the end of the PID.



<u> 10</u>8 **OR** ,622 **OR** out3

IF

Po55

OUTPUT OFFSET RELATED TO PID SET

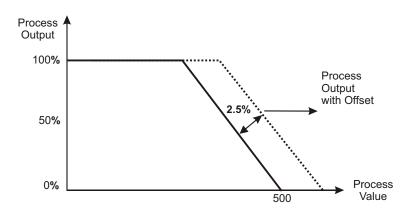
(FOR HEATING PID 0.0%, 100.0%) (FOR COOLING PID -100.0%, 0.0%) (FOR HEATING-COOLING PID -100.0%, 100.0%)

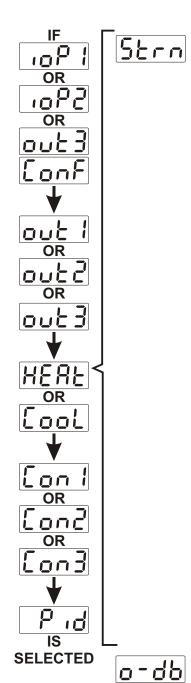
This parameter is added to the %process output that is calculated at the end of the PID according to process set value.

Poss * Pset / (upl - Lol)

Example: If $P5EL = 500^{\circ}C$, $PL = 1000^{\circ}C$, LoL = 0, Po55 = 5.0%then P_055 * P5EE / (PL - L_0L) = 5.0 * 500 /(1000-0) = 2.5% 2.5% is added to calculated process value.







PROCESS VALUE STABILIZATION (1, SCALE HIGH POINT)

It is used to control if process value oscillates or not when $\[\underline{\textbf{Funn}} \]$ Parameter is $\[\underline{\textbf{Rtun}} \]$ or $\[\underline{\textbf{Rt.5t}} \]$

lf;

P5EŁ - 5Łrn <= Process Value <= P5EŁ + 5Łrn condition is not true and process value starts to oscillate (as shown in the diagram). If Lunn parameter is RŁun or RŁ5Ł, then RŁŁn parameter is selected and thenLimit Cycle Tune operation starts for determining new PID parameters.

Scale High Point : Maximum process input value in Pt-100 and Tc inputs

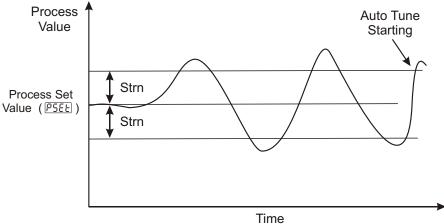
9999 for fixed dual point calibration used inputs,

Scale high point is the biggest one from Pal or Pal for selectable dual point calibration used inputs

Scale high point is the biggest one from $P_0 UU$ or $P_0 UU$ for multi point calibration used inputs

Note: Point position changes according to process input type and scale,

Unit changes according to the selection in this unit parameter.



PROPORTIONAL BAND SHIFTING ((-SCALE HIGH POINT/2), (SCALE LOW POINT/2))

If heating-cooling or only cooling function is performed;

Cooling process set value is calculated by adding set value P5EE with parameter a-db

Control form can be ON/OFF or PID.

If set value for heating = PSEE + SUoF; Then set value for cooling = PSEE + SUoF + o-db

Scale High Point : Maximum process input value in Pt-100 and Tc inputs

9999 for fixed dual point calibration used inputs,

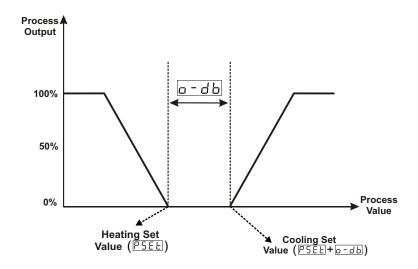
Scale high point is the biggest one from Pall or Pall for selectable dual point calibration used inputs

Scale high point is the biggest one from $P_0 \square \square$ or $P_0 \square \square$ for multi point calibration used inputs

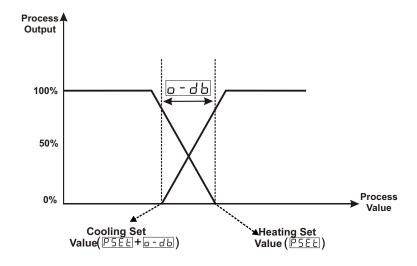
Note: Point position changes according to process input type and scale.

Unit changes according to the selection in this parameter.

If a - db > 0 (Dead Band)



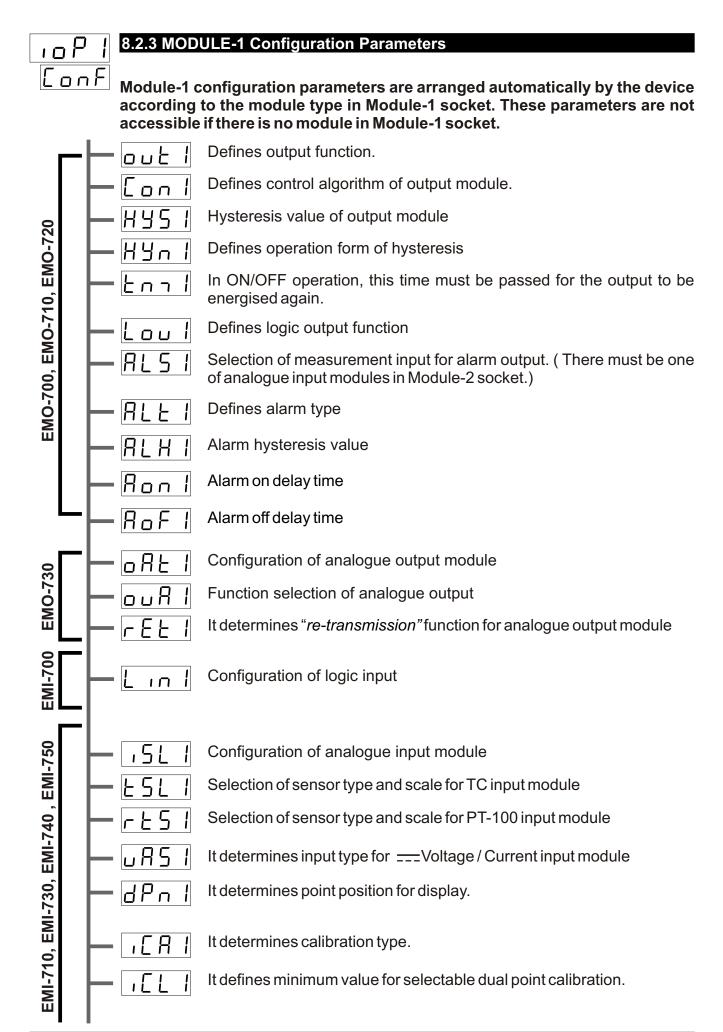
If o-db< 0 (Overlap Band)

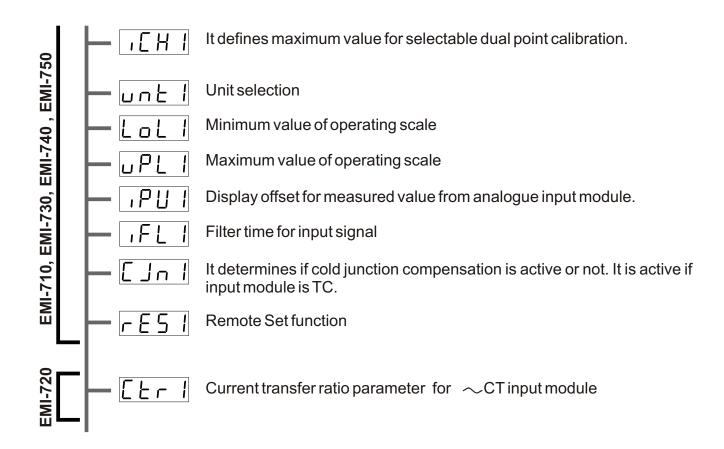


SENSOR BREAK OUTPUT VALUE (FOR HEATING PID 0.0%, 100.0%) (FOR COOLING PID -100.0%, 0.0%) (FOR HEATING-COOLING PID -100.0%, 100.0%)

When sensor breaks, controlling of the process can continue by entering %output value to 5 b o u parameter.

If this parameter 0.0, process control output does not perform an output when sensor breaks.



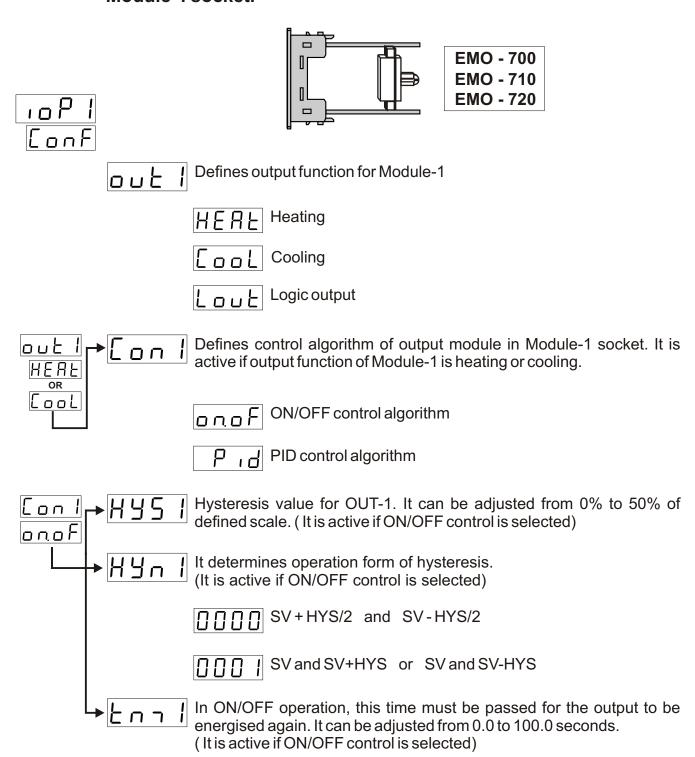


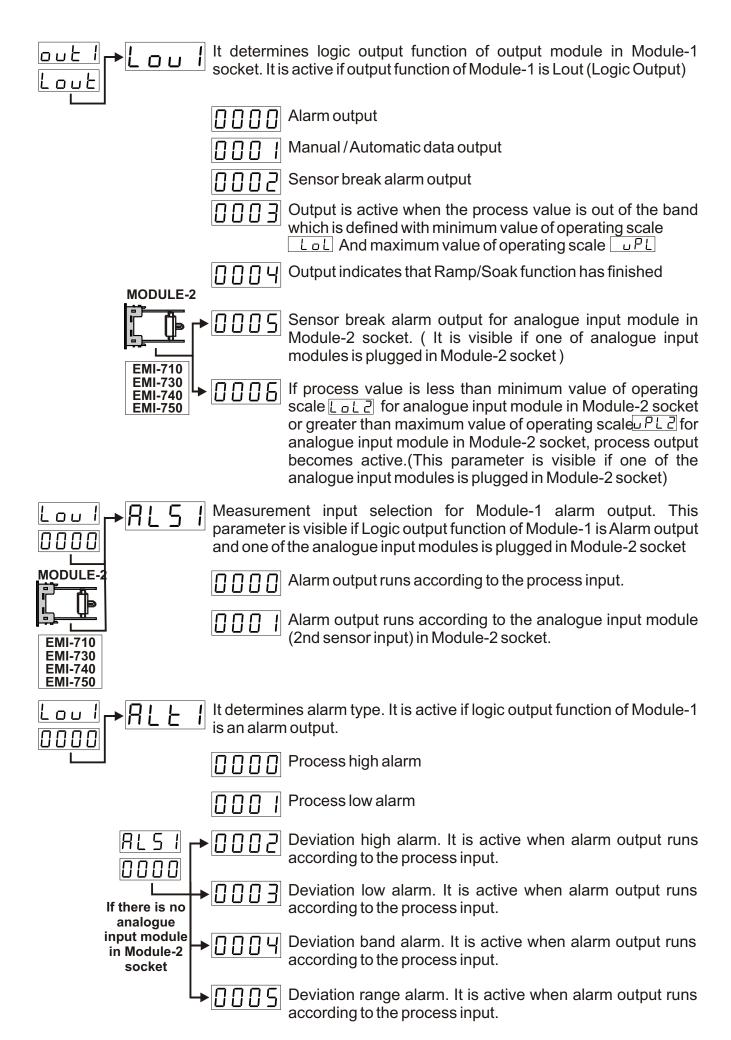
Module-1 configuration parameters are defined according to which input / output modules are plugged in Module-1 socket.

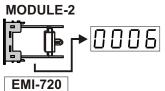




These parameters are active if EMO-700 (Relay Output), EMO-710 (SSR Driver) or EMO-720 (Digital Output) module is plugged in Module-1 socket.

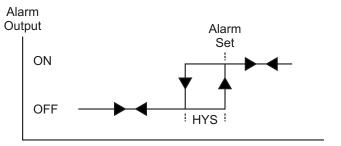






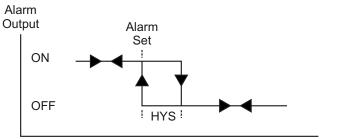
Heater failure alarm. It is active if \sim CT input module is plugged in Module-2 socket.

Process high alarm



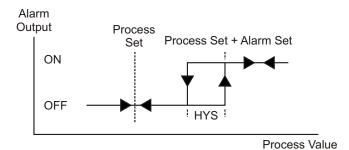
Process Value

Process low alarm

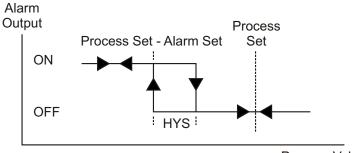


Process Value

Deviation High Alarm

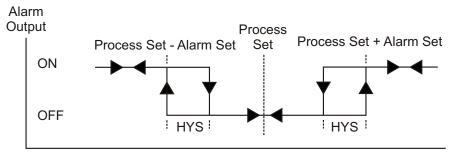


Deviation Low Alarm



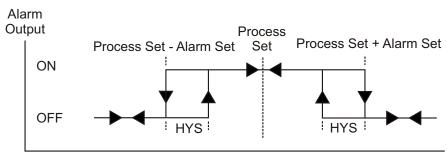
Process Value

Deviation Band Alarm



Process Value

Deviation Range Alarm



Process Value



Alarm- 1 hysteresis value. It is active if logic output function of Module-1 is selected alarm output.

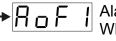
If $\square \square \square \square \square$ or there is no analogue input module (2nd sensor input) in Module-2 socket, then it can be adjusted from 0% to 50% of process input scale ($\square P \square - \square \square$)

If $\square \square \square \square \square$ and there is one of an analogue input module (2nd sensor input) in Module-2 socket, then it can be adjusted from 0% to 50% of analogue input module scale ($\square \square \square \square \square$)

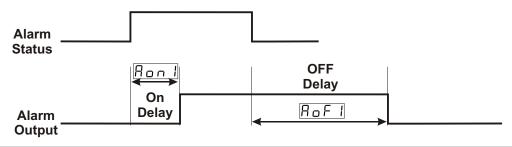
If there is \sim CT input module (EMI-720) in Module-2 socket and alarm type parameter $\boxed{\textit{RLEI}}$ is $\boxed{\textit{DDDE}}$, then it can be adjusted from 0.0 to 20.0A \sim



Alarm on delay time. It can be adjusted from 0000 to 9999 seconds. It is active if logic output function of Module-1 is alarm output.



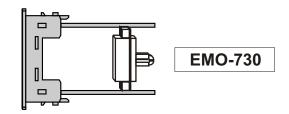
Alarm off delay time. It can be adjusted from 0000 to 9998 seconds. When the value is greater than 9998, LECH is seen on the display. It means alarm latching output is selected. It is active if logic output function of Module-1 is alarm output.



10P1Conf



These parameters are active if EMO-730 (0/4...20 mA___ Current Output) module is plugged in Module-1 socket.





Configuration of analogue output module in Module-1 socket.

0...20mA output or 0...10V=== according to Section 5.2.5 is selected.

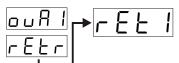
4...20mA output or 2...10V—— according to Section 5.2.5 is selected.

Function selection of analogue output module in Module-1 socket.

HERE Analogue output module in Module-1 socket is used for heating

Analogue output module in Module-1 socket is used for cooling.

Analogue output module in Module-1 socket is used for retransmission.

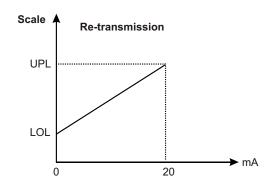


Defines "Re-transmission" function. (It is active if "re-transmission" function is selected for analogue output module in Module-1 socket.

_ _ L. P _ It retransmits Process value to analogue output.

It retransmits difference between Process and Set value to analogue output.

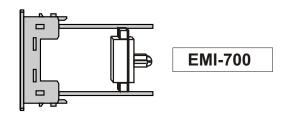
☐ 上 ☐ ☐ It retransmits Set value to analogue output.



10P1Conf



These parameters are active if EMI-700 (Digital Input) module is plugged in Module-1 socket.





Configuration of digital input in Module-1 socket.

Manual / Automatic selection input

When the logic input is triggered;

Auto Tune (Limit Cycle Tuning) Start/Stop input.

When the logic input is triggered;

It is used to start or stop the Auto Tune operation.

If input is being active while REUN operation does not perform, automatic tune selection parameter REEN is selected YES and then Auto Tune operation starts to run. If input is being active while Atun operation performs, Auto Tune operation is stopped.

Ramp&Soak, Start / Stop input.

When the logic input is triggered;

If Ramp / Soak control parameter F55L is Fun or HoLd then oFF is selected

If it is oFF then run is selected.

Ramp&Soak, Start / Hold input.

When the logic input is triggered;

If Ramp / Soak control parameter - 55L is run then Hold is selected Hold then run is selected

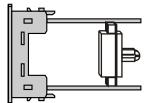
When the logic input is triggered;

If there is a latching alarm output and alarm condition is not active, latching is canceled.

rop (Conf



These parameters are active if EMI-710 (0/4...20mA___ Current Input), EMI-730 (TC or 0...50mV__ input), EMI-740 (PT-100 Input) or EMI-750 (0...10V__ Input) module is plugged in Module-1 socket.



EMI - 710 EMI - 730 EMI - 740 EMI - 750

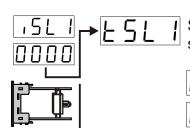


Configuration of analogue input module in Module-1 socket

TC input type selection. This must be selected if analogue input module in Module-1 socket is EMI-730.

PT-100 input type selection. This must be selected, if analogue input module in Module-1 socket is EMI-740.

Voltage / Current input type selection. This must be selected if analogue input module in Module-1 socket is EMI-710, EMI-730 or EMI-750.



EMI-730

Selection of sensor type and scale for TC input module in Module-1 socket. It is active if input type of Module-1 is selected TC.

☐ ☐ ☐ ☐ ☐ L (-100°C;850°C) or (-148°F;1562°F)

L (-100.0°C;850.0°C) or (-148.0°F;999.9°F)

☐ ☐ ☐ ☐ ☐ J (-199.9°C;900.0°C) or (-199.9°F;999.9°F)

[] [] Ц K (-200°С;1300°С) or (-328°F;2372°F)

ПППБ K (-199.9°С;999.9°С) or (-199.9°F;999.9°F)

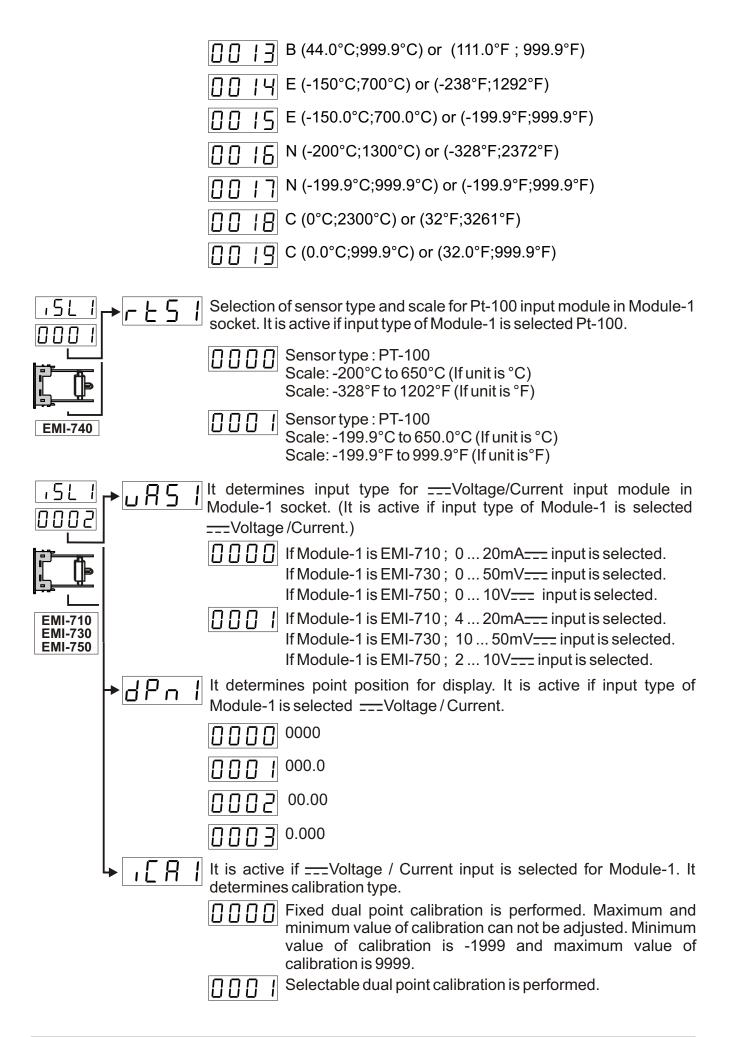
R (0°C;1700°C) or (32°F;3092°F)

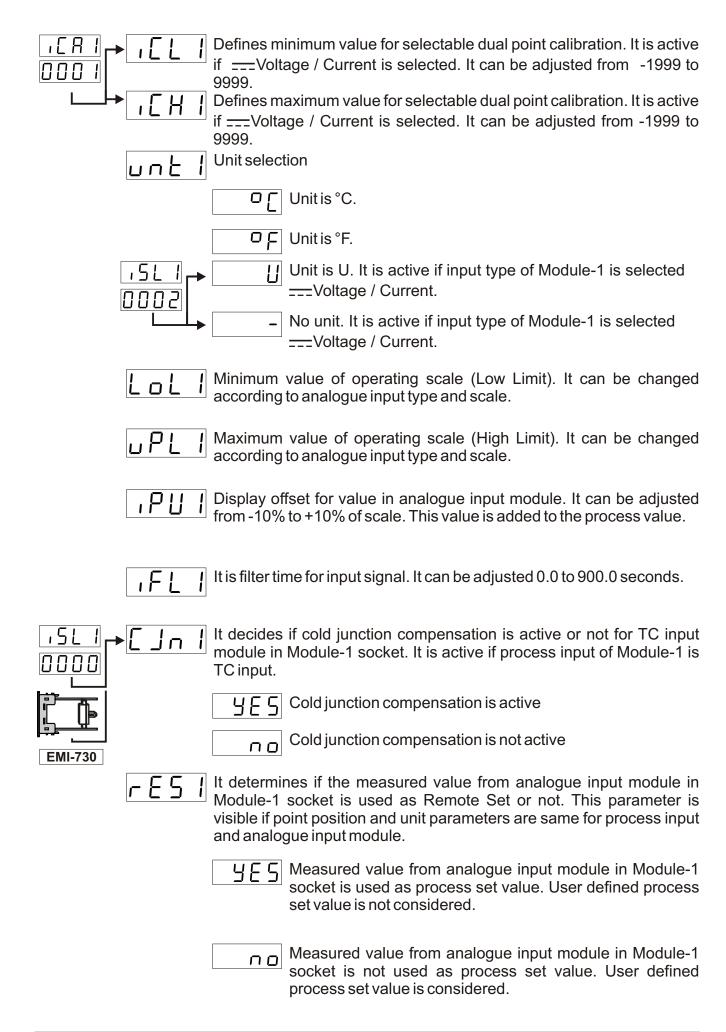
R (0.0°C;999.9°C) or (32.0°F;999.9°F)

☐ ☐ ☐ ☐ ☐ S (0°C;1700°C) or (32°F;3092°F)

S (0.0°C;999.9°C) or (32.0°F;999.9°F)

☐ ☐ ☐ ☐ B (44°C;1800°C) or (111°F;3272°F)



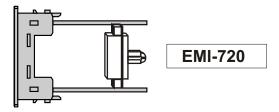


10P IConf



These parameters are active if EMI-720 (\sim CT) Input Module is plugged in Module-1 socket.





Current transfer ratio for Module-1. It can be adjusted from 0 to 100

Example: For 100:5A type current transformer;

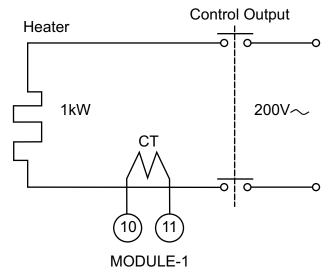
Current Transformer

Calculating set value for heating failure



Set = [(Current value without failure + Current value with heater failure)]/2

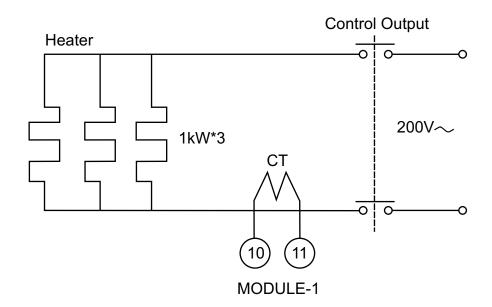
For example; If that there is a system with one heater (200V \sim and 1kW); In normal conditions current in heater = 1000/200 = 5A If there is a heater failure no current will be on the heater (0 A). Then Set value must be adjusted = (5+0)/2 = 2.5A





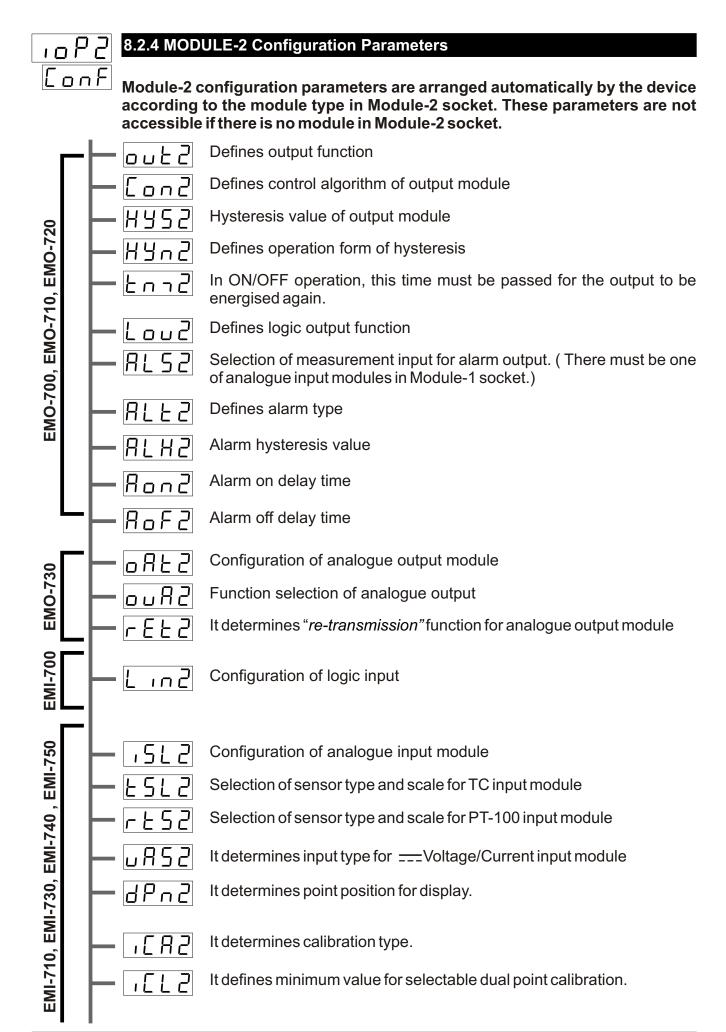
For correct measurements with EMI-720 (\sim CT) Input Module in Module-1 socket, heating output mut be active minimum for 0.2 sec (200 msec).

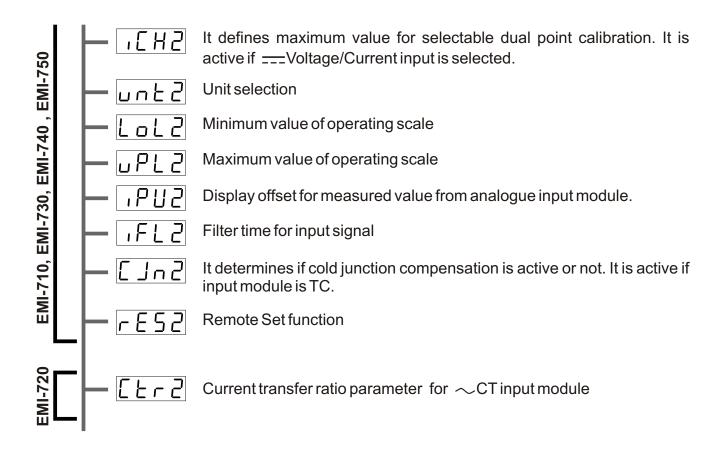
For example; If there is a system with three heater ($200V \sim \text{and 1kW}$); In normal conditions current in heater; [1000/200]*3 = 5A*3 = 15A If one of the heater is out of order, there is 5*2 = 10A current on two heaters. Current in heater failure is 10A. Then Set value must be adjusted (15+10)/2 = 12.5A



For correct measurements with EMI-720 (~CT) Input Module in Module-1 socket, heating output mut be active minimum for 0.2 sec (200 msec).

If a system operates with PID control form, heating minimum control time <u>a L E H</u> Must be minimum 0.2 second.



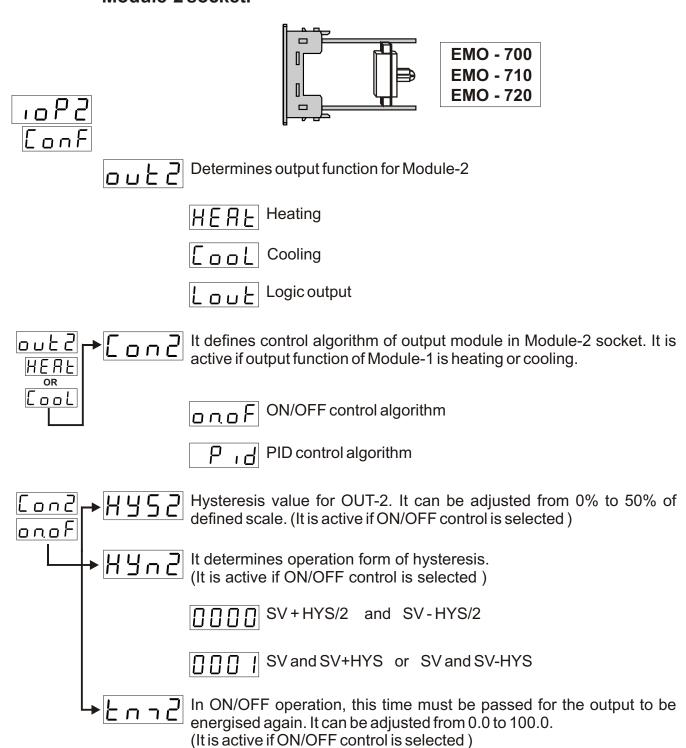


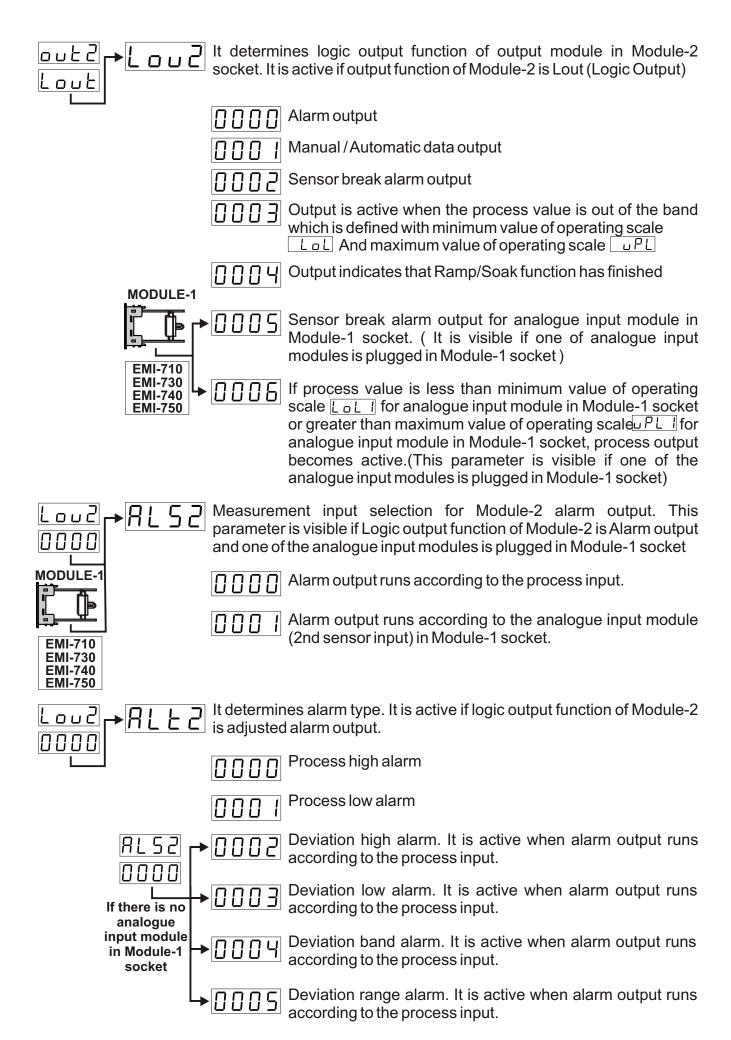
Module-2 configuration parameters are defined according to which input / output modules are plugged in Module-2 socket.

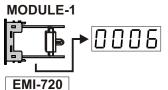




These parameters are active if EMO-700 (Relay Output), EMO-710 (SSR Driver) or EMO-720 (Digital Output) module is plugged in Module-2 socket.

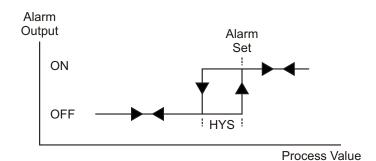




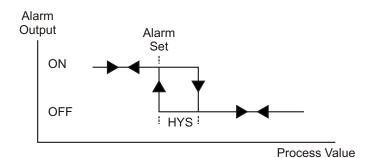


Heater failure alarm. It is active if \sim CT input module is plugged in Module-1 socket.

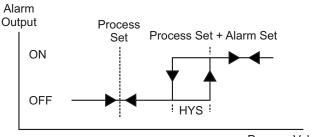
Process High Alarm



Process Low Alarm

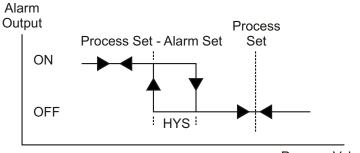


Deviation High Alarm



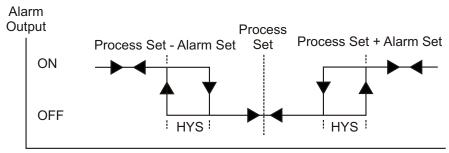
Process Value

Deviation Low Alarm



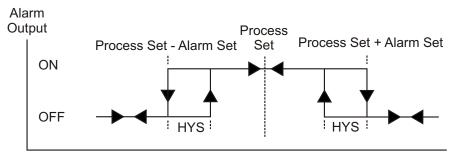
Process Value

Deviation Band Alarm

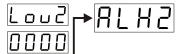


Process Value

Deviation Range Alarm



Process Value



Alarm- 2 hysteresis value. It is active if logic output function of Module-2 is alarm output.

If $\square \square \square \square$ is $\square \square \square \square$ or there is no analogue input module (2nd sensor input) in Module-1 socket, then it can be adjusted from 0% to 50% of process input scale ($\square P \square$ - $\square \square$)

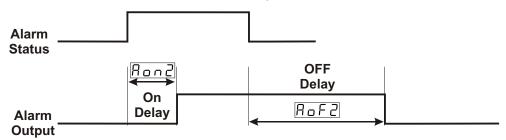
If $\square \square \square$ is $\square \square \square$ and there is one of an analogue input module (2nd sensor input) in Module-1 socket, then it can be adjusted from 0% to 50% of analogue input module scale ($\square \square \square \square$)

If there is \sim CT input module (EMI-720) in Module-1 socket and alarm type parameter $\frac{\text{PLE2}}{\text{DDDD}}$ is $\frac{\text{DDDD}}{\text{DDDD}}$, then it can be adjusted from 0.0 to 20.0A \sim

Alarm on delay time. It can be adjusted from 0000 to 9999 seconds. It is active if logic output function of Module-2 is alarm output.



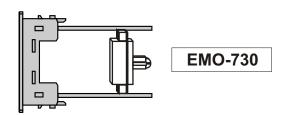
Alarm off delay time. It can be adjusted from 0000 to 9998 seconds. When the value is greater than 9998, LEIH is seen on the display. It means alarm latching output is selected. It is active if logic output function of Module-2 is alarm output.



10P2Conf



These parameters are active if EMO-730 (0/4...20mA—— Current Output) module is plugged in Module-2 socket.





Configuration of analogue output module in Module-2 socket.

0...20mA output or 0...10V according to Section 5.2.5 is selected.

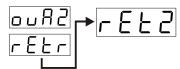
4...20mA output or 2...10V— according to Section 5.2.5 is selected.

Function selection of analogue output module in Module-2 socket.

HERE Analogue output module in Module-2 socket is used for heating

Analogue output module in Module-2 socket is used for cooling

Analogue output module in Module-2 socket is used for "retransmission"

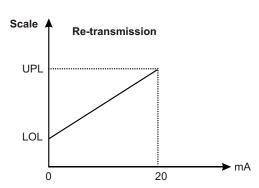


Defines "Re-transmission" function. (It is active if "re-transmission" function is selected for analogue output module in Module-2 socket)

_ ├ P ┌ It retransmits Process value to analogue output.

It retransmits difference between Process and Set value to analogue output.

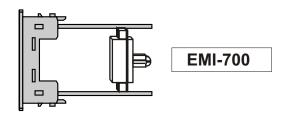
r ⊢ P ∐ It retransmits Set value to analogue output.



10P2Conf



These parameters are active if EMI-700 (Digital Input) is plugged in Module-2 socket.





Configuration of digital input in Module-2 socket.

Manual / Automatic selection input

When the logic input is triggered;

Auto Tune (Limit Cycle Tuning) Start/Stop input

When the logic input is triggered;

It is used to start or stop the Auto Tune operation.

If input is being active while $\boxed{B \not\vdash u \cap}$ operation does not perform, automatic tune selection parameter $\boxed{B \not\vdash u \cap}$ is selected $\boxed{G \not\vdash u \cap}$ and then Auto Tune operation starts to run. If input is being active while Atun operation performs, Auto Tune operation is stopped.

Ramp&Soak, Start / Stop input

When the logic input is triggered;

If Ramp / Soak control parameter <u>-55L</u> is <u>-un</u> or <u>HoLd</u> then <u>oFF</u> is selected If it is <u>oFF</u> then <u>run</u> is selected.

Ramp&Soak, Start / Hold input

When the logic input is triggered;

If Ramp / Soak control parameter <u>- 55 L</u> is <u>- un</u> then <u>Hold</u> is selected Hold then <u>- un</u> is selected

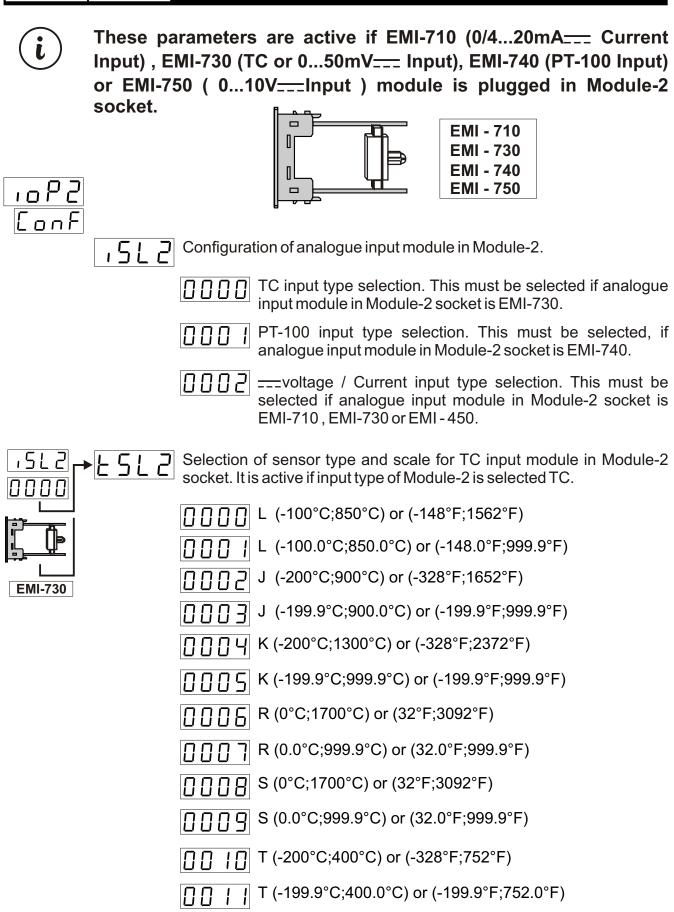
Rold then run is selecte

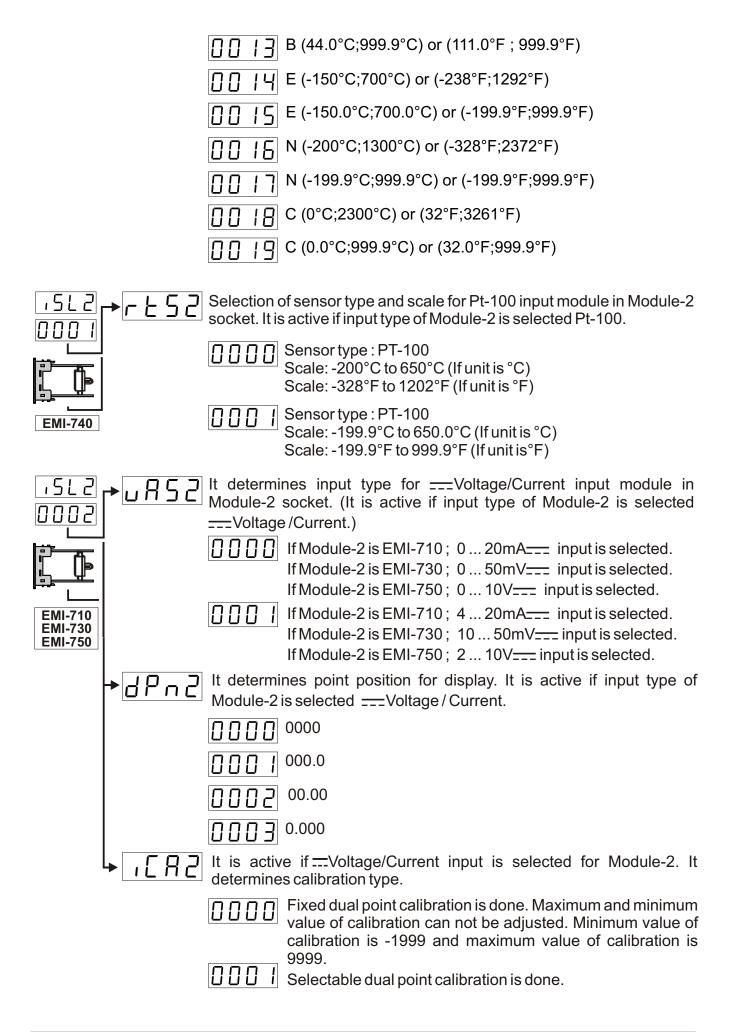
☐ ☐ ☐ ☐ ☐ Alarm Latch Canceling.

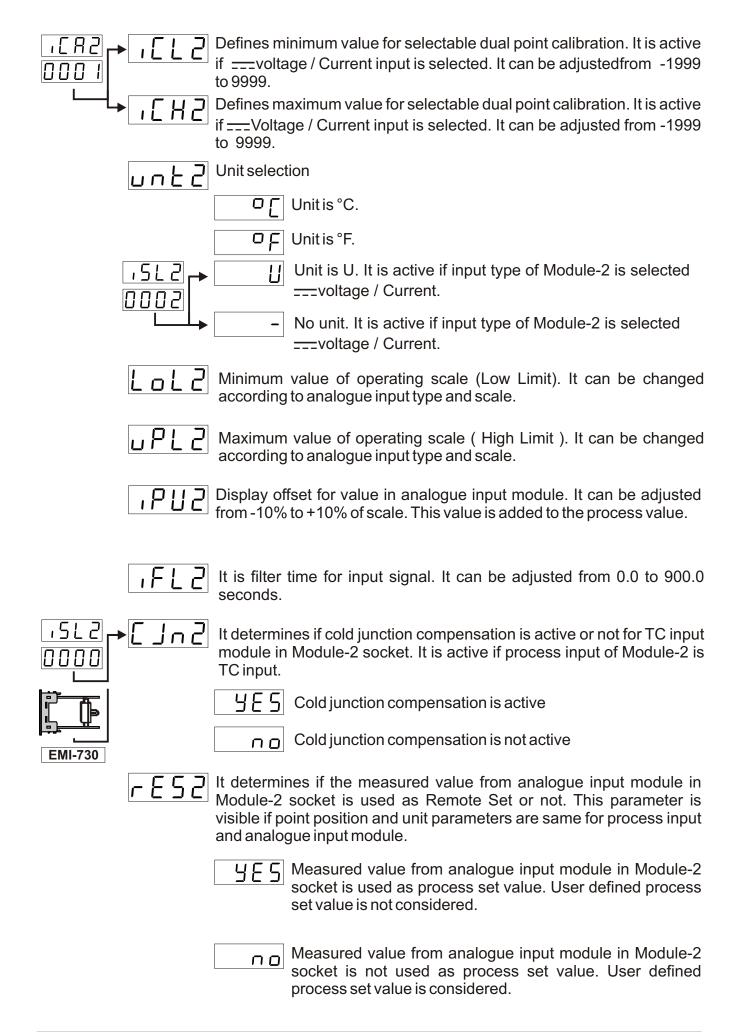
When the logic input is triggered;

If there is a latching alarm output and alarm condition is not active, latching is canceled.

10P2Conf





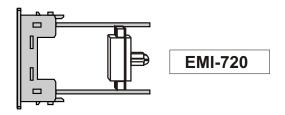


10P2Conf



These parameters are active if EMI-720 (∼CT) Input Module is





Current transfer ratio for Module-2. (It can be adjusted from 0 to 100.)

Example: For 100:5A type current transformer;

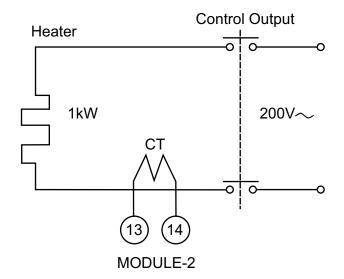
Current Transformer

Calculating set value for heating failure



Set = [(Current value without failure + Current value with heater failure)]/2

For example; if there is a system with one heater ($200V \sim and 1kW$); In normal conditions current in heater = 1000/200 = 5A If there is a heater failure no current will be on the heater (0A). Then Set value must be adjusted = (5+0)/2 = 2.5A

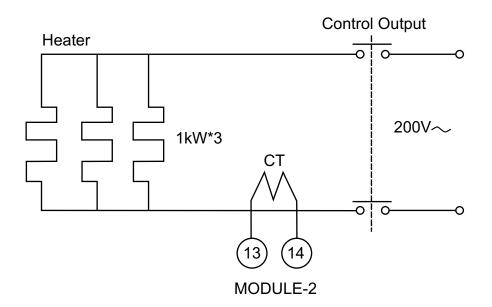




For correct measurements with EMI-720 (\sim CT) Input Module in Module-2 socket, heating output mut be active minimum for 0.2 sec (200 msec).

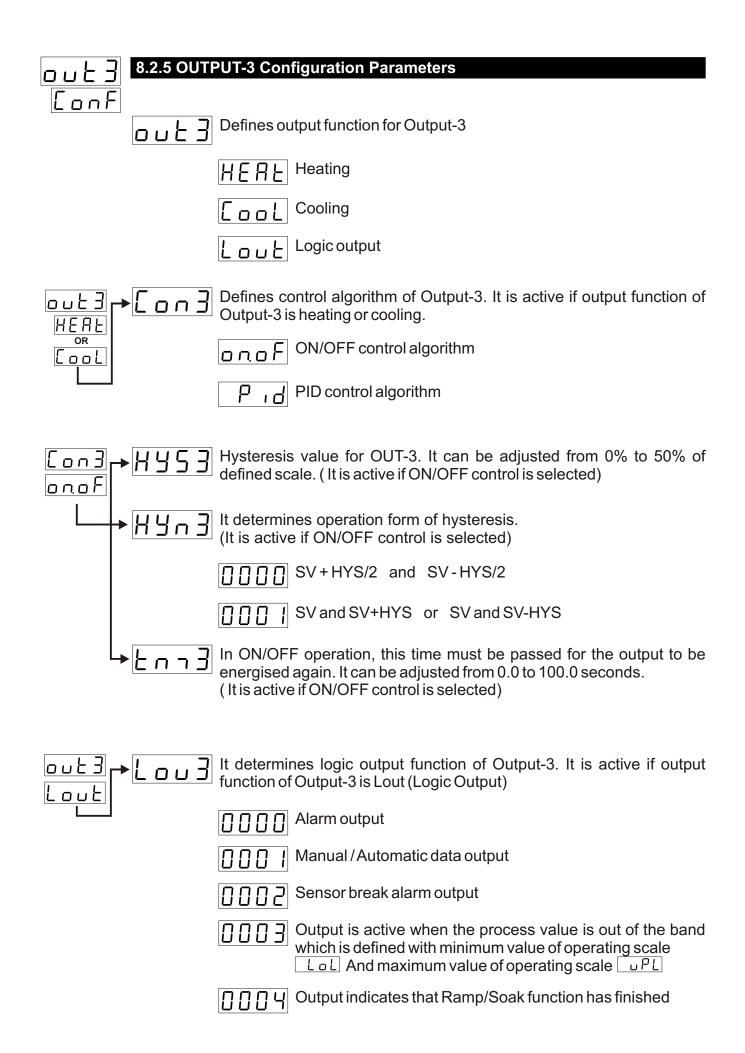
If a system operates with PID control form, heating minimum output time <u>a L E H</u> must be minimum 0.2 sec.

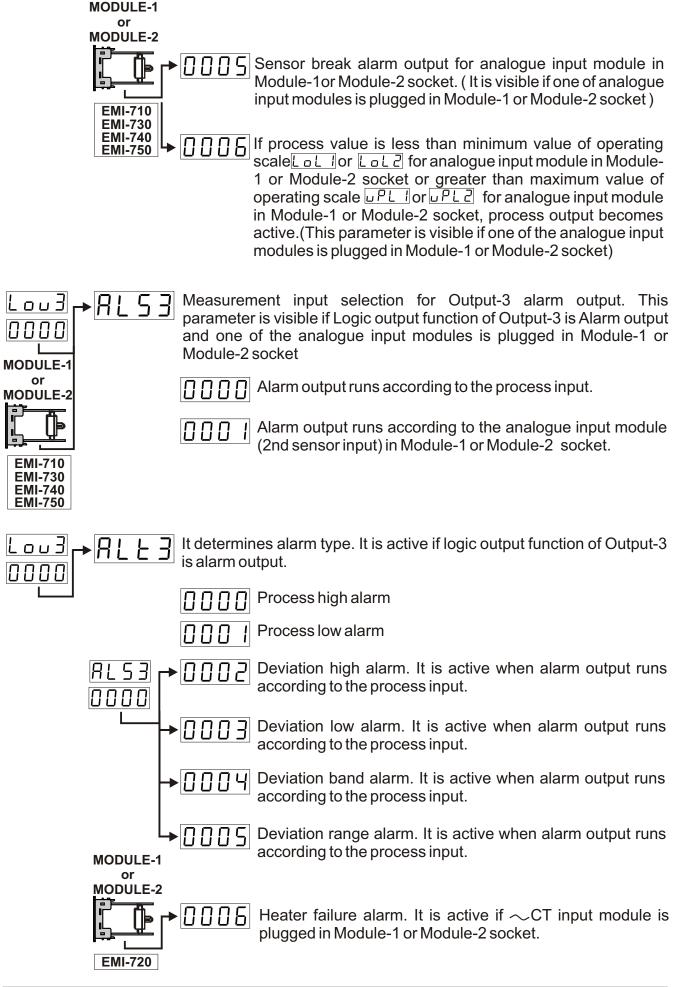
For example ;ift there is a system with three heater ($200V \sim$ and 1kW); In normal conditions current in heater; [1000/200]*3 = 5A*3 = 15A If one of the heater is out of order, there is 5*2 = 10A current on two heaters. Current in heater failure is 10A. Then Set value must be adjusted (15+10)/2 = 12.5A



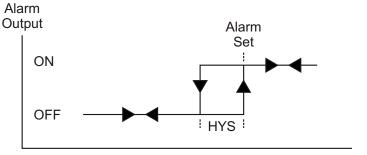


For correct measurements with EMI-720 (\sim CT) Input Module in Module-2 socket, heating output must be active minimum for 0.2 sec (200 msec).



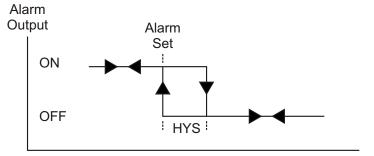


Process High Alarm



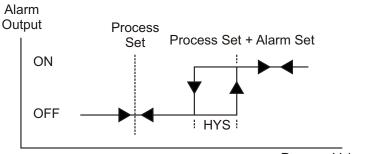
Process Value

Process Low Alarm



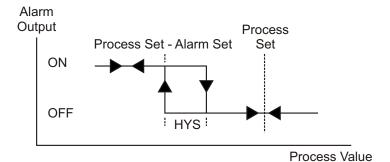
Process Value

Deviation High Alarm

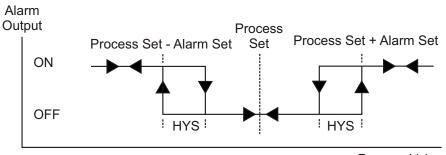


Process Value

Deviation Low Alarm

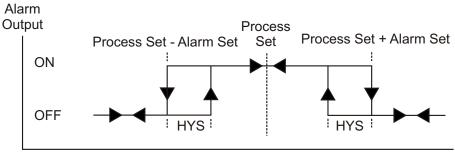


Deviation Band Alarm

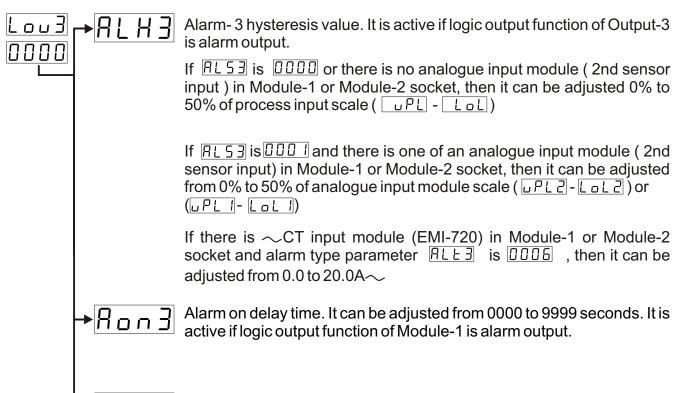


Process Value

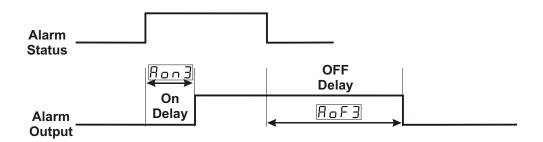
Deviation Range Alarm

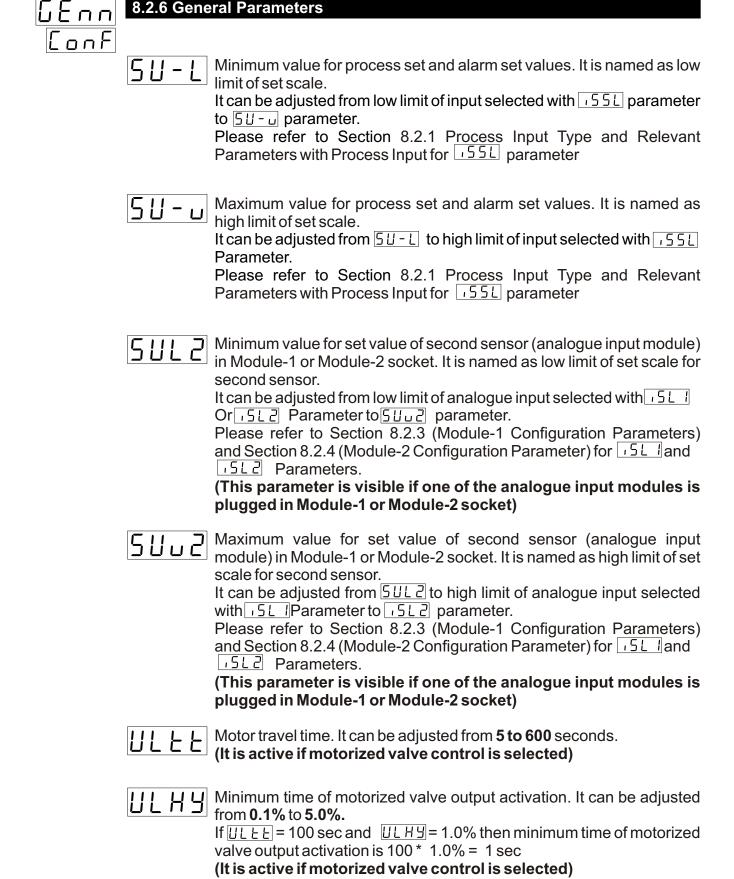


Process Value



Alarm off delay time. It can be adjusted from 0000 to 9998 seconds. When the value is greater than 9998, LEDH is seen on the display. It means alarm latching output is selected. It is active if logic output function of Output-3 is alarm output.





8.2.6 General Parameters

	8.2.7 Parar	meters for Configuration of Serial Communication		
[onF				
	SAdr	Communication Accessing Address		
		Communication accessing address of device. It can be adjusted from 1 to 247.		
	PBnq	Communication Baud Rate		
		1200 Baud Rate.		
		[
		☐ ☐ ☐ ☐ ☐ ☐ ☐ 4800 Baud Rate.		
		☐ ☐ ☐ ☐ ☐ 9600 Baud Rate.		
		☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐		
	PrEY	Parity Selection for Communication		
		No parity.		
		Odd parity.		
		Even parity.		
	SEPb	Stop Bit Selection for Communication		
		1 stop bit		
		2 stop bits		



8.2.8 Operator and Technician Passwords

П	Ø	Ø	$\overline{\Box}$
	r	r	J

It is used for accessing to the operator parameters. It can be adjusted from 0 to 9999.

> If it is \(\begin{aligned} \Omega \O parameters.

If it is different from "0" and user wants to access to the operator parameters:

1- If user does not enter PPS password correctly: It turns to operation screen without accessing to parameters.

2- When $\square PPS$ in top display and $\square \square \square \square$ in bottom display are seen, if user presses SET button without entering **OPPS** password (For observing the parameters):

Operator can see operator menus and parameters but operator can not change the parameters

(Please refer to Section 9. Failure Messages in ESM-7750 Process Controllers)



L [P 5] It is used for accessing to the technician parameters. It can be adjusted from 0 to 9999.

> If it is [[] [] ; no password protection while entering to the technician parameters.

If it is different from "0" and user wants to access to the technician parameters;

1- If user does not enter \(\begin{aligned} It turns to operation screen without accessing to parameters.

2- When <u>EEP5</u> in top display and <u>ODOO</u> in bottom display are seen, if user presses SET button without entering [[] password (For observing the parameters):

Technician can see all menus and parameters except Operator and Technician Password menu ("Pass Conf") but technician can not change the parameters

(Please refer to Section 9. Failure Messages in ESM-7750 Process Controllers)

9. Failure Messages in ESM-4450 Process Controllers



1 - Sensor failure in analogue inputs. Sensor connection is wrong or there is no sensor connection.





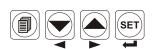
2 - If <u>Ld5P</u> parameter in "Disp List" menu is <u>DDD2</u> and analogue input module is plugged in Module-1 or Module-2 socket, this is sensor failure of analogue input module. Sensor connection is wrong or there is no sensor connection.



Please refer to Section 8.1.3 for detailed information about this parameter.



3 - If <u>Lusp</u> parameter is <u>DDDD</u> and <u>busp</u> parameter is <u>DDDD</u> and analogue input module is plugged in Module-1 or Module-2 socket, this is sensor failure of analogue input module. Sensor connection is wrong or there is no sensor connection.



Please refer to Section 8.1.3 for detailed information about this parameter.



4 - If top display blinks : If analogue input value is less than minimum value of operating scale LaL top display starts to blink.



If analogue input value is less than minimum value of operating scale LoL top display starts to blink.

Please refer to Section 8.2.1 for detailed information about this parameter.





5 - If top display blinks : If analogue input value is greater than maximum value of operating scale \(\tilde{\pu} \psi_{\textsq} \), top display starts to blink.

In "PinP Conf" Menu;

$$.55L = 0000$$
; $.55L = 0003$; $... = 0003$; $... = 0003$; $... = 0003$; $... = 0003$; $... = 0000$;

If analogue input value is greater than maximum value of operating scale \(\bu PL \), top display starts to blink.



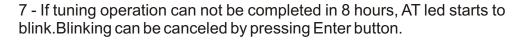
Please refer to Section 8.2.1 for detailed information about this parameter.





6 - If operator or technician password is different from "0" and user accesses to the parameter by Set button without entering the operator or technician password and wants to change a parameter, the warning message is shown on the bottom display as shown on the left. Device does not allow to do any changes without entering the password correctly.







Please refer to Section 8.1.2 for detailed information about this parameter.



8 - If user does not do anything for 120 seconds while device is on operator or technician menus, device turns to operation screen.







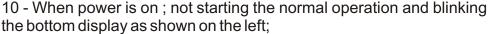




- 9 When Ramp / Soak operation finishes;
- If <u>bd5P</u> parameter is <u>0002</u>, screen on the left is shown (Please refer to Section 8.1.3 for bdsp parameter)



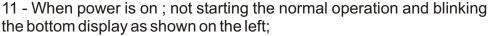




It appears when two analogue input modules (EMI-410, EMI-430, EMI-440, EMI-450) are plugged in Module-1 and Module-2 socket at the same time.

For starting normal operation power off and pull out one of the analogue input modules.





It appears when two EMI-420 ~CT input modules are plugged in Module-1 and Module-2 socket

For starting normal operation power off and pull out one of the EMI-420 CT input modules.



10. Specifications

Device Type : Process Controller

Housing&Mounting: 72mm x 72mm x 87.5mm DIN Size 43700 plastic housing

For panel mounting. Panel cut-out is 69x69mm.

Type-1 Enclosure Mounting.

Protection Class : NEMA 4X (IP65 at front, IP20 at rear).

Weight : Approximately 0.25 Kg.

Environmental Ratings : Standard, indoor at an altitude of less than 2000 meters

with none condensing humidity. : -40 °C to +85 °C / 0 °C to +50 °C

: 90 % max. (None condensing)

Storage/Operating Temperature

Storage/Operating Humidity

Installation : Fixed installation

Overvoltage Category : II

Pollution Degree : II, office or workplace, none conductive pollution

Operating Conditions : Continuous

Supply Voltage and Power : 100 - 240 V (-15% / +10%) 50/60 Hz 6VA

24 V~(-15% / +10%) 50/60 Hz 6VA

24 V===(-15% / +10%) 6W 12 V===(-15% / +10%) 6W

: PT 100 (IEC751) (ITS90)

Process Inputs : Universal input TC, RTD, ___Voltage/Current

Thermocouple Input Types : Selectable by parameters

L (DIN43710),

J ,K ,R ,S ,T ,B ,E ,N (IEC584.1)(ITS90) , C (ITS90)

Thermoresistance Input Types

Selectable by parameters 0...50mV===, 0...5V===,

0...10V---

——Current Input Types

Accuracy

: Selectable by parameters 0...20mA___, 4...20mA___

: ± 0,25% of full scale for thermocouple, thermoresistance

and voltage,

 $\pm\,0,\!70\%$ of full scale for current

Cold Junction Compensation : Automatically \pm 0.1°C/1°C.

Line Compensation : Maximum 10

Sensor Break Protection : Upscale

Sampling Cycle : 3 samples per second **Input Filter** : 0.0 to 900.0 seconds

Control Forms : Programmable ON / OFF, P, PI, PD or PID.

Standard Relay Output : 5A@250V ∼ (Programmable control or alarm output)

(Electrical Life: 100.000 Operation (Full Load))

Optional Output Modules :-EMO-700 Relay Output Module (5A@250V∼)

-EMO-710 SSR Driver Output Module

(Max. 26mA, 22V____)

-EMO-720 Digital (Transistor) Output Module

(Max 40mA@18V===)

-EMO-730 0/4...20mA=== Current Output Module

Optional Input Modules :-EMI-700 Digital Input Module

-EMI-710 0/4...20mA=== Current Input Module

-EMI-720 0...5A \sim CT Input Module -EMI-730 TC or 0...50mV Input Module

-EMI-740 PT-100 Input Module -EMI-750 0...10V== Input Module

Standard Communication Module Optional Communication Module

: EMC-700 RS-232 Communication Module : EMC-710 RS-485 Communication Module

Communication Protocol

: MODBUS-RTU

Process Display :14 mm Red 4 digit LED display

Set Display : 9 mm Green 4 digit LED display
Led Indicators : AT (Auto Tune), SV (Set value), I

: AT (Auto Tune), SV (Set value), Man (Manual Mode), Auto (Automatic Mode), O1 / 2 / 3 (Outputs) Leds,

°C / °F / V unit, Ramp, Remote Leds

11. Other Informations

Manufacturer Information:

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Thank you very much for your preference to use Emko Elektronik Products.