SANMOTION

MOTION CONTROLLER

C

With EtherCAT interface





Ver.2

SANMOTION MOTION CONTROLLER











SANMOTION C S100

Equipped with the industry-trusted high-speed fieldbus EtherCAT interface, these models are available in two configurations: a high-performance type (Model no. SMC100-A) for controlling robots and a standard type (Model no. SMC100-B) that specializes in PTP (Point-to-Point) positioning.

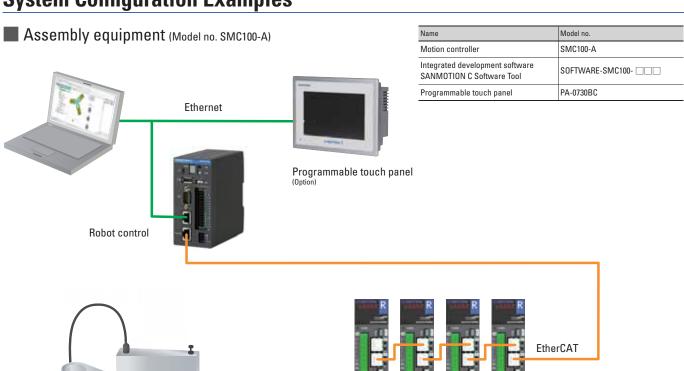
They are ideal for applications such as assembly equipment and conveying machines.

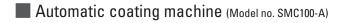
Refer to the following catalogs for AC servo systems and closed-loop stepping systems (Model No.PB) equipped with EtherCAT interface. Catalogs are available for download from our Catalog Site.

- · SANMOTION R 100/200 V General Catalog
- · SANMOTION Model No.PB Catalog
- · SANMOTION R ADVANCED MODEL 48 VDC Catalog

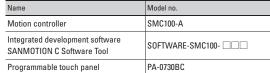


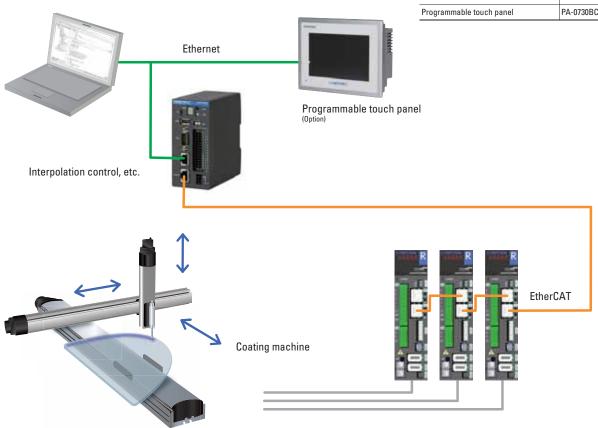
System Configuration Examples





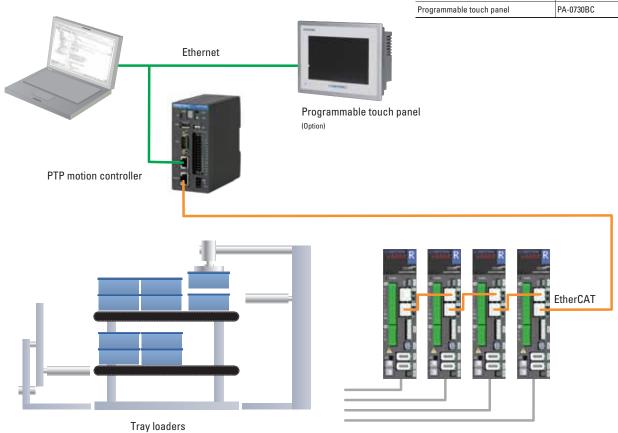
SCARA robot





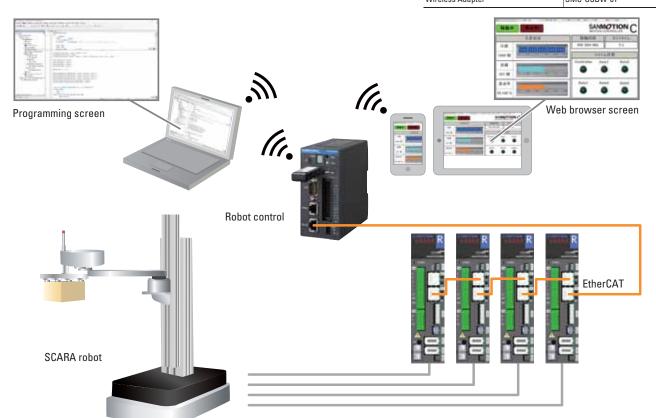
Tray loader (Model no. SMC100-B)

Name	Model no.
Motion controller	SMC100-B
Integrated development software SANMOTION C Software Tool	SOFTWARE-SMC100-
Programmable touch panel	PA-0730BC



SCARA robot moving with automated guided vehicle (Model no. SMC100-A)

Name	Model no.
Motion controller	SMC100-A
Integrated development software SANMOTION C Software Tool	SOFTWARE-SMC100-
Wireless Adanter	SMC-USBW-01



Integrated development software SANMOTION C Software Tool

Software features various functions for system development.

- Programming tool
- Electronic cam editor
- Configuration tool
- Simple HMI (human machine interface) tool
- Analysis and diagnostic tool



Easily configurable Programmable Touch Panel

- The touch panel simulation function enables users to check touch panel operation on a PC.
- The touch panel screen interface can be easily configured just by selecting from a set of on-screen elements.
- The high-resolution screen is highly visible and easy to use.



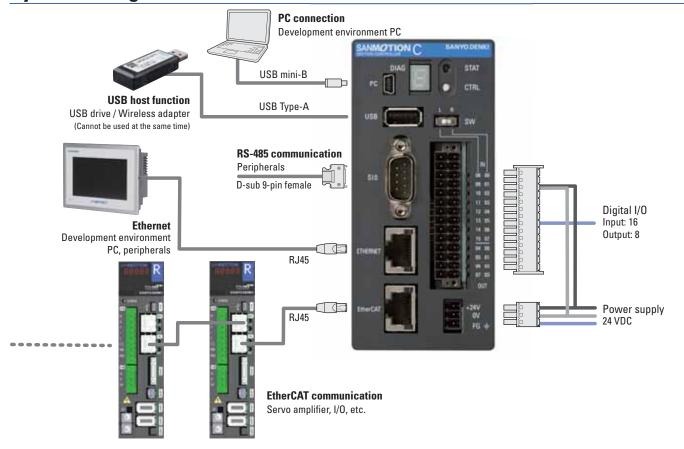
Wireless Adapter adds wireless communication to motion controllers

- Status monitoring and settings of SANMOTION products can be done remotely from smart devices.
- Motion controllers can be connected to a wireless LAN network by simply connecting the adapter to their USB port.
- The adapter can be set for use in various countries.
- Send a license key we provide to motion controllers to turn on wireless capability.

Note: The serial number of the controller is required for issuing the license key.



System Configuration



Specifications

Model no.		SMC100-A	SMC100-B	
Interface		EtherCAT (100 Mbps) master function, FoE-compatible		
		Ethernet (10/100/1000 Mbps) protocols (Modbus TCP, OPC-UA)		
		RS-485 (9600 to 115200 bps)		
		USB 2.0 (for memory storage)		
		Digital input: 16 points; rated input voltage: 24 VDC; positive/negative comm	non input	
Digital I/O		Digital output: 8 points; load voltage range: 19.2 to 30 VDC; maximum load current: 0.5 A/point; sink output		
	main power supply	Rated voltage: 24 VDC; load voltage range: 19.2 to 30 VDC; Rated current: 0		
Input power supply	I/O power supply	Rated voltage: 24 VDC; load voltage range: 19.2 to 30 VDC; Rated current: 2	0 mA	
Power consumption		19.2 W		
Cooling method		Passive		
Dimensions		55(W) × 120(H) × 110(D) mm		
Mass		300 g		
Max. no. of controlla	ble axes	8		
		Sequence control	Sequence control	
		Motion control	Motion control (PTP control)	
Control functions		(Electronic cam, electronic gear, linear interpolation, circular interpolation)		
		Robot control		
		(Cartesian coordinate, SCARA, and parallel link robots)		
Network functions		Web visualization		
Control longuage		Programming languages conforming to international standard (IEC 61131-3)		
Control language		G-code (SMC100-A only)		
Ambient temperature	е	0 to 55°C		
Storage temperature	1	-40 to 70°C		
Operation/storage hu	umidity	10 to 95% (non-condensing)		
Vibration resistance		Constant amplitude: 3.5 mm (5 to 8.4 Hz) conforming to JIS B 3502:2011		
Vibration resistance		Constant acceleration: 10 m/s ² (8.4 to 150 Hz) conforming to JIS B 3502:2011		
Shock resistance		Peak acceleration: 147 m/s ² , duration 11 ms conforming to JIS B 3502:2011		
Operation altitude		2,000 m max.		
Installation location		In control panel		
Overvoltage categor	у	II or lower		
Degree of pollution		2 or lower		

Motion control function

Number of controllable axes	8	
Communication cycle	2 to 16 ms	
Control system	Position control, speed control, torque control	
Acceleration/deceleration profile	Trapezoidal, Sin², trapezoidal with jerk limit	
Unit for positioning control	Arbitrary (pulse, mm, inch, degree)	
Programming language	Complies with IEC 61131-3 IL, ST, LD, FBD, SFC, CFC	
Function block	Homing, incremental mode, absolute mode, constant speed mode, electronic cam, electronic gear	

Robot control function (Model no. SMC100-A only)

Number of controllable axes	Robot: 4 axes max	Robot: 4 axes max	
Communication cycle	8 to 16 ms	8 to 16 ms	
Control system	PTP motion, 3D linear interpolation, 3D circular interpolation	PTP motion, 3D linear interpolation, 3D circular interpolation	
Teaching method	Numeric input	Numeric input	
Unit for positioning control	Arbitrary (pulse, mm, inch, degree)	Arbitrary (pulse, mm, inch, degree)	
Programming language	Motion function block		
Supported robots	Cartesian coordinate (3 axes), SCARA (4 axes), parallel link (4 axes)		

EtherNet/IP specifications

Interface		Ethernet (10/100 Mbps) Note: Can be combined with Modbus TCP, etc.	
		Scanner function: Network master	
	Communication	Adapter function: Network slave	
Con		Note: Cannot be used at the same time.	
Common	Node distance	100 m or less	
	Topology	Star	
	Communication cable	Shielded twisted pair cable, category 5/5e or higher recommended	
	Conformance testing	ODVA conformance (Conformance test 16 passed)	
Scanner	Maximum number of connectable units	4	
nner Mi	Minimum communication cycle	50 ms	
Device type 12		12	
	Manipulate Laureh	Output: 508 bytes, input: 504 bytes	
	Maximum data length	(Recommended output: 128 bytes, input: 128 bytes)	
Ad	Minimum communication cycle	50 ms	
Adapter		BYTE (1 byte)	
er		WORD (2 bytes)	
	Supported data types	DWORD (4 bytes)	
		REAL (4 bytes)	
		Big (A collection of BYTE type data with the maximum data length)	

Software

■ Connector set

Model no.	Application	Manufacturer part no.
AL-01005600-01	Power connector	Phoenix Contact K.K. FMC 1,5/3-ST-3,5
AL-01005600-02	I/O connector	Phoenix Contact K.K. DFMC 1,5/14-ST-3,5-LR

■ USB cable

Model no.	Application
AL-00896515-01	USB cable (1 m)
AL-00896515-02	USB cable (2 m)

■ Integrated development software SANMOTION C Software Tool

Model no.	Application	
SOFTWARE-SMC100-	Integrated development software for sequence/motion/robot control	

Peripherals

■ Programmable touch panel

Model no.		PA-0730BC	
Dimensions		212(W) × 156(H) × 57(D) mm	
Mass		Approx. 1200 g	
Rated power supply		24 VDC / 1.1 A	
Screen size		7 inch	
Resolution		800(W) × 480(H) pixel	
Display type		Wide TFT touch screen	
Color		65536	
Protection grade		Front panel: IP65; rear panel: IP20	
Backlight		LED	
USB		1	
COM1		RS-232C only	
COM2		Selectable RS-232C/RS-422/RS-485	
LAN		1 (10/100 Mbps)	
Operating environment	Ambient temperature	0 to 50°C	
operating environment	Ambient humidity	20 to 80% (non-condensing)	

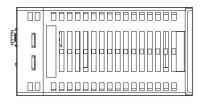
■ Wireless Adapter

Mo	Model no.		SMC-USBW-01
	Dimensions		21.8 (W) × 11.5 (H) × 56.5 (D) mm
Basic	Rated voltage Interface		Approx. 10 g
ic sp			5 VDC
specifications			USB 2.0 Type A
icat	Use with		Motion controllers (SANMOTION C S100) only
ions	Ambient temperature		0 to 55°C
	Operating environment	Ambient humidity	10 to 95% (non-condensing)
	Wireless standard		Compliant with IEEE802.11b / IEEE802.11g / IEEE802.11n
	Operating frequency band		2.4 GHz band
	Channels		1 to 13
Functions	Maximum communication speed		72.2 Mbps
tion	Wireless LAN mode		Access point mode (Acting as a master network station)
S	Wileless LAIV IIIoue		Station mode (Acting as a slave network station)
	Maximum number of conn	ectable units	3 (in access point mode)
	Security		WPA2-PSK (AES)
Apı	Japan Europe North America China Taiwan		Technical Standard Conformity Certification, VCCI
Applicable			CE (RE Directive, RoHS2)
ıble			FCC, ISED
regions			SRRC
ons			NCC

Dimensions [Unit: mm]

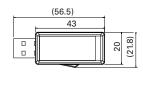
Motion controller

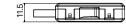
Model no.: SMC100-A, SMC100-B

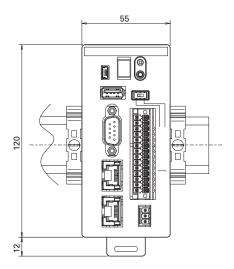


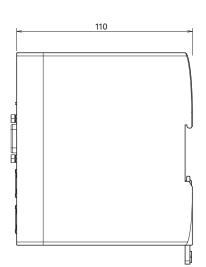
■ Wireless Adapter

Model no.: SMC-USBW-01



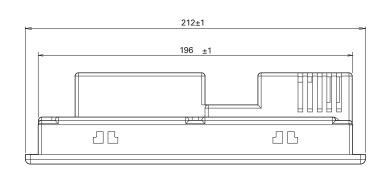


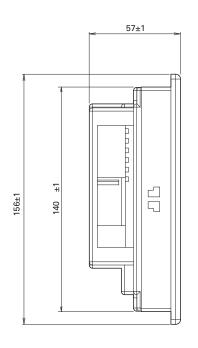


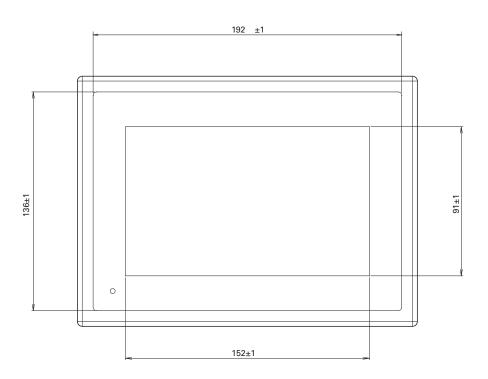


Programmable touch panel

Model no.: PA-0730BC







MEMO





■ Eco Products

SANYO DENKI's ECO PRODUCTS are designed with the concept of lessening impact on the environment in the process from product development to waste. The product units and packaging materials are designed for reduced environmental impact. We have established our own assessment criteria on the environmental impacts applicable to all processes, ranging from design to manufacture.

Those products that satisfy the criteria are accredited as ECO PRODUCTS.

Notes Before Purchase

- The products in this catalog are designed to be used with general industrial devices. Read the accompanying Instruction Manual carefully prior to using the product.
- Do not use this product in an environment where vibration is present, such as in moving vehicles or shipping vessels.
- Do not perform any retrofitting, re-engineering, or modification to the product.

Please contact us beforehand if you intend to use this product in the following applications.

- Medical equipment that may have an effect on human life
- Systems or equipment that may have a major impact on society or on the public
- Special applications related to aviation and space, nuclear power, electric power, submarine repeaters, etc.

SANYO DENKI CO., LTD. 3-33-1 Minami-Otsuka, Toshima-ku, Tokyo 170-8451, Japan TEL: +81 3 5927 1020

https://www.sanyodenki.com